

EUROPEAN EDITION

# EDN®

ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS WORLDWIDE

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22 APR 1992

A CAHNERS PUBLICATION  
March 30, 1992

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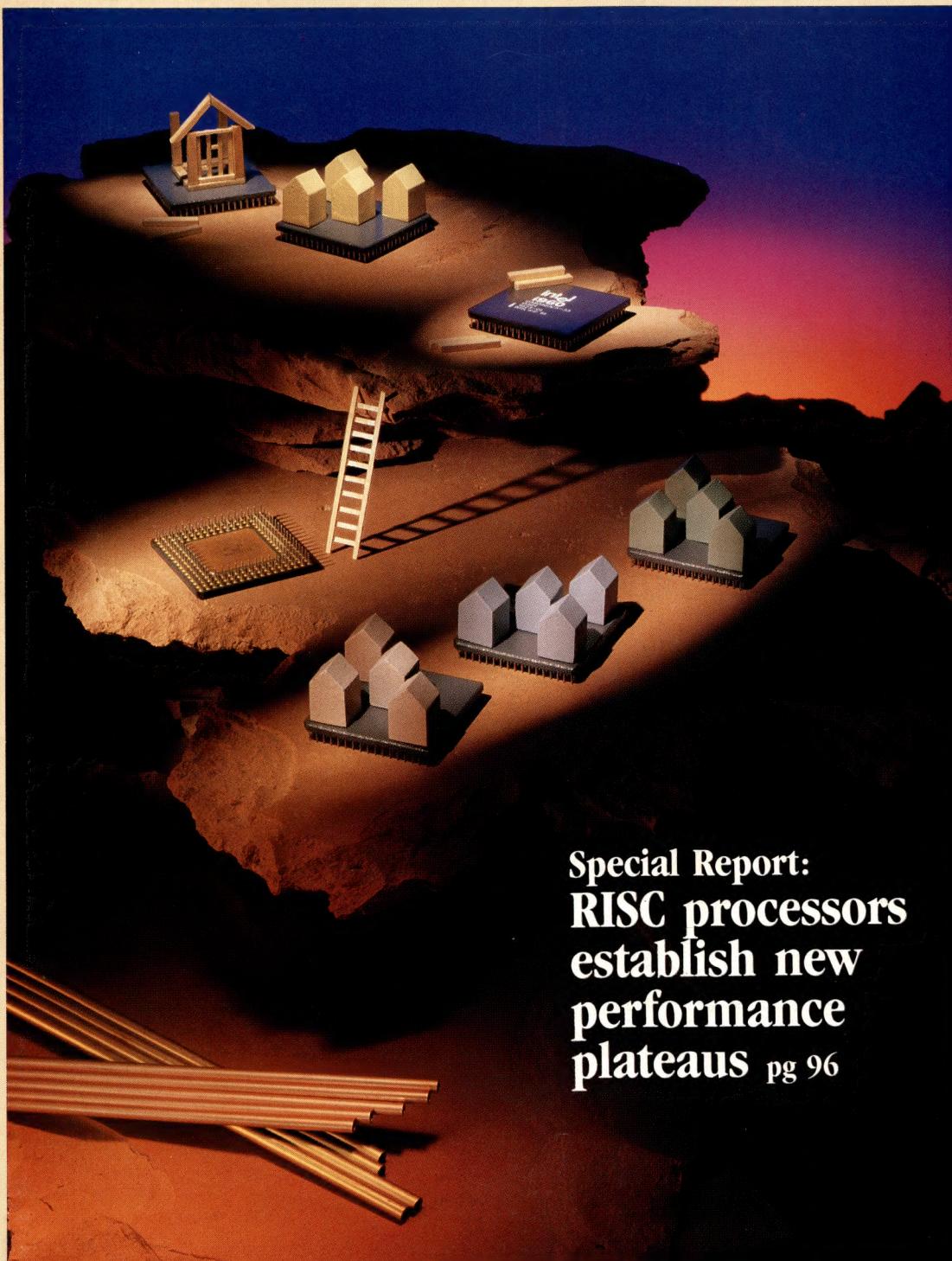
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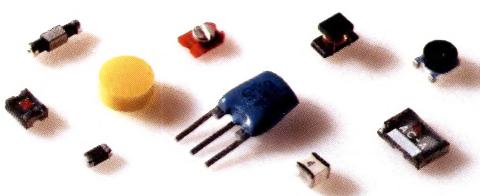
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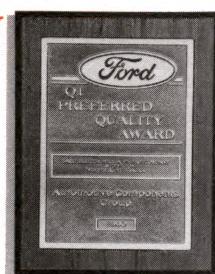
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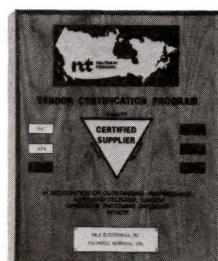
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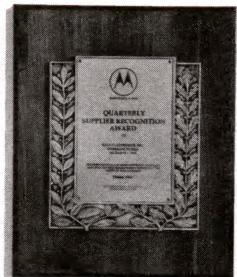
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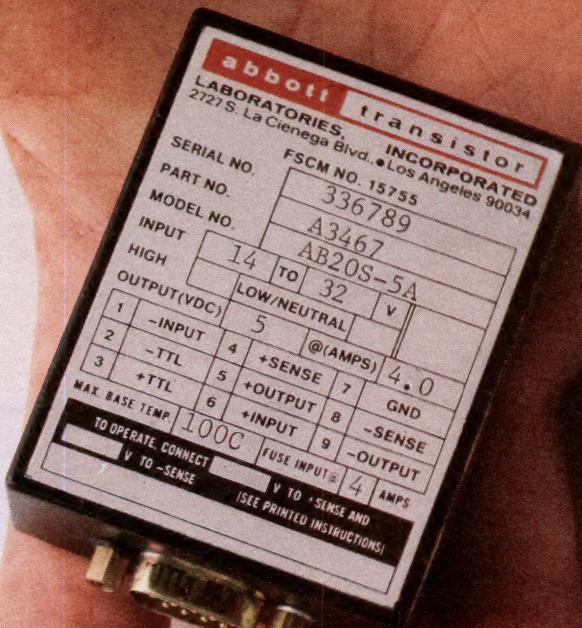
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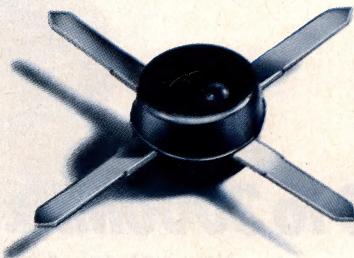
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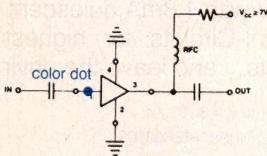
MODEL	FREQ. MHz	GAIN, dB				• MAX. PWR. dBm	NF dB	PRICE \$ Ea.	PRICE \$ Qty.
		100 MHz	1000 MHz	2000 MHz	Min. (note)				
MAR-1	DC-1000	18.5	15.5	—	13.0	0	5.0	0.99	(100)
MAR-2	DC-2000	13	12.5	11	8.5	+3	6.5	1.35	(25)
MAR-3	DC-2000	13	12.5	10.5	8.0	+8	6.0	1.45	(25)
MAR-4	DC-1000	8.2	8.0	—	7.0	+11	7.0	1.55	(25)
MAR-6	DC-2000	20	16	11	9	0	2.8	1.29	(25)
MAR-7	DC-2000	13.5	12.5	10.5	8.5	+3	5.0	1.75	(25)
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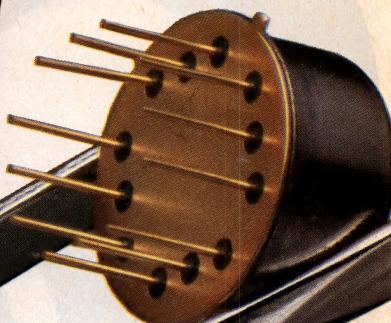
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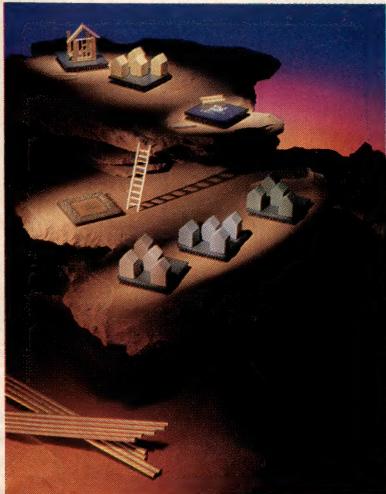
	TOSW-230 <i>ZSDR-230</i>	TOSW-425 <i>ZSDR-425</i>
Freq. Range(MHz)	10-3000	10-2500
Insert. Loss (dB)	typ. max.	typ. max.
10-100MHz	1.3	1.9
100-1500MHz	1.1	1.9
1500-3000MHz	1.8	2.7
Isolation(dB)	typ. min.	typ. min.
10-100MHz	60	40
100-1500MHz	40	28
1500-3000MHz	35	22
1dB Compression(dBm)	typ. min.	typ. min.
10-100MHz	17	6
100-1500MHz	27	19
1500-3000MHz	30	28
VSWR(ON)	typ. max.	typ. max.
Switching Time ( $\mu$ sec)	1.3	1.6
(from 50% TTL to 90% RF)	2.0	4.0
Oper. Temp.(°C)	-55 to +100	-55 to +100
Stor. Temp.(°C)	-55 to +100	-55 to +100
Price (10-24) (1-9)	\$39.95 <i>\$89.95</i>	\$59.95 <i>\$109.95</i>

CIRCLE NO. 4

F126 REV.A

MARCH 30, 1992

VOLUME 37, NUMBER 7



On the cover: The first and second generation of RISC microprocessors laid the groundwork for the increased performance of the current collection. (Photo courtesy Intel, Chandler Div; concept, design, sets, and photography by Imagination) . . . . . PAGE 96

ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS WORLDWIDE

## Third-generation RISC processors

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Mainframe and supercomputer design techniques are pushing the performance of RISC processors to 70 VAX MIPS and beyond.—*Ray Weiss, Technical Editor*

## Time-domain techniques enhance testing of high-speed ADCs

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Add a sine-wave curve-fitting algorithm or beat-frequency test to commonly used DSP techniques to characterize the performance of ADCs.

—*Michael J Demler, Micro Networks*

## Use the analytic approach to avoid errors when probing CMOS circuits

Probe resistance and probe capacitance can affect voltage measurements as well as the accuracy of delay-time measurements.—*Art Porter, Hewlett-Packard Co*

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## Micropower voltage references: Microamps sustain stable sources

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The selection, handling, and application of micropower voltage references remain decisive issues in setting performance.—*Brian Kerridge, Technical Editor*

## Battery-powered DSOs: Versatile units find more use than you'd expect

These instruments offer surprisingly good performance that often is just what design engineers need.

—*Dan Strassberg, Technical Editor*

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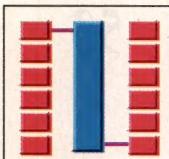
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FPGA	28 MHz	5000	DELAYED
GATE ARRAY	40 MHz	10000	DELAYED
FPGA Start-up	28 MHz	5000	CANCELLED
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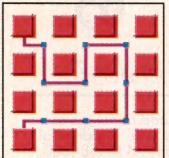
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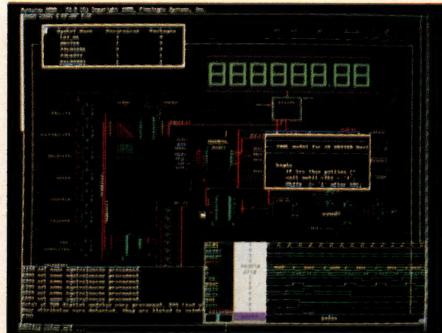
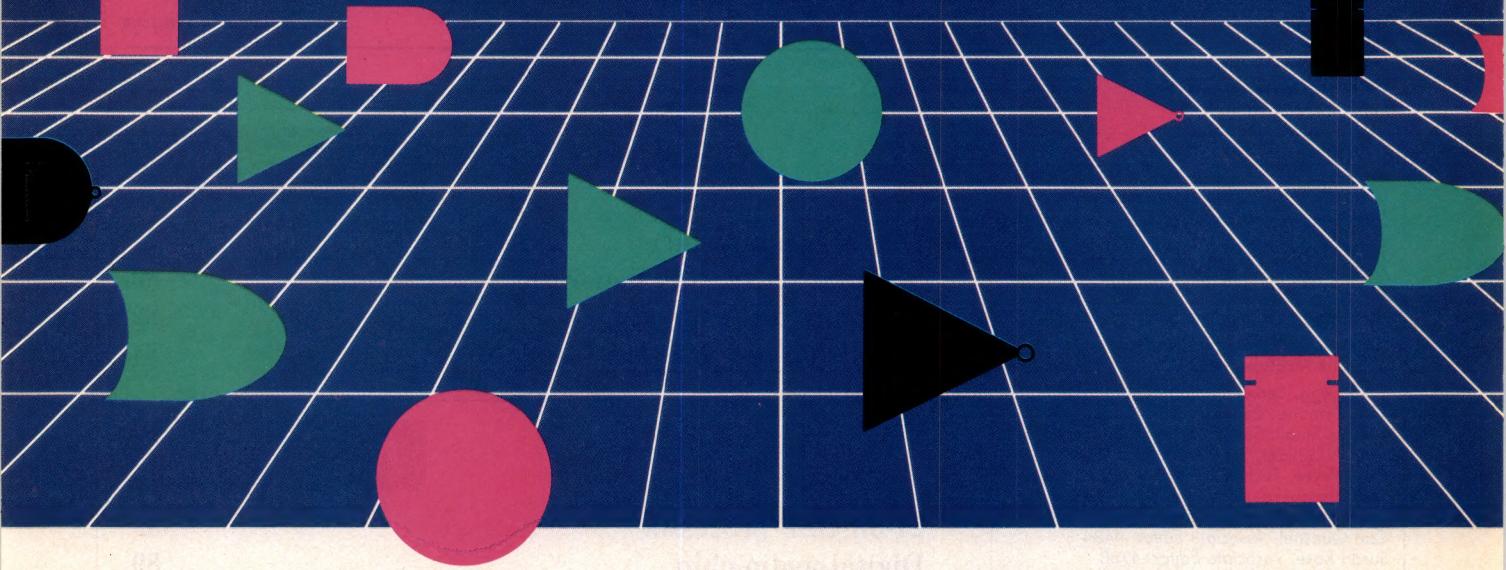
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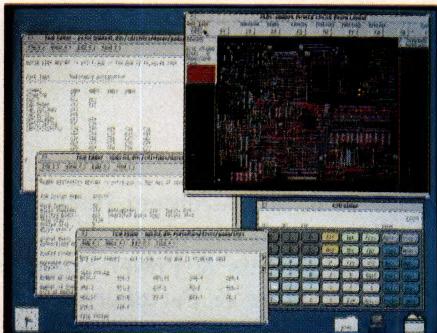
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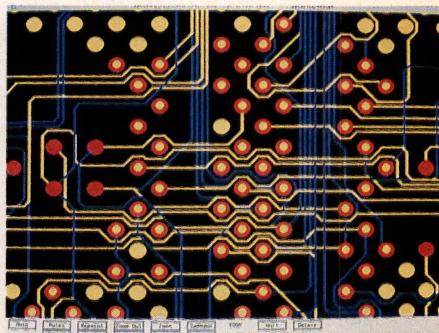
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# INSIDE EDN

A summary and analysis of articles in this issue

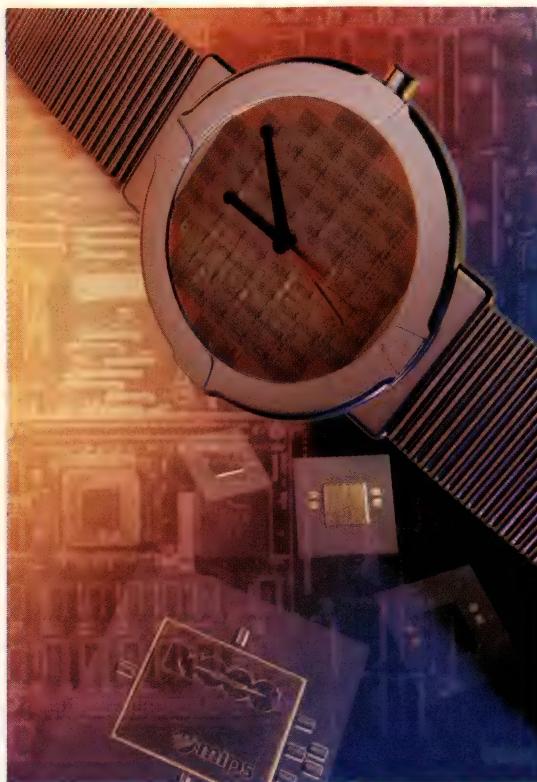
Third-generation RISC processors are just starting to appear. Some of these  $\mu$ Ps represent the latest evolutionary step for an existing processor family, whereas others skipped the first and second generations entirely. Technical Editor Ray Weiss rounds up both the available and soon-to-be available RISC devices and architectures in this issue's Special Report. If you're not yet comfortable with the brave new world of superlative adjectives ("superscalar" and "superpipelined") used to describe these high-powered computing engines, this article will bring you up to speed.

Although a few of these processors are already available in sample quantities, many have not yet been realized in working silicon. Generally, EDN's articles present products with both price and availability data because our reader surveys tell us that you want it that way. The price and date of availability serve as reality checks; if a vendor can tell you when a product will be available and how much it will cost, the product is probably real. However, for critical products with long evaluation or design-in times, such as 32-bit  $\mu$ Ps, we make an exception to this policy. Even when the products are not yet available, we will still supply the best availability information we can get. Such is the case with this issue's Special Report on RISC  $\mu$ Ps.

Technical Editor Brian Kerridge's Technology Update on micropower voltage references jumps from high-power  $\mu$ P systems into the world of low-power analog design. Micropower voltage references are all based on bandgap de-

vices instead of zeners. Kerridge's story tells you why and also gives you several application pointers to help you avoid noise and stability problems.

You'll most likely find one or more of these micropower voltage references in the battery-powered digital sampling oscilloscopes (DSOs) covered in Technical Editor



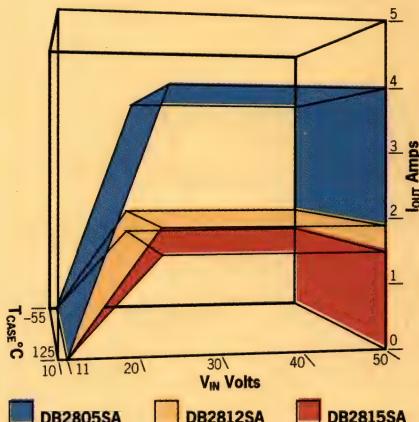
Dan Strassberg's Technology Update. You might think of these instruments as field-service tools, but Strassberg shows that they pack enough punch for general design use. Some even have enough extra functions to replace a rack of equipment with one handheld instrument. The article's sidebar discussing batteries for DSOs should interest designers of any battery-powered equipment.

Steven H Leibson  
Executive Editor

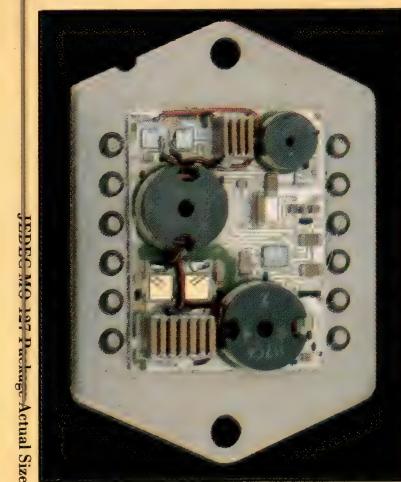
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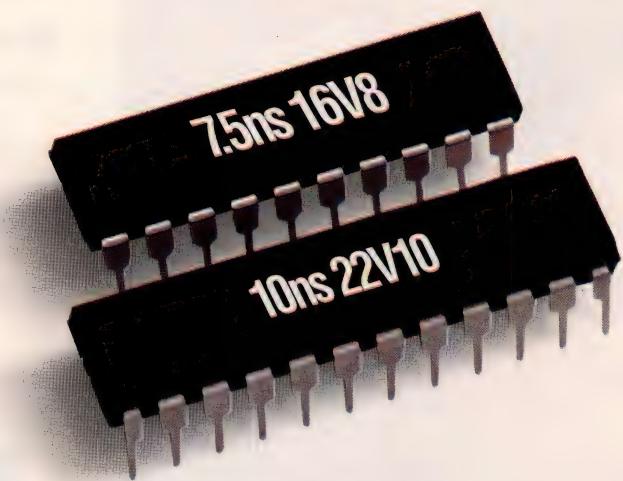
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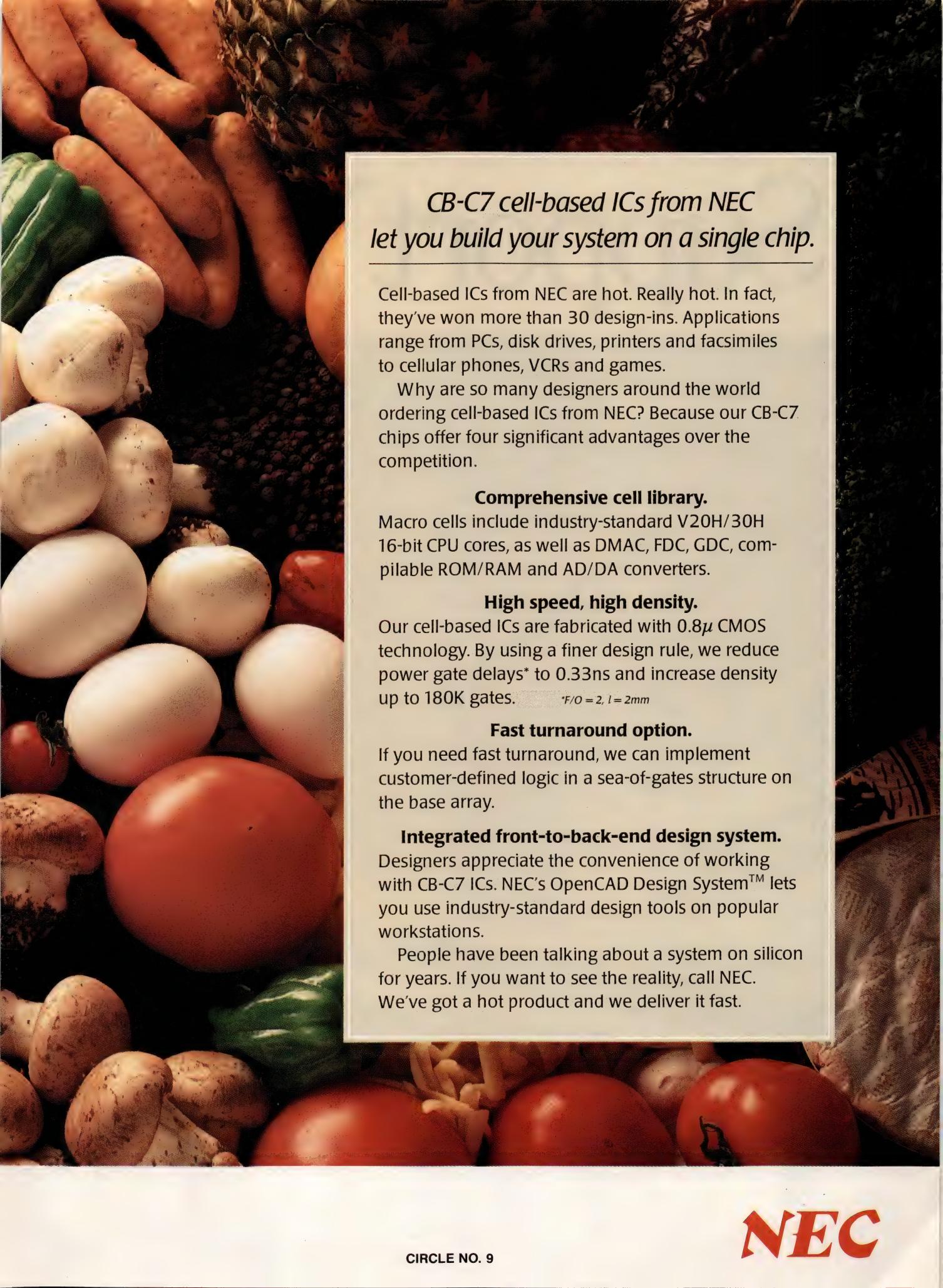
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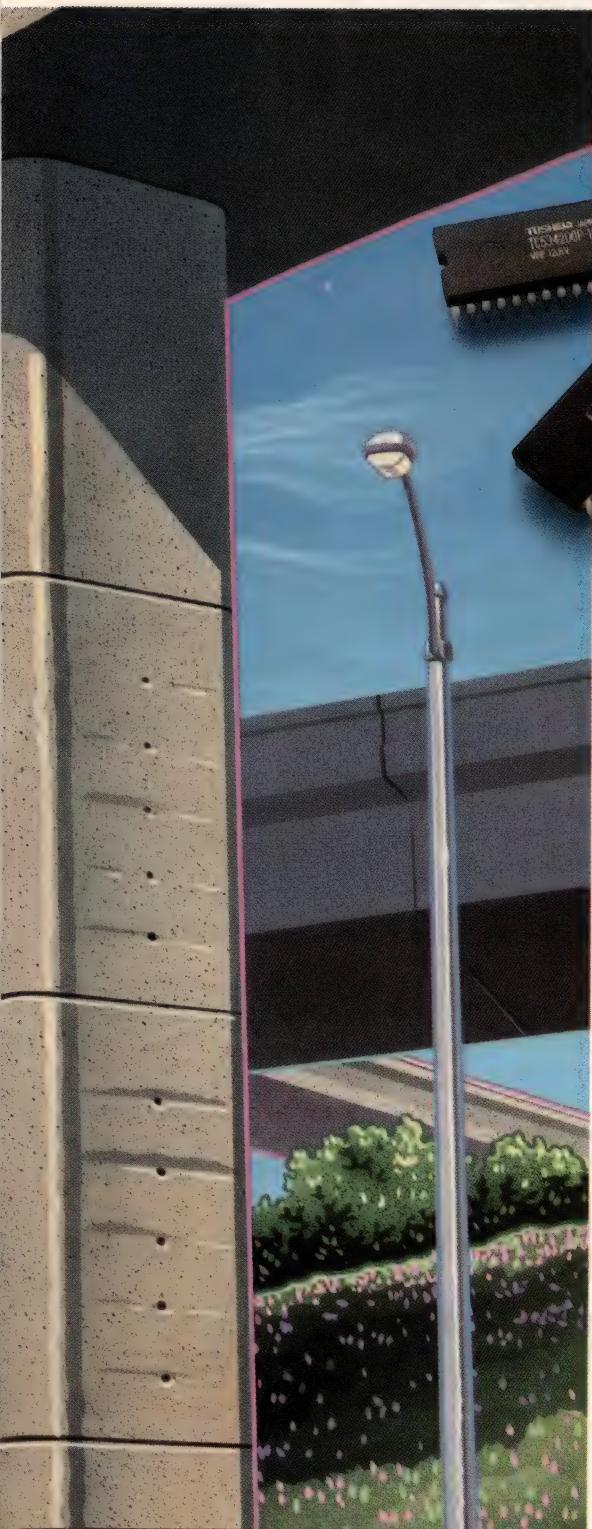
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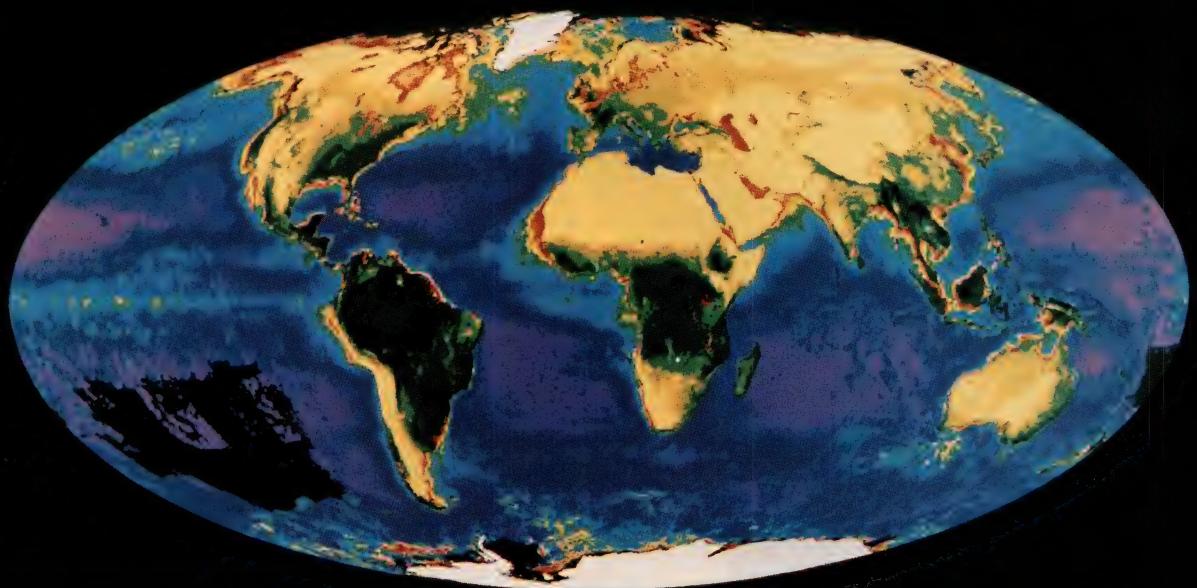


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## FPGA delivers 10,000+ gate densities

With its XC4010, Xilinx increased its FPGA (field programmable gate array) densities to 10,000 usable gates. The FPGA is the next step in the XC4000 FPGA chip family. The RAM-based-array usable-gate density increases with the availability of a programmable RAM, which you can use as a RAM block. XCA4010 register clock rates can hit 45 MHz, according to Xilinx.

Register-intensive designs can use the programmable RAM look-up table instead of the block logic it controls. You can address the RAM as a  $2 \times 16$ - or  $1 \times 32$ -register array with a 4.5-nsec access time. You can configure multiple logic blocks to build wide, deep register sets. The FPGA is made up of a  $20 \times 20$  matrix of 400 of these configurable logic blocks (CLBs). Each CLB has two 4-input functional logic units and two D flip-flops. Fast-carry logic supplements the CLBs for adder and addressing functions. The FPGA suits 32-bit processing. The chip provides 40-chip-wide, 3-state bit buses, which can handle a 32-bit word with additional control or parity byte. You can route the CLBs to pick up or put data values on any bit bus. The FPGA family includes 16 11-nsec, 60-input decoders.

Designers can change the FPGA designs on the board as well as FPGA functionality, depending on board or system conditions. However, the company's FPGAs require programming on power up, requiring special logic and system memory or an EPROM to hold FPGA programming data. The chip costs \$737 (1000). Xilinx Inc, San Jose, CA, (408) 559-7778, FAX (408) 559-7114.—Ray Weiss

## VHDL package integrates multiple tools

Vantage Analysis Systems Vantage Spreadsheet version 4.0 lets engineers compile, debug, and analyze their VHDL (VHSIC Hardware Description Language) designs. The software's compilation and simulation speeds are an order of magnitude faster than previous versions. The software also speeds testing with a tool that grades test stimulus by counting up the num-

ber of times a VHDL source-code line executes, as well as tracking the number of events for each signal. The Concurrent Compiler, a parallel version of the VHDL compiler that automatically partitions and distributes compilation tasks across a Sun or HP processor network, speeds compilation. Finally, a generic loader lets you load as many as 100,000 parameters per minute, without stopping the compiler. The software pricing starts at \$44,000. Vantage Analysis Systems Inc, Fremont, CA, (510) 659-0901.—Ray Weiss

## Ethernet and Token Ring on one chip

*Texas Instruments' TMS380C26 chip handles both Ethernet and Token-Ring communications protocols. With this chip on a mother board, users can connect their system to either network—they do not have to choose a desktop protocol when buying the system. The chip supports Ethernet standards and remains pin and software compatible with TI's TMS380C16, an IBM-verified 4- or 16-Mbit/sec Token-Ring coprocessor.*

*To make reconfiguration (shifting from one to the other on site) easier, the company is also releasing the C26 Selectable Physical Layer Interface Transceivers to ease reconfiguration. These transceivers let you interface a mother board to either Token-Ring or Ethernet wiring media. Configuration is at the cable level. The TMS380-C26 will be available in a 132-pin plastic quad flatpack. \$58.80 (10,000). Texas Instruments Inc, Dallas, TX, (800) 336-5236, ext 3990.*

—Ray Weiss

## Cache-tag RAM offers 12-nsec validated match

The CY7B180 and CY7B181 are  $4k \times 18$ -bit cache-tag RAMs with extra logic to simplify your cache

designs. Both devices offer a 16-bit tag field with a 2-bit status field at each location. You can read and write the two fields independently. The 180 lets you use the status bits to code the tag data for multi-processing systems. The 181 uses these status bits to denote valid and "dirty" data. It automatically sets the "dirty" bit on a write hit and uses the valid bit to gate the match signal so that only valid matches are signaled to the cache. The validated match takes 12 nsec.

To further simplify designs, the devices automatically generate a write output signal to the cache RAM when they detect a write hit. The devices also offer an additional data port, letting you read tag data immediately when you find a match. The instant availability of the tag data helps speed copy-back cache schemes. The devices come in a 68-pin plastic lead chip carrier and cost \$72.05 (100). Cypress Semiconductor, San Jose, CA, (408) 943-2600, FAX (408) 943-2741.

—Richard A Quinnell

## Scope offers record lengths to 8 Mbytes

The Systemware digital oscilloscope is available with as much as 8 Mbytes of memory words, letting the instrument record exceptionally long waveforms. The PC-based oscilloscope runs under Microsoft Windows 3.0 with

a software control panel. The instrument has a 40-MHz bandwidth and digitizes 8 bits at 100 Msamples/sec. Prices range from \$10,000 for an instrument with 256 kbytes of

memory, to \$18,825 for a system with 8 Mbytes of memory. Systemware, Westlake Village, CA, (805) 497-9603, FAX (805) 494-9719.

—Doug Conner

## Conditions relax as Europe's EMC Law comes into force

Although Europe's EMC law theoretically came into force on January 1 of this year, clarifications of its implementation continue to appear. Since EDN first reported details of this law (September 16, 1991, pg 57), later statements from the Commission of European Communities have defined more clearly what products the law applies to and over what time scale the law will be introduced.

Generally, there is an overall relaxation in the scope of products that must comply with the law. Broadly, the law classifies products into one of four categories: components, apparatus, systems, and installations. Components and installations do not have to comply with the law, but apparatus and systems must. The terms are thus defined:

- **Components:** Any element likely to be part of an apparatus, and not intended for use by an end user. This category includes passive components, ICs, and PCB subassemblies.
- **Apparatus:** A finished product with an intrinsic function intended for an end user that will be placed on the market as a single commercial unit. The law squarely applies to products in this category.
- **Systems:** Several pieces of apparatus designed and intended to work together. A typical example is a PC, and such products must comply.
- **Installations:** Several pieces of apparatus put into service in a given place for a specific task but not intended to be placed on the market as a single commercial unit. On the understanding that an installation consists of already-compliant apparatus and systems, the overall installation needs no further approval.

The Commission of European Communities has also made clear that the end-date of the transition period is December 31, 1995. During the transition period you can opt to comply with the EMC law or continue to observe prevailing national EMC regulations. At present, only Denmark has incorporated the EMC law into its national legislation. Other countries will follow suit later this year.

The arrangement for competent bodies and notified bodies to perform approval work in the EC stands. In the UK, the Department of Trade and Industry has issued a provisional list of companies to perform this service.

—Brian Kerridge

## Mixed-signal IC tester gets smaller and faster

As mixed-signal ICs grow in digital complexity, the distinction between testers for mixed analog/digital chips and those for high-pin-count digital devices is becoming less clear. Teradyne Inc's mixed-signal-IC tester, the A580, has many of the attributes of testers for purely digital ICs. The system has 280 channels—of which 192 are digital—and a 200-MHz maximum clock rate for digital testing. The mixed-signal-chip tester can handle the majority of testing performed on high-pin-count digital ICs, so many companies that make both digital and mixed-signal parts should be able to use a single type of tester.

In addition to offering 2.5× as many channels and 4× the digital-test speed of its most nearly equivalent predecessor, the tester is considerably smaller (about one-half the floor space), and at \$1 to \$2 million, slightly less expensive. The unit also uses so much less power that it has no need for a separate power-conditioning "vault." The lower power dissipation means users won't have to install as much air conditioning. For analog applications, the highest signal frequency is 4 GHz vs 10 MHz for the earlier system; the highest voltage

is 1 kV vs 60V; and the largest source current is 100A vs 1A. Teradyne Inc, Boston, MA, (617) 422-2567.

—Dan Strassberg

## VGA chips attack PC-video performance problems

Now that PC processor speeds have jumped into the 33- to 50-MHz range, IC vendors are attacking the next major performance bottleneck—video display speeds—with chips that off-load graphics operations from the main CPU. AT&T's ATT20C101 super-VGA controller incorporates several features that boost display performance, including a 16-bit bus interface that can keep pace with 80386 and 80486 μPs, a write buffer that reduces wait times (at least during write operations), and a 32-bit interface to page-mode dynamic RAMs for the bit-map memory. The \$14 (1000) chip has nine display modes that range from 640×480 to 1024×768 pixels and display 256- to 16.8-million colors.

The company is also offering three companion color-palette DACs: the 110-MHz, triple 8-bit ATT20C491; the 110-MHz, triple 6-bit ATT20C492; and the 200-MHz, triple 8-bit ATT20C458. These DACs cost \$13, \$11, and \$45, respectively, (1000).

ATI Technologies' 68800 super-VGA coprocessor

# Why Settle for 1/2 an '040 Board?

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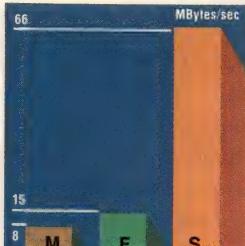


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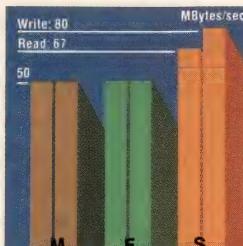
## Compare our specs. Synergy is superior across the board!



### VME Transfers

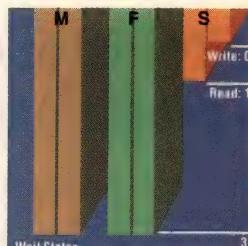
VME64 doubles bus performance to 66 MB/s—and the SV430 is the only '040 board that has it. But we don't need VME64 to win this comparison.

Even normal 32-bit transfers race at 33 MB/s. That's 200% faster than Force or Motorola.



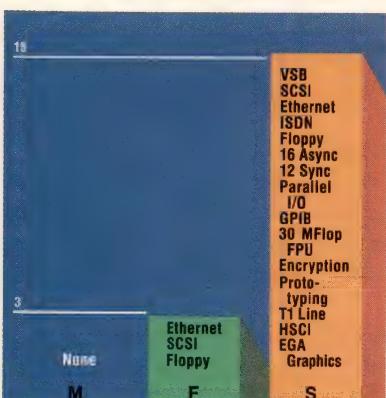
### DRAM Burst Rates

A 25 MHz '040 is capable of accessing memory at 80 MB/s. The closer you are to this maximum, the more '040 performance you're gaining. SV430 bursts are 26% faster than Force and Motorola.



### DRAM Random Accesses

Non-burst '040 performance is measured in wait states. Fewer wait states mean higher performance. The SV430 is not only 66% faster than Force or Motorola, it supports twice the on-board memory—32 MB.



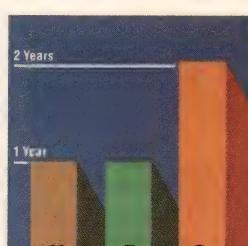
### I/O Modules

Synergy's EZ-Bus modules are compatible with our entire line of SBCs. This means Synergy's current line of 12 intelligent I/O modules are immediately available for the SV430—today. No other vendor comes close for selection, functionality or availability.



### '020/'030 Compatibility

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### Product Warranty

Synergy backs the reliability of its SBCs with a two year standard warranty. Force and Motorola only offer you one.



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Data from Motorola MVME165 data sheet dated 2/90, and Force CPU-40 data sheet A1 Rev. 1. DRAM measurements shown are with parity. VMEbus transfers are to a 60ns slave.

VM64 is a trademark of Performance Technologies, Inc.

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CIRCLE NO. 18

uses many of the same graphics-acceleration techniques and adds a few of its own. The \$79 (1000) IC has a configurable bus interface with a FIFO buffer that will transfer 8-, 16-, or 32-bit words and is fast enough to operate on the host CPU's local bus at clock speeds to 40 MHz. The controller chip communicates with video memory over a 64-bit bus and can accommodate 4M bytes of video RAM, producing a maximum display resolution of 1280×1024 24-bit pixels. An on-chip drawing coprocessor can perform bitblts, point-to-point line

drawing, pattern filling, and clipping with little or no host CPU intervention. The chip also provides hardware-based assistance for antialiased character fonts. A less-expensive version of the device, the \$49 (1000) 68800SX, will be available later this year. It will only accommodate 2M bytes of video memory and 1024×768-pixel displays. AT&T Microelectronics, Allentown, PA, (800) 372-2446, FAX (215) 778-4106. ATI Technologies, Inc, Scarborough, ON, Canada, (416) 756-0718, FAX (416) 756-0720.

—Steven H Leibson

## High-density PLD allows in-system programming

Lattice Semiconductor's PLSI 1032 and ISPLSI 1032 are the first members of a high-density PLD family that are based on EEPROM technology. Both devices have 64 I/O pins, 8 dedicated input pins, and 196 registers. The devices' basic logic block lets you create 20 AND-product terms from a selection of 18 complementary signal pairs, 2 of which come from the dedicated input pins and 16 from any of the logic blocks. Propagation delay through the device is 15 nsec; delay for internal feedback is as low as 3 nsec.

Both the PLSI and ISPLSI devices are pin- and parameter compatible, but the ISPLSI device has an additional feature: You can program the device in-system. The ISPLSI device multiplexes four I/O pins and uses one dedicated pin (no-connect on the PLSI parts) to provide a serial access port for programming. The device has an on-chip programming voltage, so you don't need any additional voltages in your system.

Lattice supports the family with development software and engineering kits. The software runs under Windows, offers a library of macro functions, and lets you design with Boolean equations. The software costs \$995; the engineering kit costs \$395. The parts' cost varies with speed grade. The PLSI 1032 costs from \$49 to \$81 (1000). The ISPLSI 1032 costs \$142 (100) in sample qty. Lattice Semiconductor, Hillsboro, OR, (503) 681-0118, FAX (503) 681-0347.—Richard A Quinnell

## Voltage regulator models thin package

The TL-SCSI285 fixed-voltage regulator from Texas Instruments implements a new method for terminating SCSI lines, called active termination, which reduces power consumption by as much as 30×, thereby increasing the possibilities for SCSI portable systems. The regulator lets input voltages drop as low as 3.45V and still maintain an output voltage of 2.85V. With this dropout voltage of 0.6V, the regulator meets demands of both desktop computer systems and laptop and portable systems. Total tolerance in the 2.85V output is ±2% overtemperature, including variations caused by line voltage and load changes. The device's 110Ω, ±2% series resistors match the typical transmission-line characteristic impedance.

The device comes in a thin-scaled small-outline package (TSSOP). The 20-pin package has lead spacings of 0.025 in. and is 0.040 in. thick, which is half the height of the standard small-outline package. At 25°C, the package's power-dissipation rating is 0.775W compared with 1W for a standard DIP. The TSSOP-packaged regulator costs \$1.70; DIP and TO-200 versions are also available. A second regulator with a 1V dropout voltage, the TL2217-285, costs from \$1.39. These regulators are the first devices available in the thin package,

but the company will also offer the package for existing and new standard linear devices. Texas Instruments Inc, Dallas, TX, (800) 336-5236, ext 3990, (214) 995-6611, ext 3990.

—Anne Watson Swager

## Microsoft introduces C++

Microsoft Corp has introduced C/C++ v 7.0 Development System for Windows. The system is an ANSI C and C++ v3.1 development environment. The system's compilers use precompiled header and C++ files for increased speed.

The package includes the Microsoft Foundation Classes and an Application Framework. These classes are available in source form for use as program examples. The framework is a platform for multiple tools, including third-party development packages. Among the debug tools are a new version of Codeview for C++ and a C++ Object Browser. Other optimizations include "Packed P code" object format (interpreted P-code for 40 to 60% size reductions), programmer-directed function in-lining (saving call overhead by expanding function calls with the actual code), automatic function in-lining (compiler directed), and a virtual overlay manager. Also provided is a set of Windows documentation and basic C++ class libraries. The software costs \$499. Microsoft Corp, Redmond, WA, (206) 882-8080.—Ray Weiss

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## PR3400 MIPS RISC Processor

This new monolithic VLSI component contains the PR3000A, PR3010A and more! When used with the PACEWRAP™ PR3100A, (Performance's single-chip write, read and parity buffer), it makes possible a single-board MIPS computer at 25, 33 and 40MHz.

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- **Single 1X-Clock Pin** No external delay line required.
- **System Performance at 40MHz** SPECmark Rating = 32.4, 33 VAX MIPS; 11.6 MFLOPS, Single-Precision LINPACK; 6.7 MFLOPS Double-Precision LINPACK.
- **Available Speeds** 25, 33 and 40MHz.
- **Packages** 175-pin PGA, 25, 33 & 40MHz, 160-pin surface mount.

## PACEWRAP PR3100A Write/Read & Parity Buffer

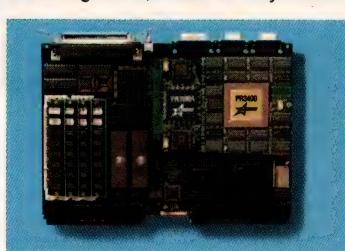
This new component provides a full-featured interface between the high-speed processor-cache bus and lower-speed I/O & main-memory bus resulting in outstanding performance and board density at lowest cost.

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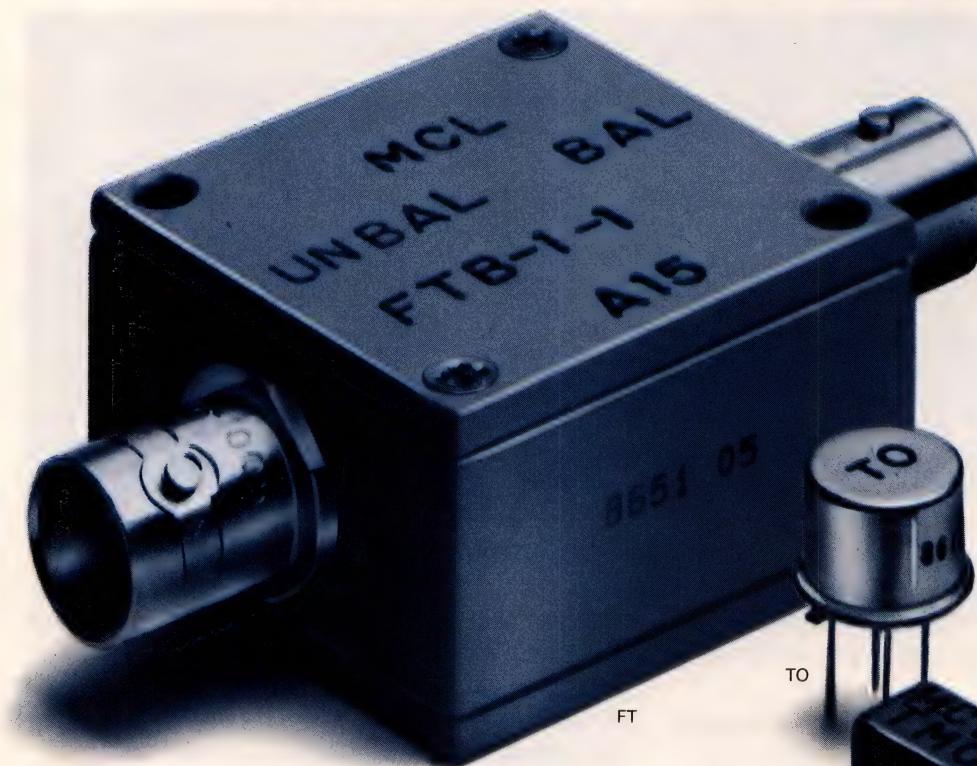
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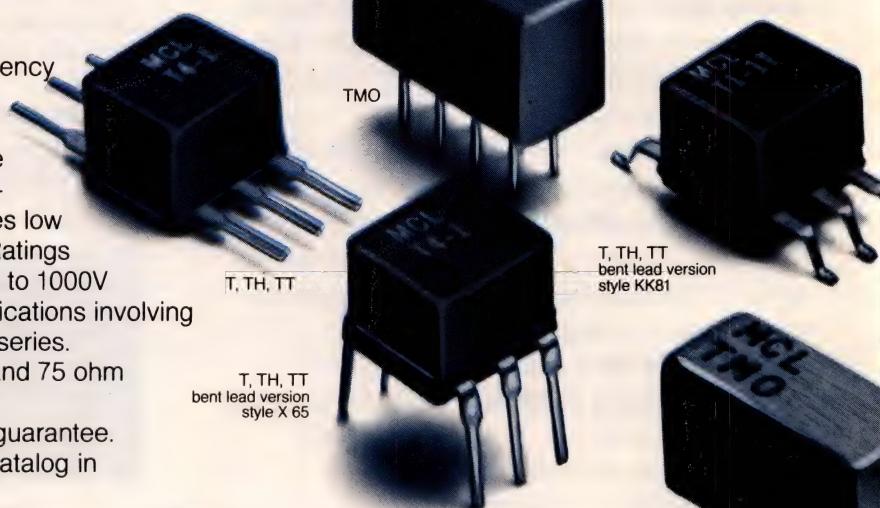
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#### NSN GUIDE

##### MCL NO. NSN

MCL NO.	NSN	MCL NO.	NSN
FTB1-1-75	5950-01-132-8034	TMO2-1	5950-01-183-6414
FTB1-6	5950-01-225-8773	TMO2.5-6	5950-01-215-4038
T1-1	5950-10-128-3745	TMO2.5-6T	5950-01-215-8697
T1-1T	5950-01-153-0668	TMO3-1T	5950-01-168-7512
T2-1	5950-01-106-1218	TMO4-1	5950-01-067-1012
T3-1T	5950-01-153-0298	TMO4-2	5950-01-091-3553
T4-1	5950-01-024-7626	TMO4-6	5950-01-132-8102
T9-1	5950-01-105-8153	TMO5-1T	5950-01-183-0779
T16-1	5950-01-094-7439	TMO9-1	5950-01-141-0174
	5950-01-178-2612	TMO16-1	5950-01-138-4593

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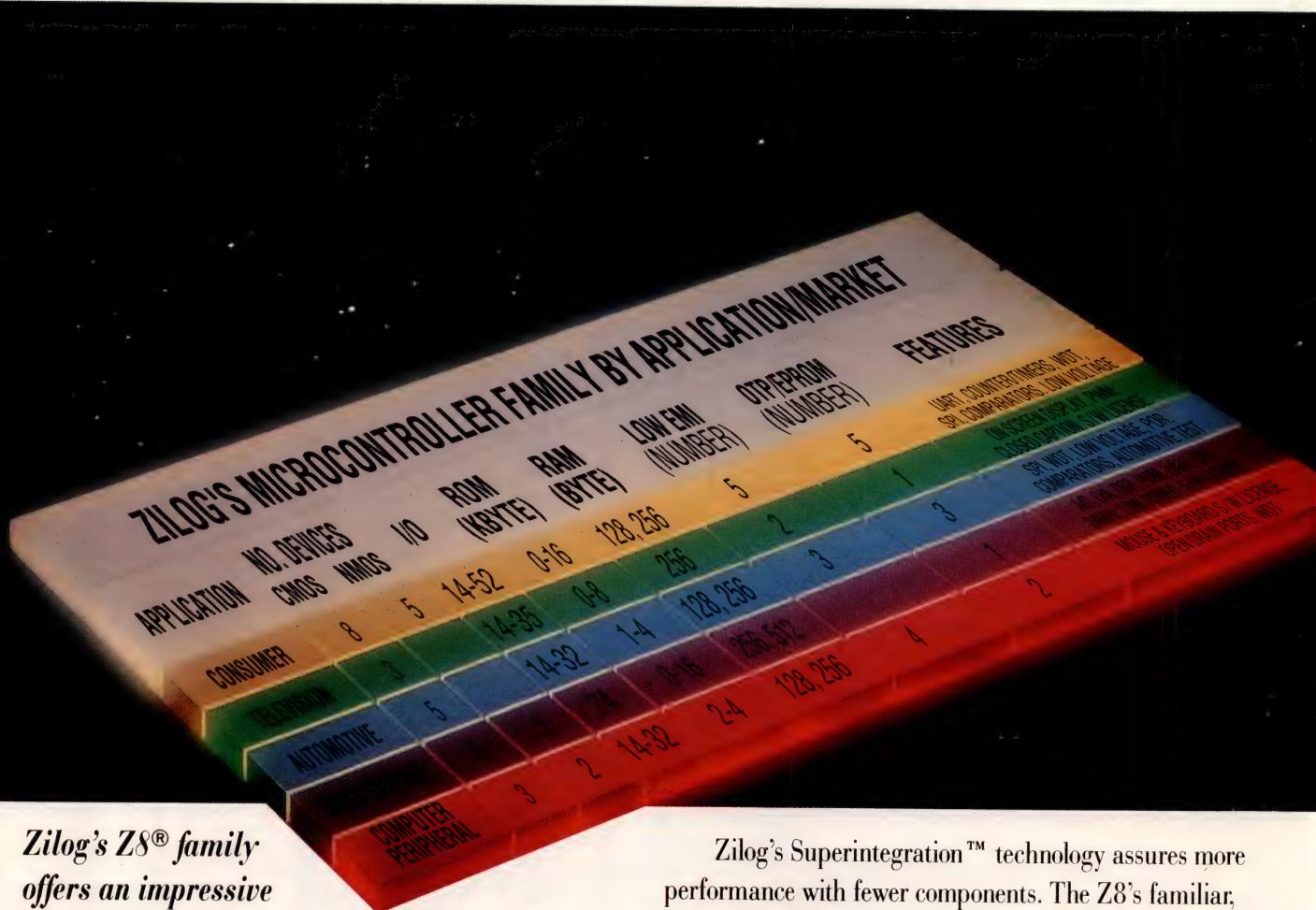
case style number see opposite page	MODEL NO.	$\Omega$ RATIO	FREQUENCY MHz	INSERTION LOSS			PRICE \$ Qty. (1-9)
				3dB MHz	2dB MHz	1dB MHz	
A*	T	1	.05-200	.05-200	.08-150	.2-80	4.45
		1	.003-300	.003-300	.01-150	.02-50	6.95
	T1-6T	1	.07-200	.07-200	.1-100	.5-50	4.95
	T2-1T	2	.01-100	.01-100	.02-50	.50-20	4.95
	T2.5-6T	2.5	.05-250	.05-200	.1-200	.5-70	4.95
	T3-1T	3	.05-250	.05-200	.2-350	.35-300	3.25
	T4-1	4	.2-350	.2-350	.05-150	.0.1-100	4.45
	T4-6T	4	.02-250	.02-250	.01-100	.05-20	4.95
	T5-1T	5	.3-300	.3-300	.6-200	.5-100	4.95
	T8-1T	8	.03-140	.03-140	.10-90	.1-60	7.95
	T13-1T	13	.3-120	.3-120	.7-80	.5-20	4.95
	T16-6T	16	.03-75	.03-75	.06-30	.1-20	5.65
	T4-1H	4	.10-350	.10-350	.15-300	.25-200	5.95
B*	TH	1	.05-200	.05-200	.08-150	.2-80	7.95
	TMO	1	.07-200	.07-200	.1-100	.5-50	8.45
	TMO1-1T	2	.01-100	.01-100	.02-50	.05-20	8.45
	+TMO2.5-6T	2.5	.05-250	.05-250	.1-200	.5-70	7.95
	+TMO3-1T	3	.05-250	.05-250	.35-300	.2-100	6.25
	TMO4-1	4	.2-350	.2-350	.3-300	.5-100	8.45
	TMO5-1T	5	.3-300	.3-300	.6-200	.5-100	8.45
	TMO13-1T	13	.3-120	.3-120	.7-80	.5-20	8.45
	TT	1	.004-500	.004-500	.02-200	.1-50	6.95
	TT1.5-1	1.5	.075-500	.075-500	.2-100	.1-50	5.95
	TT2.5-6	2.5	.01-50	.01-50	.025-25	.05-10	6.45
	TT4-1	3	.05-200	.2-50	.2-50	.1-30	5.95
C	TT4-1A	4	.01-300	.01-300	.02-250	.0.3-180	6.95
	TT25-1	25	.02-30	.02-30	.05-20	.1-10	9.95
	TTMO25-1	25	.02-30	.02-30	.05-20	.1-10	11.95
	TTMO1-1	1	.005-100	.005-100	.01-75	.05-40	11.45
	TTMO4-1A	4	.01-300	.01-300	.02-250	.0.3-180	13.95
	T	1	.15-400	.15-400	.35-200	.2-50	3.25
	T1.18-3	1.18	.001-250	.001-250	.002-200	.003-50	5.65
	T1-6	1	.01-150	.01-150	.02-100	.05-50	5.65
	T1.5-1	1.5	.1-300	.1-300	.2-150	.5-80	4.45
	T1.5-6	1.5	.02-100	.02-100	.05-50	.0.1-25	5.65
	T2.5-6	2.5	.01-100	.01-100	.02-50	.05-20	4.45
	T4-6	4	.02-200	.02-200	.05-150	.1-100	4.45
D	T9-1	9	.15-200	.15-200	.3-150	.2-40	3.95
	T16-1	16	.3-120	.3-120	.7-80	.5-20	4.45
	T36-1	36	.03-20	.03-20	.05-10	.1-5	6.95
	TO	1	.10-500	—	.10-500	.40-250	6.95
	TH	1	.8-300	.8-300	.10-200	.25-100	5.95
	T1-1H	1	.2-90	.2-90	.3-75	.6-50	6.45
	T9-1H	9	.7-85	.7-85	.10-65	.15-40	6.45
	T16-H	16	.1-800	.1-800	.2-500	—	9.45
	TMO	1	.15-400	.15-400	.35-200	.2-50	6.25
	TMO1-1	1	.1-300	.1-300	.2-150	.5-8	8.45
	TMO1.5-1	1.5	.01-100	.01-100	.02-50	.05-20	7.95
	+TMO2.5-6	2.5	.02-200	.02-200	.05-150	.1-100	7.95
E	FT	4	.3-200	.3-200	.5-150	.5-50	7.95
	TMO6-1	6	.15-200	.15-200	.3-150	.2-40	7.95
	TMO9-1	9	.3-120	.3-120	.7-80	.5-20	7.95
	TMO16-1	16	.1-800	.1-800	.2-500	.3-200	7.95
	T	2	.050-600	.050-600	.1-400	.5-200	3.95
	T3-1	3	.5-800	.5-800	.2-400	—	4.45
	T4-2	4	.2-600	.2-600	.5-500	.2-250	3.95
	T8-1	8	.15-250	.15-250	.25-200	.2-100	3.95
	T14-1	14	.2-150	.2-150	.5-100	.2-50	4.95
	TMO2-1	2	.050-600	.050-600	.1-400	.5-200	7.95
	TMO3-1	3	.5-800	.5-800	.2-400	—	8.45
	TMO4-2	4	.2-600	.2-600	.5-500	.2-250	7.95
	TMO8-1	8	.15-250	.15-250	.25-200	.2-100	7.95
	TMO14-1	14	.2-150	.2-150	.5-100	.2-50	8.45
F	FT1.22-1	1.22	.005-100	.005-100	.01-50	.05-25	35.95
	FT1.5-1	1.5	.1-400	.1-400	.5-200	1-100	35.95
	FTB	1	.2-500	.2-500	.5-300	.1-100	36.95
E	FTB-1	1	.01-125	.01-125	.05-50	.1-25	36.95
	FTB-1-6	1	.5-500	.5-500	.5-300	.10-100	36.95
	FTB-1-75	1	—	—	—	—	—
F	X	1	.01-10	.01-10	.0.5-100	.5-80	3.25
	Y	1	.01-10	.01-10	.0.2-5	.04-2	3.95
	Z	1	—	—	—	—	—
	FTB	1	—	—	—	—	—

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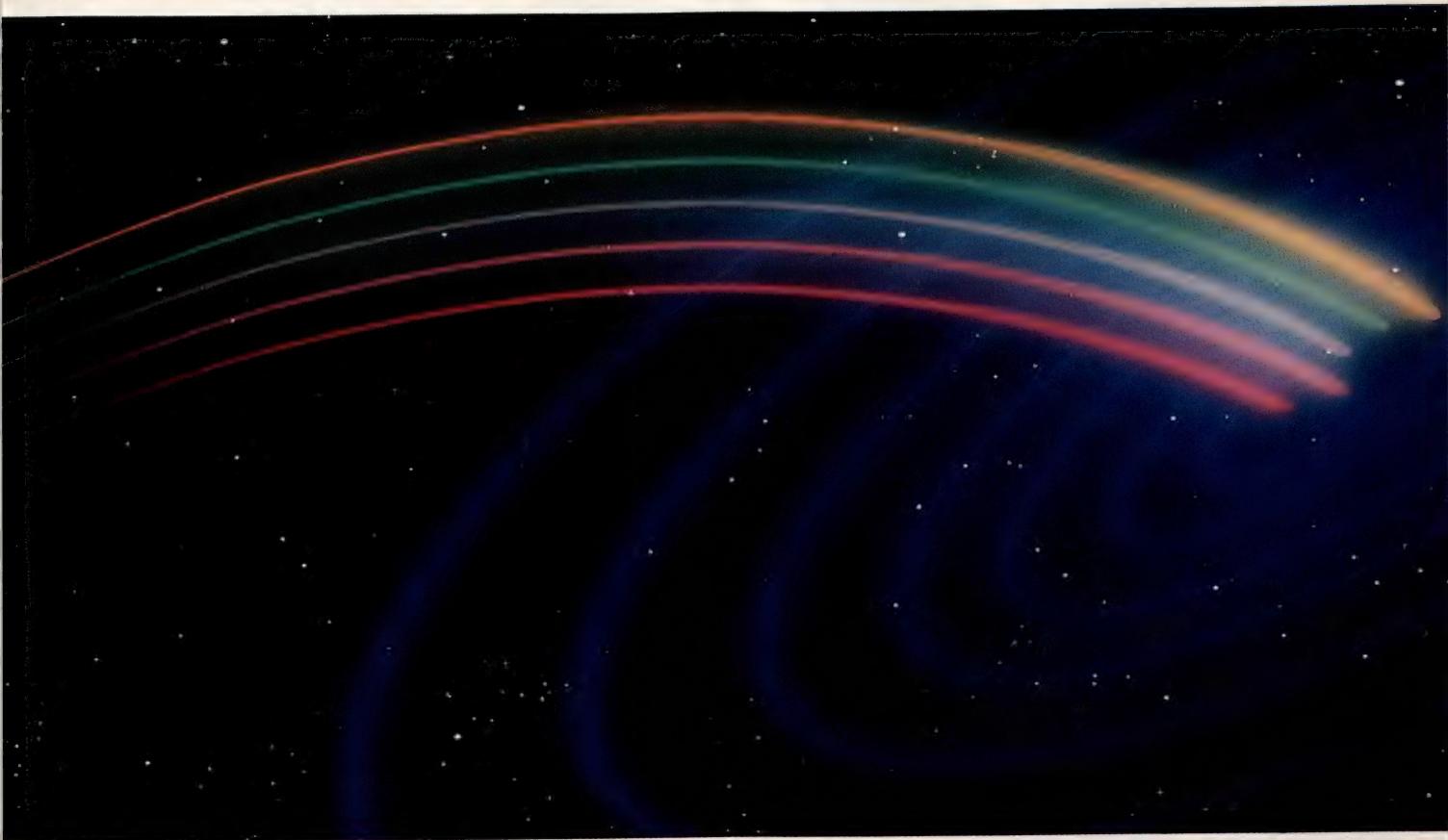
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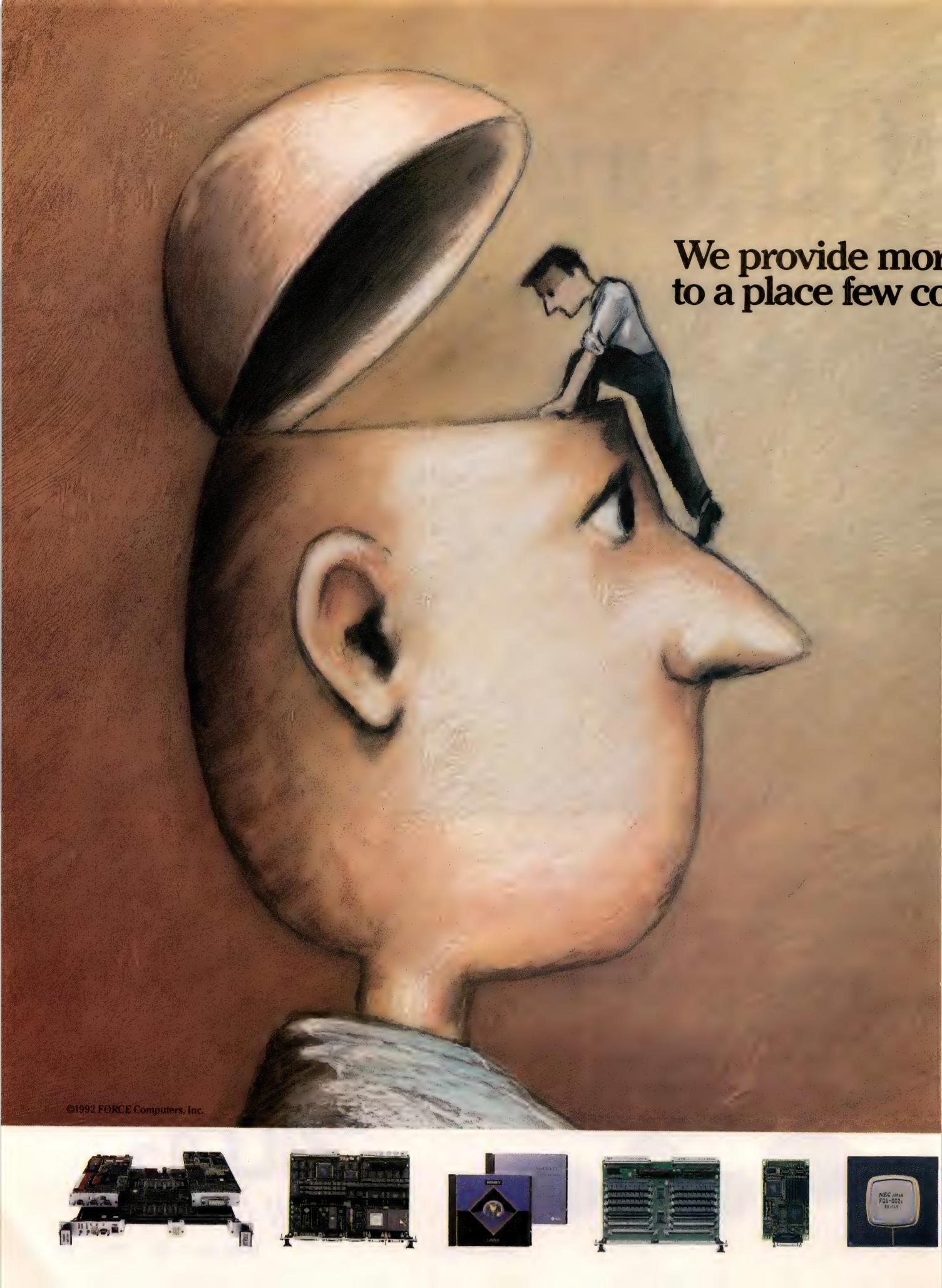


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To find out more about the Z8 Microcontroller family, or any of Zilog's rapidly growing Superintegration product families, contact your local Zilog sales office or your authorized distributor today. Zilog, Inc., 210 East Hacienda Ave., Campbell, CA 95008-6600, (408) 370-8000.

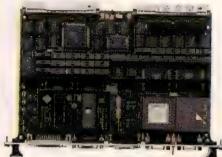
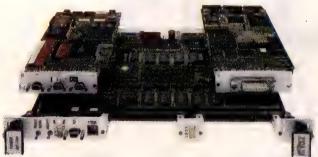
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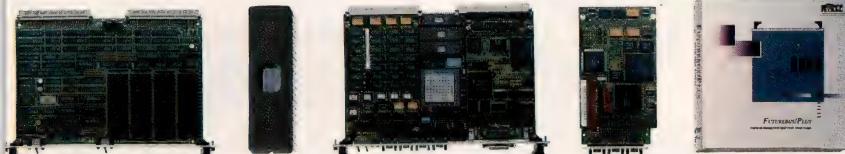
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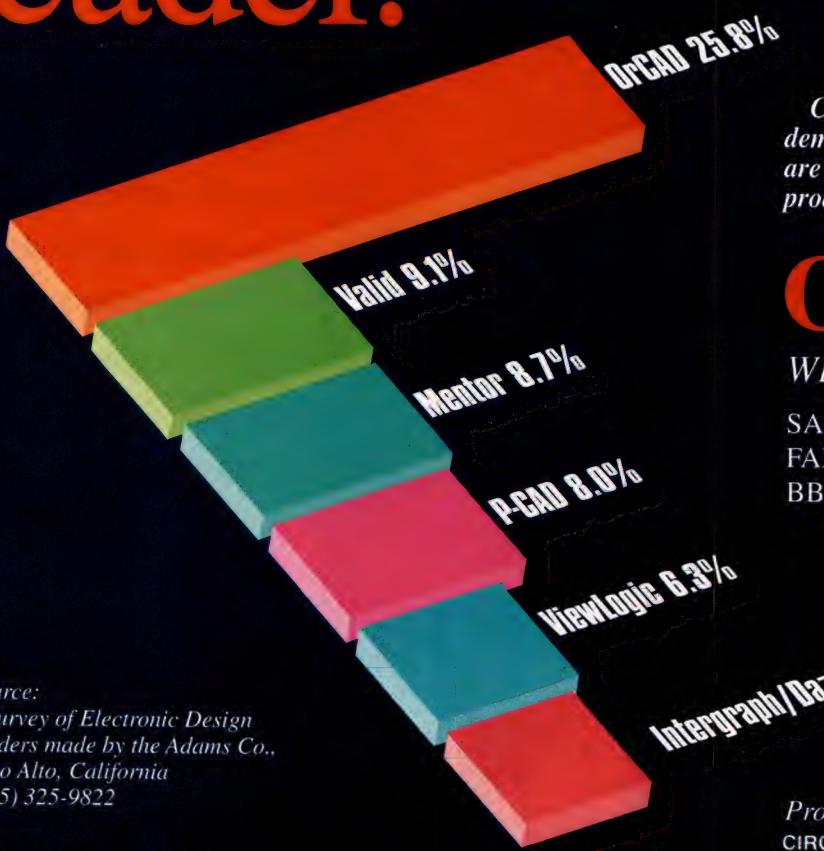
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## Criteria for manufacturable IC

Concerning Charles Small's editorial, "Make FPGA design easier" (EDN, October 10, 1991, pg 49), I'd like to add my perspective. I'm an engineer at a manufacturing plant where I'm the process owner for IC programming.

FPGA manufacturers, in addition to lacking the vision that they are in the IC manufacturing business, not the software business, haven't even made their devices fully manufacturable. Instead of using the JEDEC format for programming files, some use binary or POF formats. (For those who use Data I/O equipment, these formats correspond to Translation Formats 10 and 14, respectively.) These formats wreaked havoc with my programming system because of their non-ASCII nature. FPGA manufacturers also seem to prefer that I use their development systems rather than my industry-standard equipment to do my production programming.

A fully programmable IC must meet these criteria:

1. The programming file must be ASCII readable. Not only does this allow easy, reliable transmission from my design group in New Jersey, but it also allows me to write software to check its integrity.
2. All manufacturing functions must be supported by industry-standard, production-grade equipment. These include, but may not be limited to

- Reading a master device into the programmer's RAM.
  - Uploading the programmer's RAM to a host computer.
  - Verifying the device from RAM.
- This presupposes that test vectors can be generated and added to the (ASCII) programming file.
- IC handling machines connected to the programmer can be used. (The interface I have between programmer and handler

doesn't support certain FPGAs.)

- Gang programming should be supported for those limited to manual operations.
- Downloading of programming files from a host computer into the programmer's RAM.
- Blank-device check.

I'm currently stuck programming FPGAs one at a time, taking 5 or 10 minutes for each.

Not only have FPGA vendors locked up the design of these wondrous devices, but they have also locked up the mass programming, too. These vendors would stand to gain a fortune if these two areas were freed up so that their devices could be put into widespread use.

*Bill Fox*

*AT&T, Network Systems  
The Columbus Works  
Columbus, OH*

## Need of harmonizing European partners in trade

I've just read the article, "The economic challenge of a united Europe" by Jay Fraser, on the consequences of the Single European Market (EDN, November 7, 1991, pg 355), and I felt compelled to put pen to paper. Then I remembered that, despite living in "low-tech" Europe, I do have access to word-processing and fax facilities so I threw away the quill pen and shot the carrier pigeon—this is the result.

Europe is not quite as weak on high-tech as the article implies. We may not have put a man on the moon, but we are more than capable of producing high-tech products. A major problem facing Europe as a single market is the harmonization of standards that have followed separate evolutionary paths for hundreds of years.

[The differences] obviously cannot change overnight, if at all. Neither will I be running out to change all the main sockets in my house so I can buy a CD player in Dusseldorf. What Europe means is that

there will be no difference between the cost of that CD player and the one on sale down the road due to some artificial tariff.

Eventually, when our politicians finish their posturings about national identities and other primitive tribalism, we may end up with a single currency. Perhaps it should be called the "Youess dollar," which would make it difficult for those who gamble on foreign exchanges at the expense of real wealth creation—but that's another issue!

*Peter J Osborn*

*Product Manager  
Newport Components Ltd  
Blakelands North  
Milton Keynes, UK*

## Changed phone number

The phone number listed for inquiries about Intel's iRMX for Windows in EDN's November 21, 1991, issue (pg 47) should be changed to (800) 438-4769.

## Calling all pizzas

If you want information about Motorola's MC-145191 frequency synthesizer, don't call the number we listed on pg 118 in the February 3 issue—you'll get information about Domino's pizza instead. Try the correct number: (800) 521-6274.

## HAVE YOUR SAY

EDN's Signals & Noise column provides a forum for readers to express their opinions on issues raised in the magazine's articles or on any topic that affects the engineering industry. Send your letters to Signals & Noise Editor, EDN Magazine, 275 Washington St, Newton, MA 02158. You can also send a note via MCI mail at EDNBOS or use EDN's bulletin-board system at (617) 558-4241: From the Main System Menu, enter SS/SOAPBOX, then W to write us a letter. You'll need a 2400-bps (or less) modem and a communications program set for 8,N,1.

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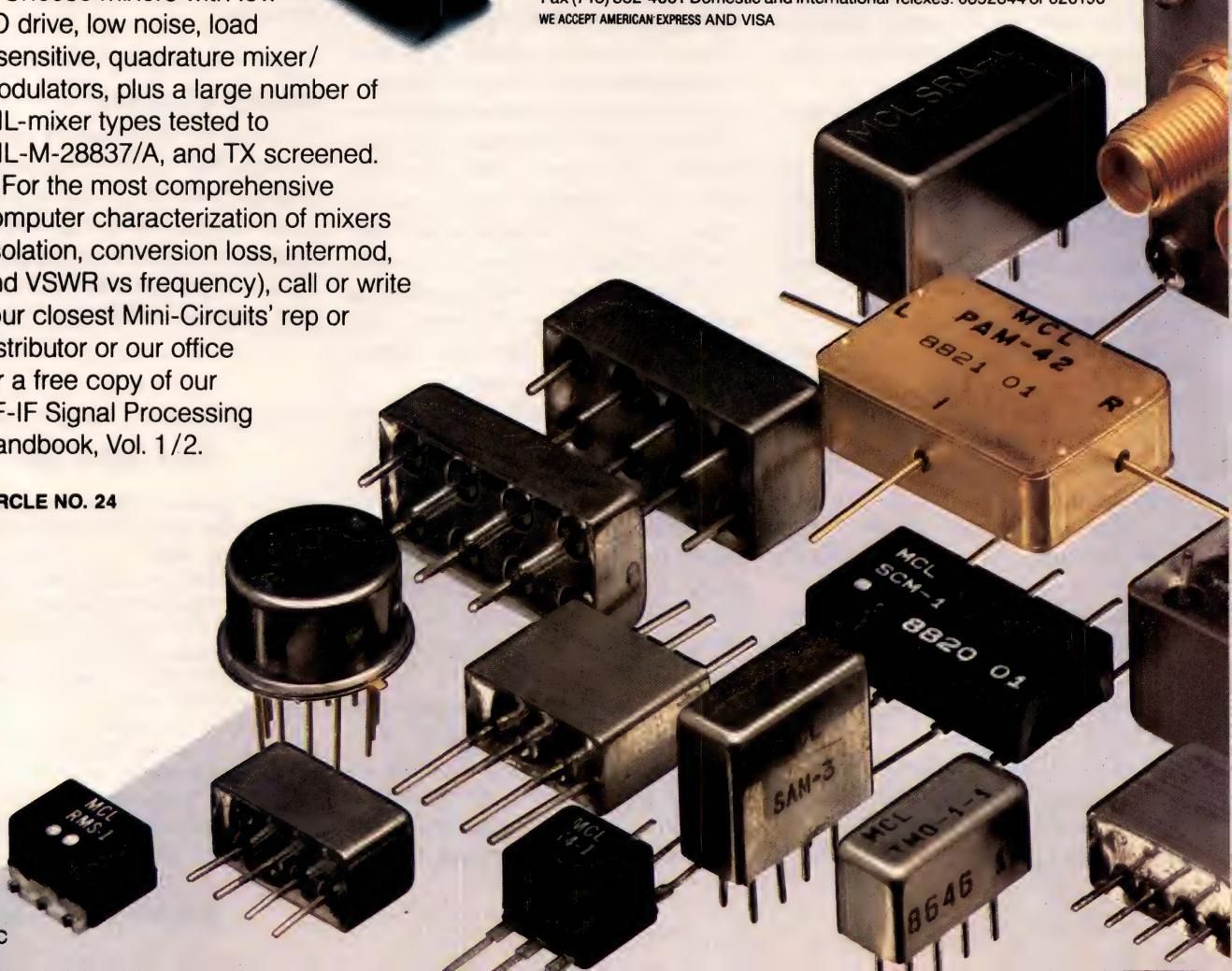
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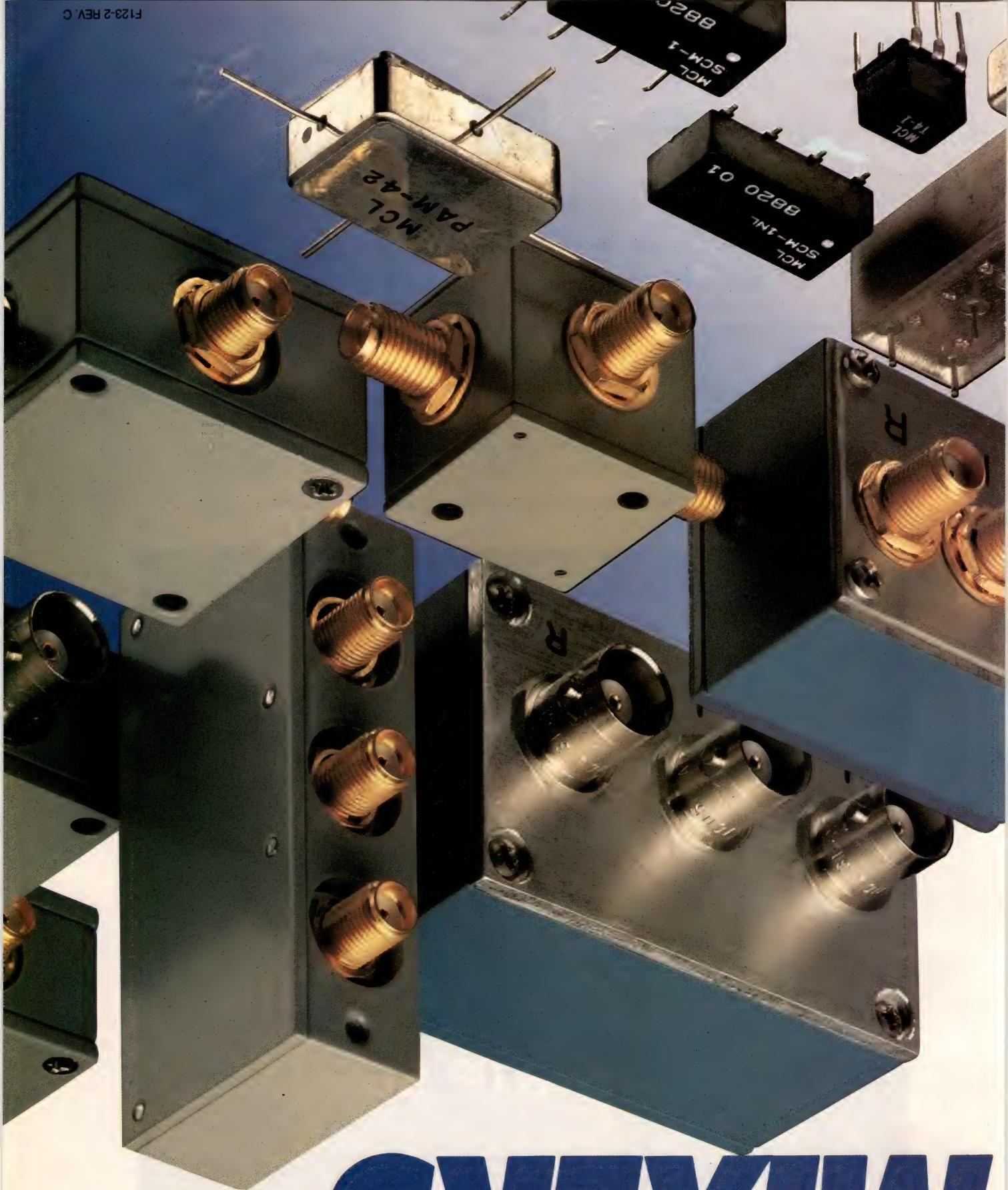


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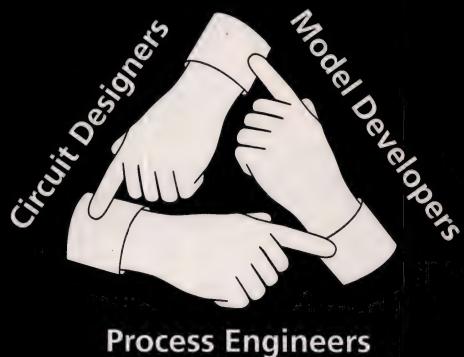
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## Getting small quantities is tough all over

After printing Peter Gottlieb's letter about the difficulties he experiences getting small quantities of state-of-the-art parts for making prototypes, Ask EDN has received dozens of replies. All of the replies reinforced Mr Gottlieb's complaint. Here's a sampling of the letters:

## Industry ignores the independent engineer

I believe Peter Gottlieb has understated the problem. I am an electrical engineer running my own business with two part-time engineers and one part-time secretary. I work on the design and prototyping of computer/microcontroller-based process controllers and custom computer bus interfaces. I generally do three or four complete designs a year. Not only do I have a difficult time obtaining small quantities of parts, but I have difficulty getting manufacturers' data books or even return phone calls from distributors of manufacturers' sales offices. I have even been turned down as a qualified subscriber to EDN. It is nearly impossible to be an independent engineer and stay afloat with the industry ignoring me.

Joe Heck  
Owner  
Joe Heck Enterprises  
Wrentham, MA

## Lack of custom parts for repair results in landfill

The letter from Mr Gottlieb hit a nerve with me. At least he has the option of ordering "production quantities" of some items—in my case, five may be a year's supply. If I had to order 1000, I'd have to find a way to resell them.

A related problem: Our company is primarily in the repair business, although we do build one-offs and short runs. Question: What happens when some of these wonderful new de-

signs made with gate arrays, PLDs, and other such custom parts go wrong? (Notice I said "when," not "if.") Chances are the manufacturer won't have any of the gate arrays left, and of course the design will be proprietary, so telling anyone else about it is out of the question. Result: landfill. And that's regardless of whether the product is otherwise any good or not. In a way, this is a "green" issue. What happens when all this wonderful stuff starts being tossed out because one flip-flop in a 3000-gate array went out, rendering half a ton of equipment useless?

Ric Locke  
E Coyote Enterprises Inc  
Mineral Wells, TX

## Seed small companies with state-of-the-art parts

In reference to the problem expressed by Peter Gottlieb in the December 5, 1991, issue of EDN, I too have experienced continuing frustration with the difficulty of obtaining small numbers of state-of-the-art components for constructing prototypes.

Manufacturers of ICs and other components fail to realize the importance of seeding small corporations with components that they can use to design new products. Like Mr Gottlieb, I too would be all too happy to pay full price for the privilege of getting a small quantity of state-of-the-art components. This would be preferable to jumping through manufacturers' hoops trying to get "freebie" samples.

Please listen, you big IC guys. Sell some of your best stuff to distributors like Allied Electronics or Newark Electronics, charge full price, and let us buy a few to make prototypes. You'll be doubly rewarded. Not only will you get paid for your samples, but some of those samples will turn into products that result in big orders. The most innovative companies are the small ones; that's where the least amount of seed will yield the most product.

Mark Wilson, MD  
President  
Enkef Instruments Inc  
Boulder, CO

## Turn problem into business opportunity

Regarding Peter Gottlieb's complaint in the December 5, 1991, issue: If it's not too late, I'd like to add my name to the amen column. Not only is finding prototype quantities of parts time consuming for a lot of people—with the commensurate lack of productivity—you sometimes settle for a little less than your best in a design just to get it moving. The problem is serious enough that I don't know why someone hasn't turned it into a business opportunity, something like a specialized Digi-Key, if you will. There should be a way to have some kind of shared service.

Jim Pierce  
JN Designs Inc  
Kansas City, MO

## Try Dallas Semiconductor

Amen to Peter Gottlieb's observations about obtaining prototype quantities of electronic parts. Yes, Mr Gottlieb's experiences are typical.

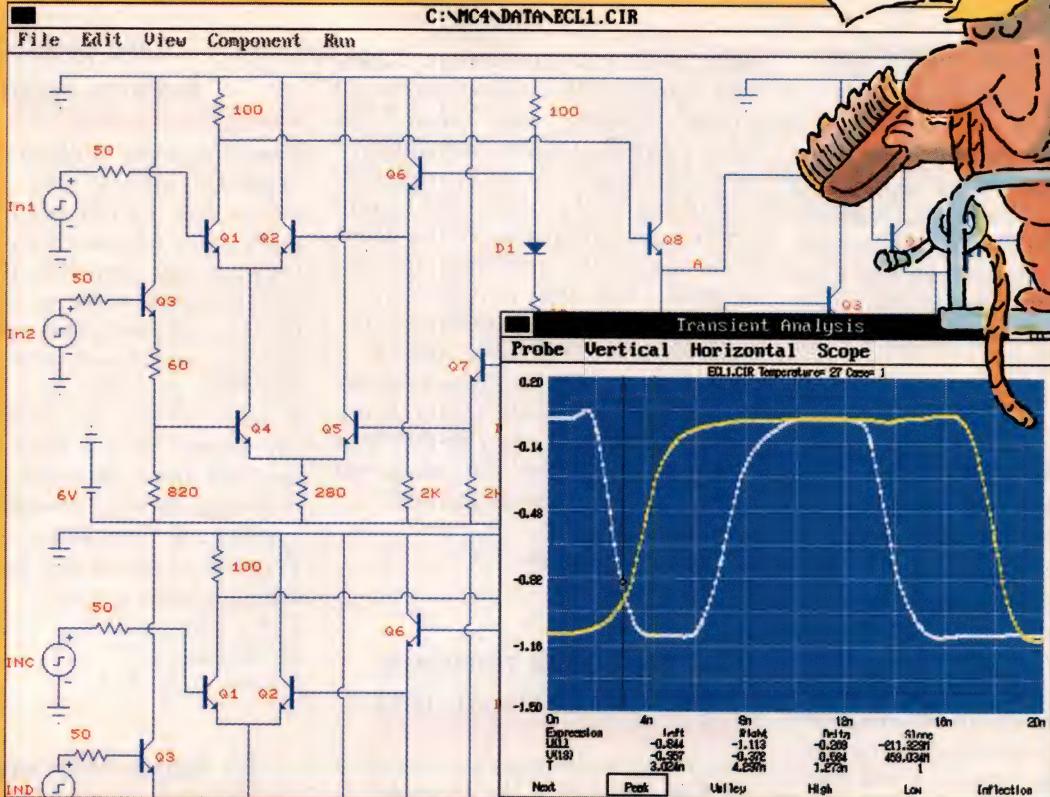
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Too bad most companies don't do this.

Walt Henry  
Fort Worth, TX

---

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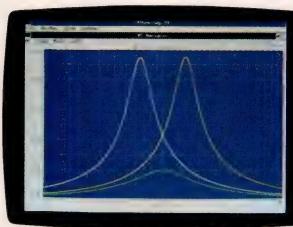


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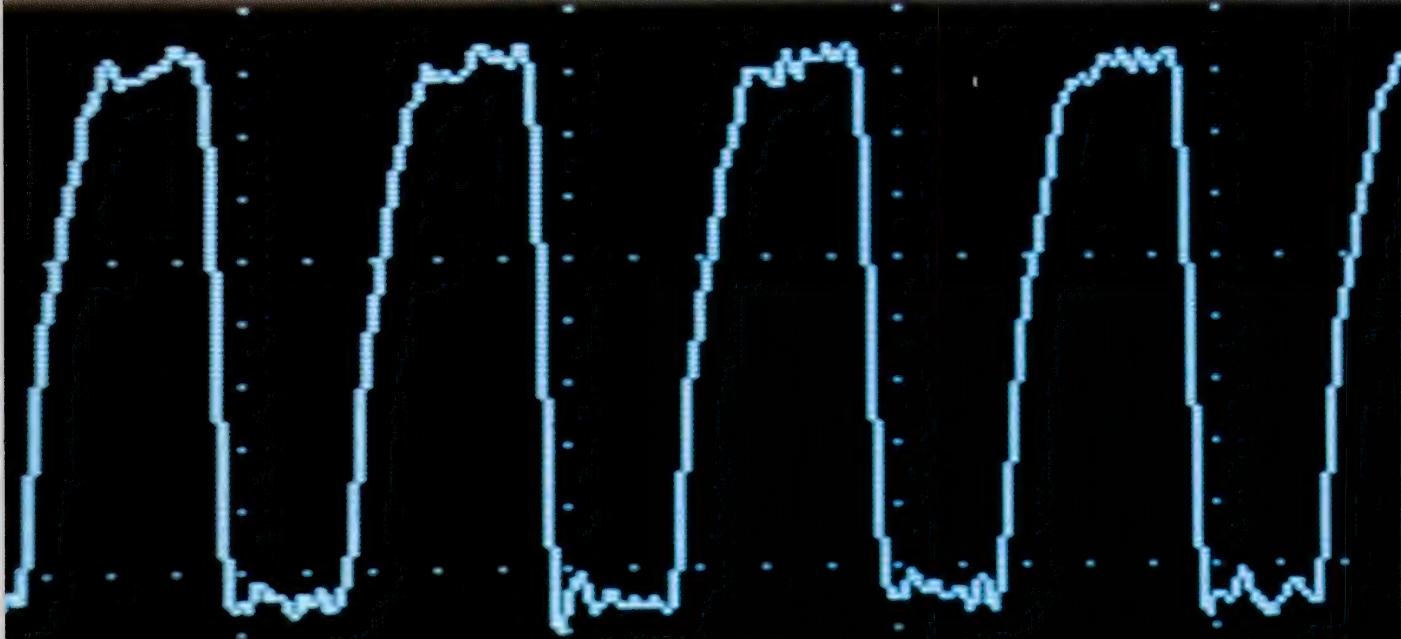
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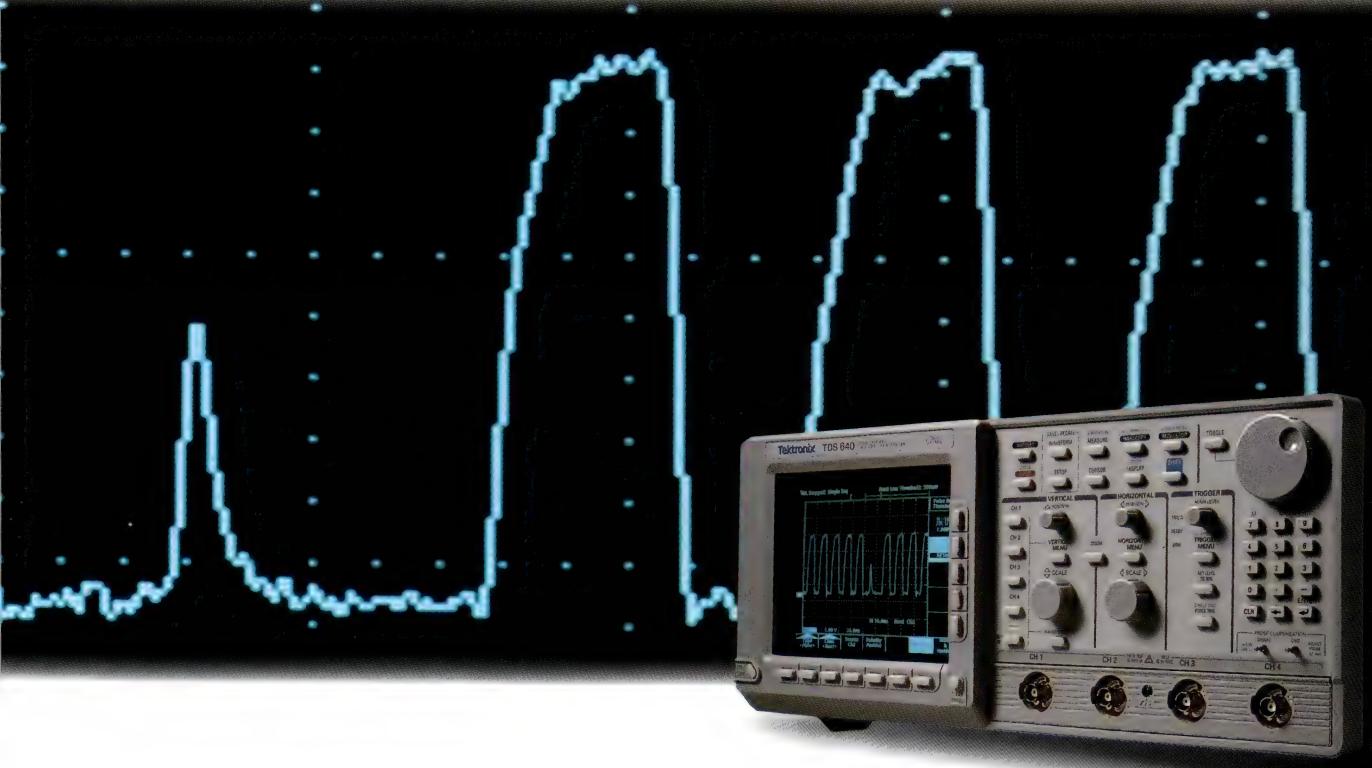
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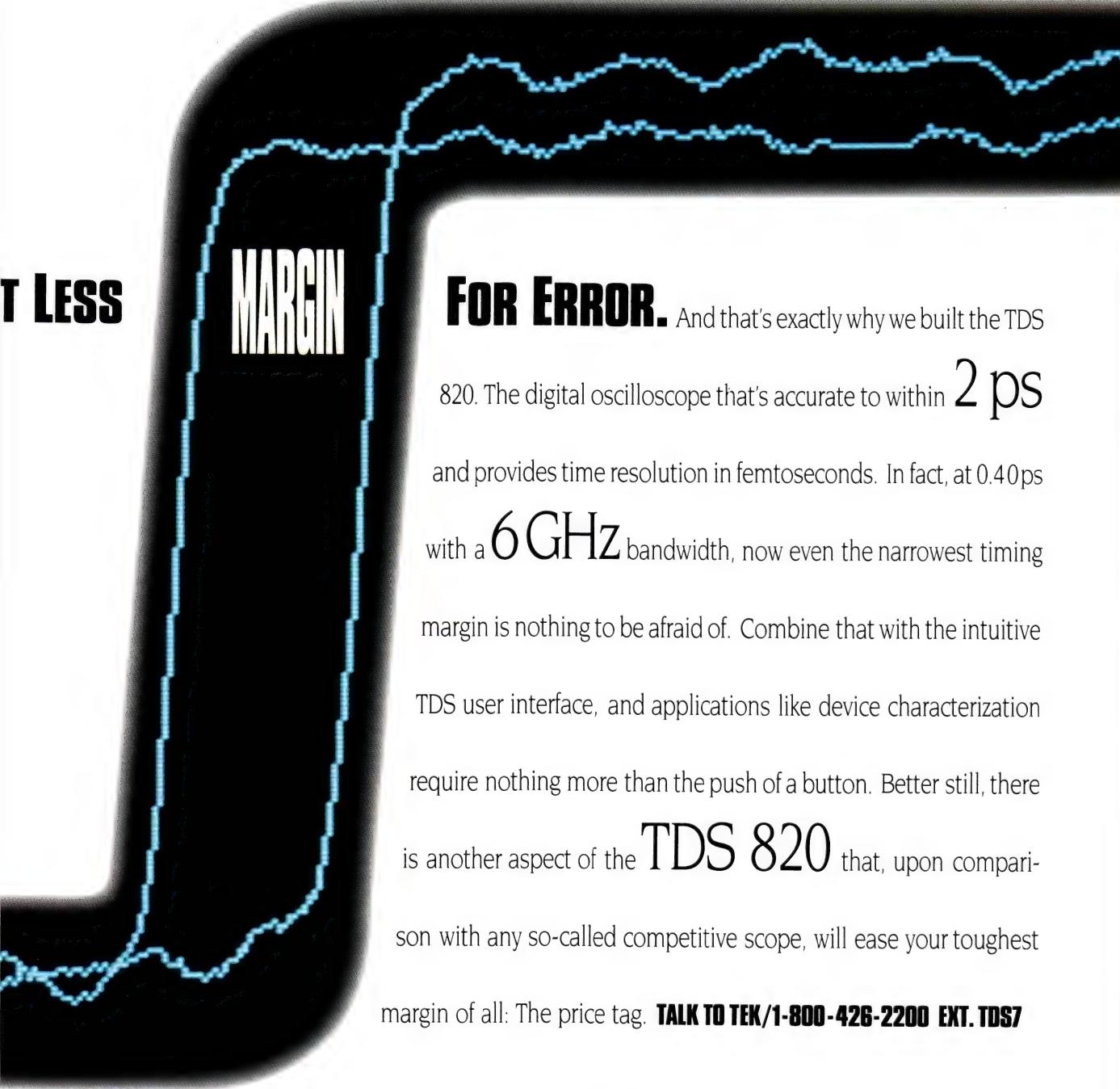
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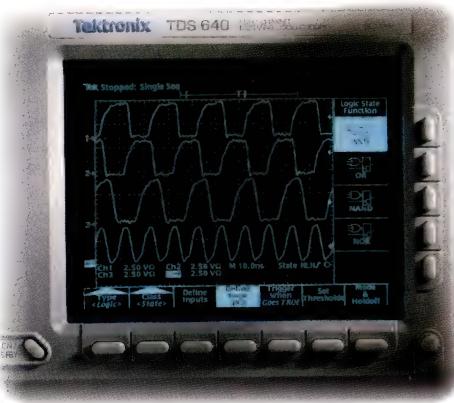


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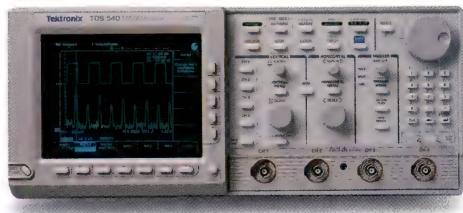
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# Get real



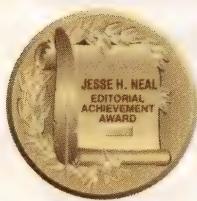
My son Chris has a problem with most of the auto manufacturers that feature futuristic vehicles at the auto shows. He thinks that unless car manufacturers are really going to offer those cars for sale, they shouldn't show them. I've explained that the futuristic cars at the shows are only testbeds for new technologies and are proof-of-concept vehicles. In fact, many of the tested technologies and designs never make it to market. Either they turn out to be too expensive, no one wants them, or they just don't work. Chris makes a good point, though: Why whet the consumers' appetites when you don't expect to offer the product? I imagine there are others who feel the same way.

Unfortunately, the electronics industry does much the same thing. Companies often announce or demonstrate products that won't reach the market for a year or more—if ever. For example, some people in our industry take the International Solid State Circuits Conference (ISSCC) as a watershed event at which people announce new products. It isn't. The ISSCC gathering is worth attending if you're a chip designer. You'll hear what other companies are doing, and you'll have an opportunity to talk about your own develop-

ment work. However, don't depend on the meeting's papers as plans for new-product introductions.

We found only a few developments at this year's ISSCC that were set for use in new products within the next quarter. Many of the developments are like the jazzy cars at the auto show. They're one-off models built to test concepts and processes. Testing new ideas is important, as is sharing ideas, and for IC designers, the ISSCC is a good forum. However, there's a big gap in time and cost between talking about ideas and demonstrating test devices, and actually delivering useful products. Some developments never make it out of the lab.

When new processes and technologies begin to show up in real products, we'll let you know. Sure, there will be times when you need to know about complex new products before they become available, but overall, readers tell us that when a product is more than six months from being available for purchase, hold off on telling them about it. After all, what's the use of knowing about a "product" that doesn't exist when you need a real product or design to solve a real problem?



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1990 Certificate, Best Series  
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**Jon Titus**  
Editor

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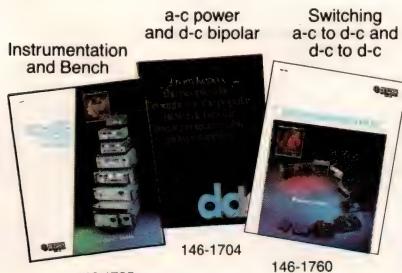
<sup>(1)</sup>LabWindows © National Instruments



## Power tools



Three 360W Power Modules shown in RA 50 Housing



LabWindows runs on 386 DOS-based computers with a VGA display and, of course, a mouse. We have drivers for all of the SN digital interfaces, type MAT power supplies and the low-voltage BOP series bipolar power supplies. The PC can drive the power supplies via the IEEE-488 bus using Kepco's model TMA 488-27 interface to fan out from one GPIB address to as many as 27 power supplies, or the PC can drive the power supplies directly via an internal half-card called TMA PC-27. The BOP require the plug-in interface card, BIT TMA-27.



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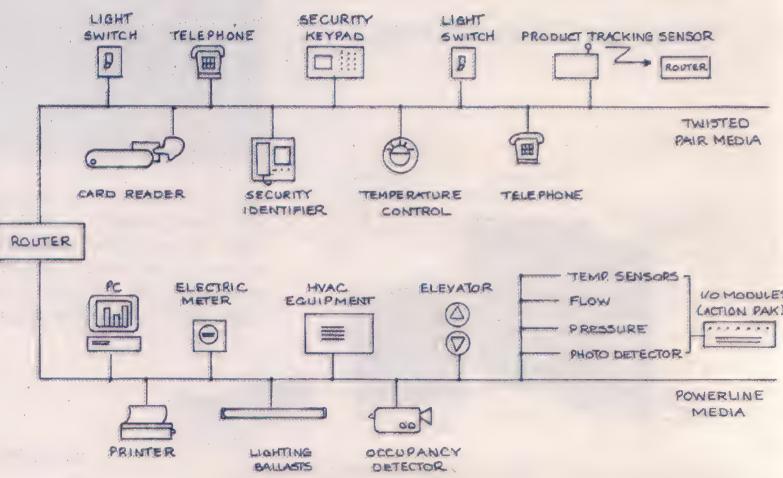
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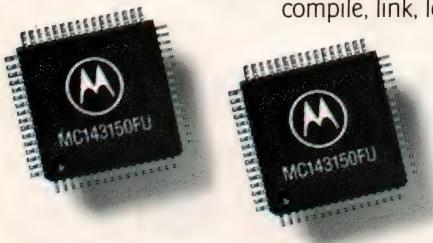
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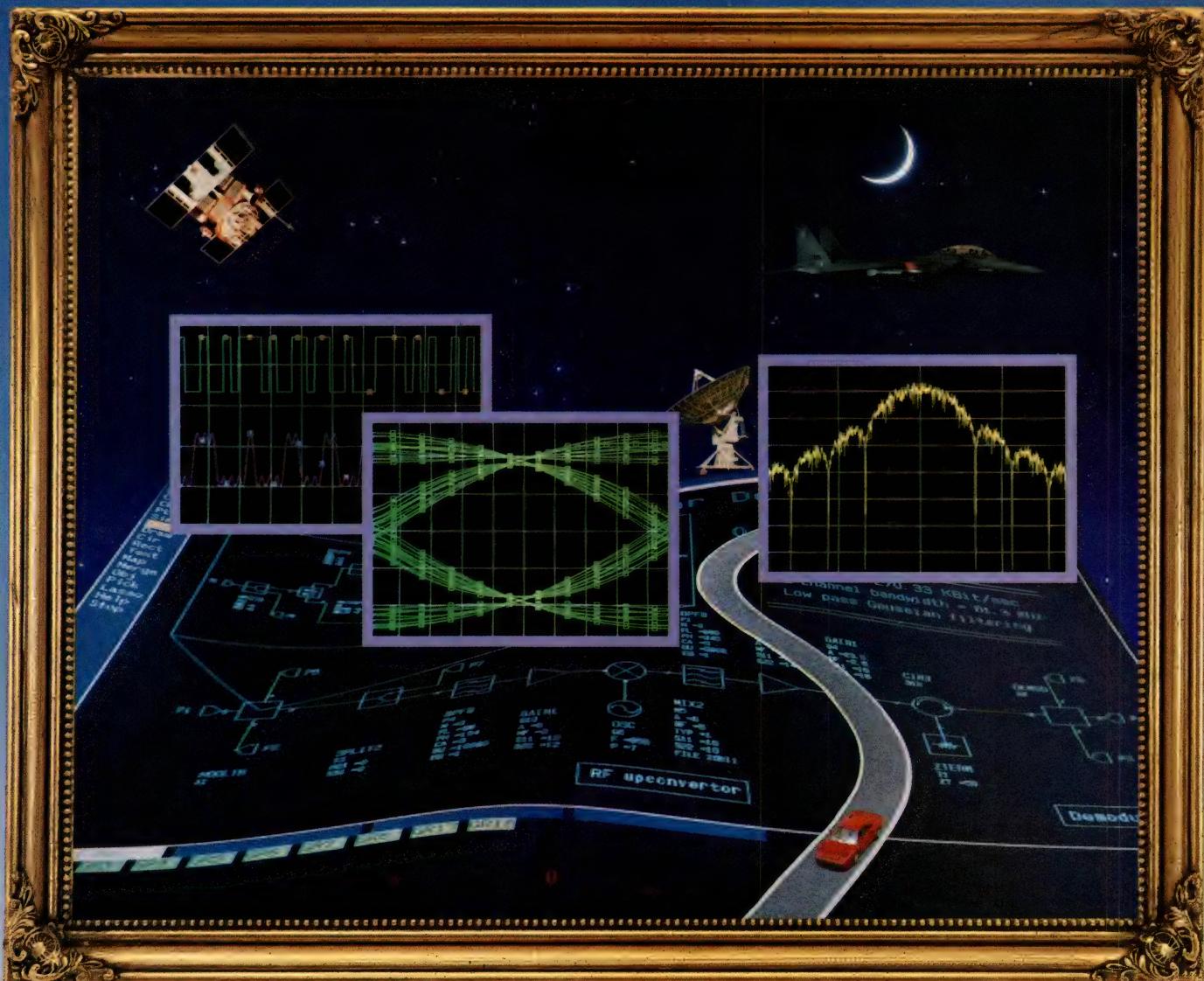
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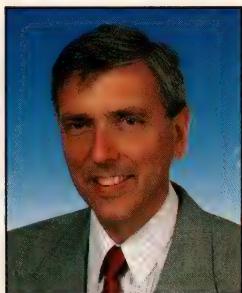
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## MICROPOWER VOLTAGE REFERENCES

# Microamps sustain stable sources

BRIAN KERRIDGE, Technical Editor



**Micropower bandgap references provide an attractive alternative to power-hungry zener diodes. But selection, handling, and application of these components remain decisive issues in setting overall performance.**

Achieving a stable voltage is possible using a micropower reference component that consumes as little as 10- $\mu$ A operating current. With other key specifications, like voltage TC (temperature coefficient) of 20 ppm/ $^{\circ}$ C, slope-resistance of <1 $\Omega$ , and a one-dollar price tag, suddenly a 7.5-mA reference zener looks like a luxury that power-conscious designers can no longer afford.

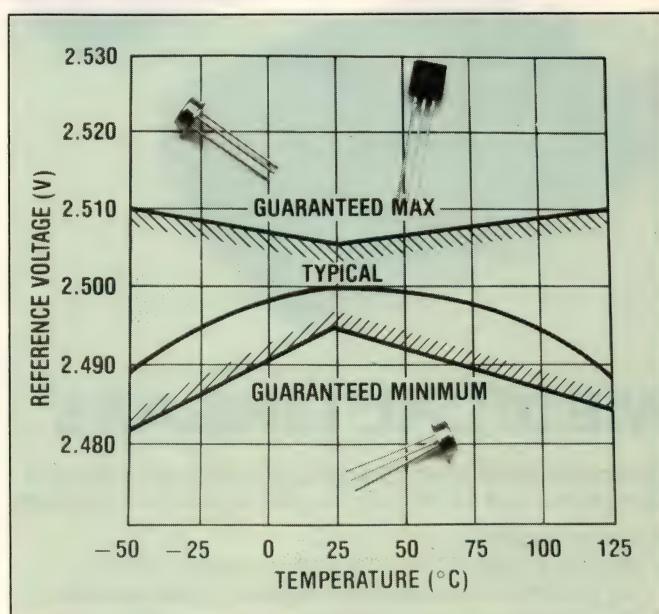
All semiconductor references rely upon either zener diode or bandgap operation for generating a stable output voltage. All micropower examples use the bandgap reference principle, which is explained in more detail in the box "Generating a bandgap voltage reference."

A great attraction of bandgap devices is that the primary reference level is inherently a minimum of approximately 1.2V. (Zeners with comparable performance to bandgap devices don't exist for levels much below 6V.) In addition, vendors offer bandgap references with output levels of 2.5, 4.1, 5, and 10V, or with the facility to trim output externally to any point within this range.

By far the greatest appeal of bandgap devices is the ability to function with operating currents from milli- down to microamps. Table 1 overviews the specifications of bandgap devices that have minimum operating currents below 100

$\mu$ A, and therefore includes examples that truly qualify as micropower.

The major application for micropower references is to provide a reference source for ADCs and DACs, and increasingly in these applications manufacturers combine converters and references on-chip. Other important applica-



The curved TC-response of Linear Technology's LM185-2.5 is typical of most micropower references. Quoted TC figures assume a straight-line average from room ambient to temperature extremes.

tions include the primary reference circuit for any battery-powered measuring instrument, battery-condition detectors, and level detecting circuits for initiating protection and control of other circuitry during power-up and power-down, or power-supply transient situations.

Table 1 clearly illustrates the voltage-noise drawback associated with all bandgap devices. For example, 60- $\mu$ V rms

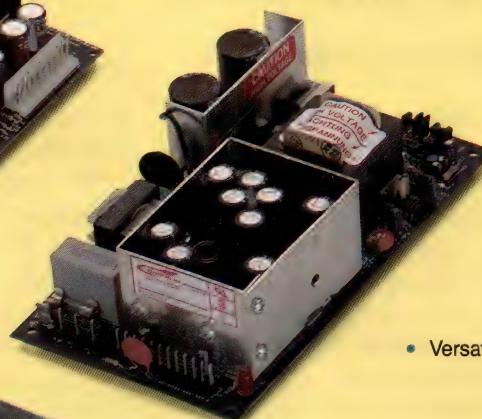
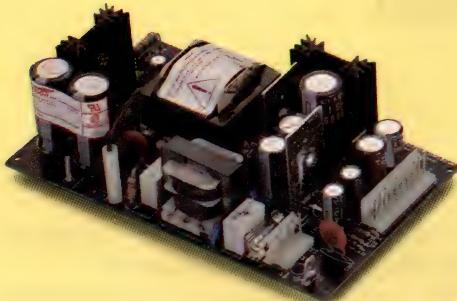
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  - 24-hour full-load burn-in and 2-year warranty
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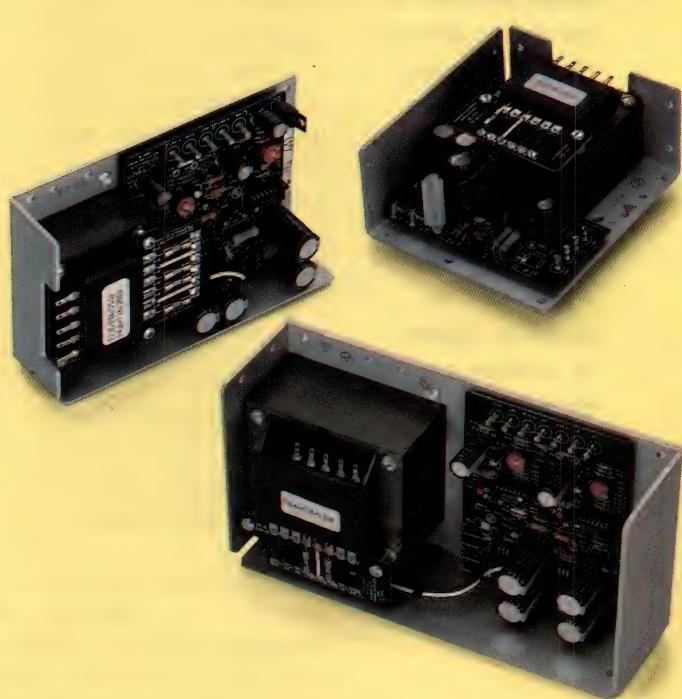


## MEDICAL LINEARS

Condor's M-Series offers 38 single and multi-output models, all designed to meet the toughest international safety requirements.

### M-Series features:

- Designed to meet IEC 601, VDE 0750, UL 544 and CSA C22.2 No. 125-M1984 medical safety specifications — most approvals are complete
- Less than 8 $\mu$ A leakage current
- Meets stringent FCC and VDE 0871 Class B EMI specs without additional filtering
- Worldwide AC input ranges
- Industry-standard packages
- 8-hour, full-load burn-in and 3-year warranty
- Tested I.C.'s and 105 °C capacitors used throughout
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**MICROPOWER VOLTAGE REFERENCES**

for a 10-Hz to 10-kHz bandwidth is typical. This figure represents at least ten times the voltage noise exhibited by reference zeners, particularly buried types.

Take care when comparing noise performance in vendor's data, as it's

common to find figures expressed as  $\mu\text{V}/\sqrt{\text{Hz}}$ , p-p, or rms, and over different bandwidths—even by the same vendor. What is more useful to know is the p-p noise in ppm over the bandwidth of interest. You can then easily translate p-p noise to

digits of error on an ADC, DAC, or digital readout. For a 1.2V micropower reference, the typical figure of 60- $\mu\text{V}$  rms is equivalent to 300-ppm p-p noise error. If you use such a device as the internal reference for a meter or data converter,

**Generating a bandgap voltage reference**

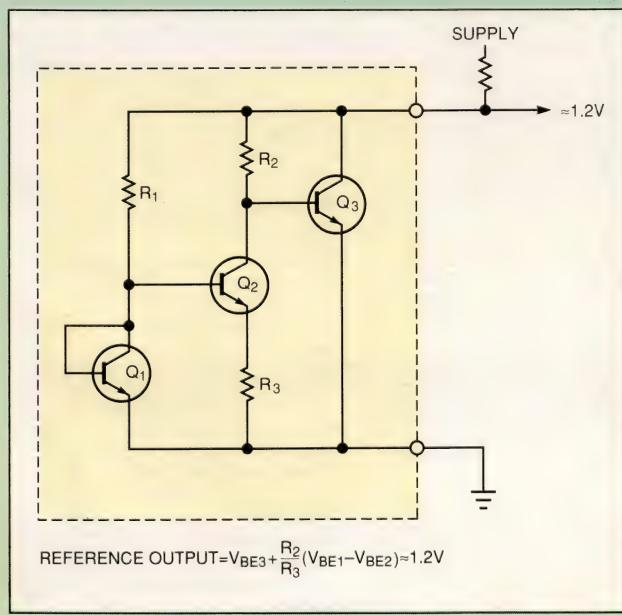
All micropower references rely upon the "bandgap" principle for operation. At the heart of each reference are two similar transistors operating at roughly a 10:1 current-density ratio. **Fig A** shows the essential circuit elements. If the collector current in  $Q_1$  is approximately ten-times that in  $Q_2$ , then the  $V_{BE}$  difference for the two transistors at 25°C is around 60 mV, with a negative TC of approximately  $-0.2 \text{ mV}/^\circ\text{C}$ . These numbers result from a simple analysis using Ebers-Moll equations for a p-n junction (for more on Ebers-Moll equations, see **Ref 1**). The key factor that determines these figures is the operating current-density ratio in the two transistors. In practice, chip geometry maintains the current-density ratio, since designers can accurately lay down transistors with emitter areas of a fixed ratio. Often, an 8:1 ratio is chosen.

The negative TC  $V_{BE}$  difference across  $R_3$  translates to a positive TC collector current in  $Q_2$ , which tends to lower  $Q_2$ 's collector voltage with rising temperature. If

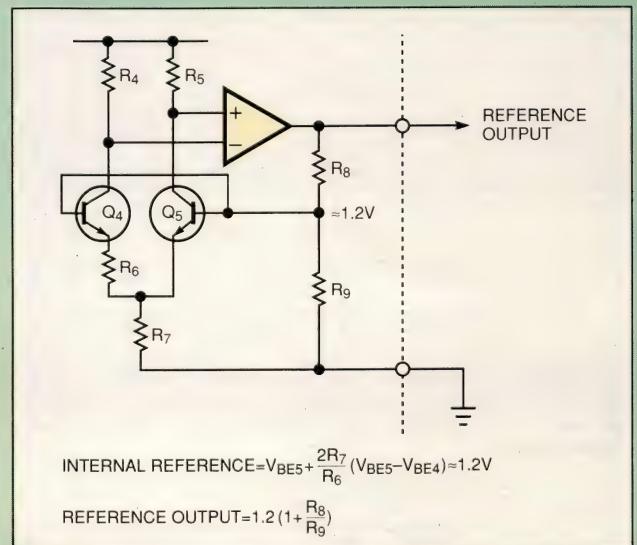
you choose the ratio  $R_2:R_3$  appropriately, then you can make the positive TC voltage across  $R_2$  balance the negative TC  $V_{BE}$  of another similar transistor, in this case  $Q_3$ . Adding the two voltages produces a reference output voltage that is stable with temperature, and in practice a 1.2V output exhibits zero TC.

More often, you need reference levels greater than 1.2V, and it's common to find the circuit shown in **Fig B**. The circuit still uses the same bandgap difference to produce a stable 1.2V level, but additional level-shifting and amplifier circuits produce a range of other reference levels depending upon the value of  $R_8$  and  $R_9$ .

Both circuits shown in **Figs A** and **B** are simplified versions of what you will find in the latest micropower references. Reference designers install a multiplicity of additional circuitry for compensating secondary effects on TC and to produce low slope resistance. Laser trimming resistors to produce close-tolerance output voltages adds further complexity.



**Fig A**—Bandgap reference circuits produce a temperature-stable output voltage by combining the +TC voltage across  $R_2$  in series with -TC  $V_{BE}$  of  $Q_3$ .



**Fig B**—Transistors  $Q_1$  and  $Q_2$  operate at the same  $I_C$ , but have different emitter area. Consequent current-density difference produces  $V_{BE}$  bandgap difference across  $R_6$ . Internal bandgap reference voltage ( $\approx 1.2\text{V}$ ) appears across  $R_9$ . Reference output voltage is set by ratio  $R_8:R_9$ .

**MICROPOWER VOLTAGE REFERENCES**

then this error would contribute directly to approximately 1 digit of run-around on a 12-bit ADC or DAC or 2 to 3 digits of run-around on a 4.5-digit display.

In practice, applying a simple low-pass filter across the reference's output reduces noise for most applications. But to obtain appreciable noise reduction, you need to restrict bandwidth to roughly 10 Hz, and this requires large components that take up valuable pc-board space and increase component cost. You need to take care with this ad-

dition, as a reference's output is active and adding only a capacitor directly across the terminals is likely to induce oscillation.

The relatively poor characteristic noise performance of bandgap devices derives from their low operating-current design. Micropower examples suffer proportionately more, since operating currents down to 10  $\mu$ A are permissible. The problem is one fundamental to any low-current IC design. By virtue of the design, internal IC resistor values need to be high, as are intrinsic

transistor resistances when operating at such low currents ( $I_C$  may be  $<1 \mu$ A). Consequently, you cannot avoid Johnson noise in these high resistances. In fact, Johnson noise forms the dominant noise source in a micropower reference. Types with outputs boosted above 1.2V have higher noise levels still, since additional internal components make their noise contribution to the amplified inherent noise.

Selecting a micropower reference with a voltage TC anywhere from 100 down to 5 ppm/ $^{\circ}$ C simply de-

**Table 1—Representative micropower voltage references<sup>1</sup>**

Manufacturer	Type	Voltage	Operating-current (min) ( $\mu$ A)	TC max (-40 to +85 $^{\circ}$ C) (ppm/ $^{\circ}$ C)	Noise (typical)	Output slope resistance (max) ( $\Omega$ )	Package	Comments	Price <sup>3</sup> (100)
Analog Devices	REF-195	5.0V $\pm$ 0.02%	30	4 ppm/ $^{\circ}$ C $\pm$ 1 mV	50 $\mu$ V p-p, 0.1 to 10 Hz	0.01	Plastic and ceramic 8-pin DIP, SO-8	2-stage output adjust-laser trim on wafer and fuse links after packaging; output sources to 30 mA.	\$1.95
GEC Plessey Semiconductors	SR12D	1.23V $\pm$ 3%	90	120	10 $\mu$ V rms, 1 Hz to 25 kHz	2.5	SOT-23	Other voltages 2.5 and 5V, maximum operating current 2.5 mA.	\$1.10
	REF12	1.26V $\pm$ 1%	60	56	1 $\mu$ V/ $\sqrt$ Hz 0.1 Hz to 25 kHz	4	TO-92, MP-8	Other voltages 2.5 and 5V, maximum operating current 2.5 mA, TC in MP-8 package is 80 ppm/ $^{\circ}$ C.	\$1.10
Linear Technology	LT1004C-1.2	1.20V $\pm$ 0.3%	10	20 typ <sup>2</sup>	60 $\mu$ V rms 10 Hz to 10 kHz	0.6	TO-46, TO-92	Other voltage 2.5V, maximum operating current 20 mA, long-term stability 20 ppm/1000 hours.	\$1.35
	LT1034C-1.2	1.20V $\pm$ 1%	20	40 <sup>2</sup>	4 $\mu$ V p-p 0.1 to 10 Hz	1	TO-46, TO-92	Other voltage 2.5V, maximum operating current 20 mA, package includes 7V zener reference.	\$2.85
	LM385-2.5	2.50V $\pm$ 1%	20	20 typ <sup>2</sup>	120 $\mu$ V rms 10 Hz to 10 kHz	1	TO-46, TO-92	Maximum operating current 20 mA, long-term stability 20 ppm/1000 hours.	\$0.80
Maxim	MAX872	2.50V $\pm$ 0.1%	10	40 <sup>2</sup>	60 $\mu$ V p-p 0.1 to 10 Hz	0.3	Plastic 8-pin DIP	Minimum supply voltage 2.6V, trim-pin for +100 mV to -25 mV adjustment.	\$2.25
	MAX874	4.10V $\pm$ 0.1%	15	40 <sup>2</sup>	90 $\mu$ V p-p 0.1 to 10 Hz	0.3	Plastic 8-pin DIP	Minimum supply voltage 4.2V, trim-pin for $\pm$ 0.2V adjustment.	\$2.25
	ICL8069	1.23V $\pm$ 1.6%	50	100 <sup>2</sup>	5 $\mu$ V rms 10 Hz to 10 kHz	2	TO-52, TO-92	Maximum operating current 5 mA, TC selection to 10 ppm/ $^{\circ}$ C.	\$1.13
Micro Power Systems	MP5010	1.22V $\pm$ 2.5%	50	100	5 $\mu$ V rms 10 Hz to 10 kHz	2	TO-52, TO-92, or SO-8	Maximum operating current 5 mA, TC selection to 5 ppm/ $^{\circ}$ C	\$0.86
National Semiconductor	LM385-1.2	1.2V $\pm$ 3%	10	150 <sup>2</sup>	60 $\mu$ V rms 10 Hz to 10 kHz	1.5	TO-46, TO-92, or SO-8	Maximum operating current 20 mA, other voltages 2.5V and adjustable, voltage selection to $\pm$ 0.3%, long-term stability 20 ppm/1000 hours.	\$0.94
	LM4040	2.5V $\pm$ 2%	65	100	35 $\mu$ V rms 10 Hz to 10 kHz	0.8	TO-92, SO-8, or SO-23	Maximum operating current 20 mA, other voltages 4.1, 5, 8.2, and 10V, voltage selection to $\pm$ 0.1%.	\$0.85

**Notes:**

1. Specifications at 25 $^{\circ}$ C unless otherwise stated.

2. TC for ambient temperature range 0 to 70 $^{\circ}$ C.

3. Prices shown for TO-92 where available, or plastic 8-pin DIP.



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\*V/ $\mu$ s   \*\*BW

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pends upon how much you are prepared to pay. For approximately \$1 you get a typical 20 ppm/ $^{\circ}\text{C}$  device. For a guaranteed maximum of 5 ppm/ $^{\circ}\text{C}$ , you'll pay more than \$10. At this level, micropower reference TC performance equates to the best specification reference zeners, such as 1N829A.

In all cases, the TC figure quoted in specifications is a straight-line average of a curved response taken from the midpoint to the extremes of the operating temperature range. The reference designers arrange that the TC approaches zero somewhere around room-ambient temperature. As the operating temperature moves off to either the maximum or minimum limit, the reference's output voltage falls more and more rapidly. Manufacturers apply various forms of compensation to iron out this basic curved response, but the TC result is never linear over the full operating temperature range.

### Stress influences stability

Long-term performance of micropower references is something most vendors are reluctant to specify, since this specification is very much stress related, and therefore dependent upon application. Linear Technology quotes a figure of 20 ppm/1000 hours for all its micropower references. This figure is worst case over the first 1000 hours, because as the component ages, the voltage increasingly stabilizes. As a rule of thumb for designing-in micropower references, you can safely assume a long-term stability specification of 20 ppm/ $\sqrt{1000}$  hours when you operate the component at room ambient.

However, if you operate references at extremes of temperature, then expect other effects to appear. For example, if you temperature cycle a reference from room ambient to its maximum or minimum operating temperature and back, you may see a hysteresis jump in output

voltage as high as 100 ppm. Stress in the die and package forces changes into the reference circuit to cause this jump. The reference output voltage will eventually recover close to its original value over several days of operation.

If long-term stability is a major concern, then oven baking all your reference parts at 150°C for a couple of days before you use them generally proves beneficial. This process tends to relieve initial stress left in the die and package following component manufacture, which in turn influences stability.

This effect raises the issue of choice of packaging in general. Although most vendors don't differentiate performance relative to package style, it's well known that choice of packaging does influence reference output voltage. In a plastic package for example, the moulding presses down on the top of the die, and therefore exerts a slight force. IC legs running through plas-

tic are not hermetically sealed, and therefore atmospheric changes can access the die. Plastic surface-mount packages introduce the additional possibility of a flexing pc-board's transmitting vibration through to the die. The net result is that your reference voltage performance is more likely to be further inside its published specification if you use a package that stands off from the pc-board, or even better has hermetically sealed legs (as in the case of ceramic or metal-can packages).

GEC Plessey Semiconductors is the only company to declare stability figures for different packages. Its REF12 1.2V references in TO-92 and 8-pin surface-mount packages have TC maximum values of 56 and 80 ppm/ $^{\circ}\text{C}$ , respectively.

With a favorable mix of specifications, micropower references, in general, can supplant zeners in many applications. Future references will offer tight voltage and

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For more information on the micropower reference products discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you read about their products in EDN.

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TC specifications by design, rather than by the expensive component selection route. Analog Devices' REF-195 exemplifies this trend with its 0.02% tolerance and 4 ppm/ $^{\circ}$ C as standard. However, 10  $\mu$ A as a minimum operating current is likely to remain simply because of fundamental noise problems. **EDN**

**References**

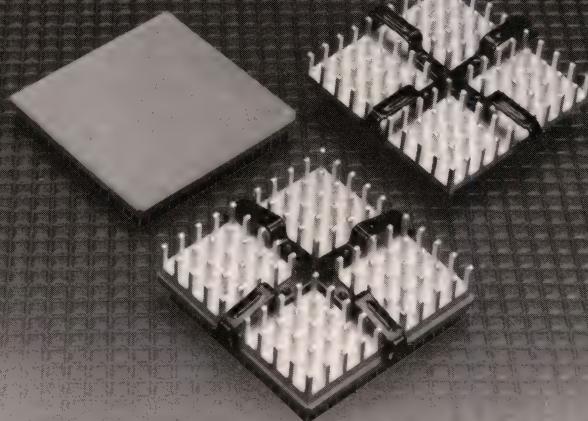
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3. Williams, Jim. "Micropower Circuits for Signal Conditioning." Linear Technology App Note 23, April 1987.

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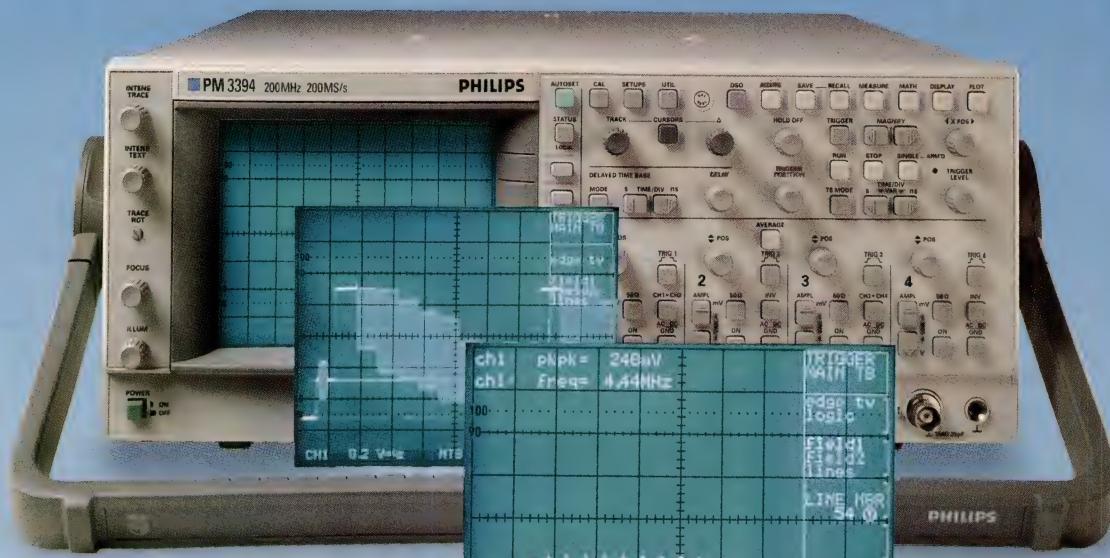
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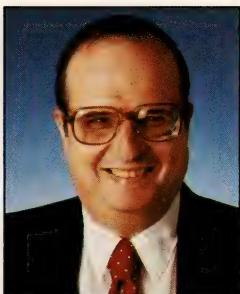


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## BATTERY-POWERED DSOs

# Versatile units find more use than you might expect

DAN STRASSBERG, Technical Editor



**Though widely thought of as tools for field service and, at times, for test, these rugged versatile instruments offer surprisingly good performance that often is just what design engineers need.**

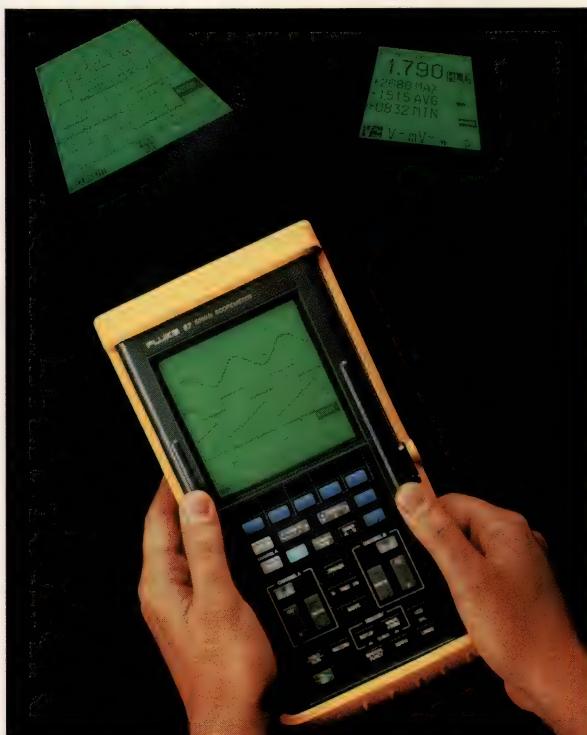
A product designed to meet the needs of a well-defined audience can appeal to a significantly larger group. Although the designers of three and possibly four of the five battery-powered DSOs in **Table 1** clearly had field-service engineers in mind, the scopes will also be useful to many design engineers.

Four of these five battery-powered DSOs (from Fluke/Philips, Gould, Leader, and Tektronix) feature small size and light weight. Three of the units (Fluke, Leader, Tektronix) weigh less than 5 lbs and fit easily into an attache case. These three units also provide input-to-chassis ohmic isolation unavailable in ac-powered DSOs—although, in one instance (Leader), the isolation applies not to the scope but to the DMM that resides in the same enclosure. The two larger units (Hewlett-Packard (HP) and Gould) are full-featured designs that make few compromises. One of these, the HP unit, is a general-purpose DSO teamed with a package that contains a sealed lead-acid battery and an inverter.

The smallest units (Fluke, Leader) have LCDs that display both numeric information and waveforms (see **box**, "Some notable features"). The Fluke 97's LCD offers electroluminescent backlighting. (Fluke's lower-priced 95 and 93 and Leader's 300 lack backlighting; you can use their displays only where there is adequate ambient light.) The

other scopes use CRTs. The Tektronix units' CRTs are small but quite readable; the HP's screen is standard scope size (7 in. diagonal); the Gould's screen size falls in between the other two.

To digitize repetitive waveforms at very high effective rates (2 to 10 GHz), all of the DSOs, except the Leader 300, use random equivalent-time sampling, which lets you view pretrigger information. The Leader unit uses sequential equivalent-time sampling to multiply its acquisition rate by 5 to 10 $\times$  at the highest sweep speeds. To take full advan-



**Drawing some of its design concepts from handheld DMMs, Fluke's 97, which is about 3 $\times$  the size of such meters, provides 50-MHz bandwidth, a 2.5-Gsample/sec equivalent acquisition rate for repetitive signals, and a long list of features, including a built-in sine/square-wave generator.**

## BATTERY-POWERED DSOs

**Table 1—Representative battery-powered DSOs**

Vendor and model	Fluke 97 <sup>3</sup>	Gould 465	HP 54600A/601A scopes; 85901A inverter	Leader 300	Tektronix 222A, 224, 222PS
<b>Base US list price</b>	\$1795	\$4485	Scopes: \$2495, \$2895; Inverter: \$1290	\$1995	\$2450, \$2750, \$2750
<b>Size—H × W × D (in.)</b>	10.8 × 5.5 × 2.5	7.6 × 10.7 × 15.7	6.8 × 12.7 × 12.5; 4.9 × 13.3 × 18.1	6.5 × 9.4 × 1.8	3.4 × 6.3 × 9.9
<b>Weight (lbs)</b>	4	14	Scopes: 14; Inverter: 31.3	2.6 <sup>8</sup>	4.4
<b>Battery type; size</b>	4 NiCd; C <sup>4</sup>	NiCd	Sealed lead-acid 2 minimum, 2.5 typical	4 Alkaline; AA 2.25	Sealed lead-acid 3 minimum; 4 typical
<b>Operating time (hours)</b>	4	2	Flashing LED and buzzer	Display	Warning on CRT
<b>Low-battery indication</b>	Symbol flashes	None	10 minutes	10 minutes	2 to 3 minutes
<b>Warning before shutdown</b>	1 hour	NA <sup>7</sup>	3 hours typical, 6 hours maximum	See "Battery" box	3 hours
<b>Fastest recharge time</b>	10 hours	2x discharge time	Battery recharges within inverter	No	Yes
<b>Charge within scope?</b>	Yes	Yes, ONLY in scope	Can use scope by disconnecting inverter	NA	Yes
<b>Use while charging?</b>	Yes	Yes	NA	NA	Yes
<b>Charge time (scope on)</b>	18.5 hours	2x discharge time	NA	NA	About 6 hours
<b>Supply needed for ac?</b>	Yes	No	No; without inverter, scopes run on ac	Yes	Yes
<b>Supply price</b>	Included	NA	NA	\$39	Included
<b>External charger price</b>	NS <sup>5</sup>	NA	Included in inverter	See box in story	\$200 See "Battery" box
<b>Battery price</b>	\$40	\$250 (repair)	\$72.50	Depends on type	\$70
<b>Channels, max traces<sup>1</sup></b>	2, 4	2, 2	54600A: 2, 4; 54601A: 4, 4	2, 4	2, 2
<b>Bandwidth (MHz)</b>	50	100	100	10	222A, 222PS: 10; 224: 60
<b>Max samples/sec/channel</b>	See note 6	200M	20M	30M—1 shared ADC	10M
<b>Samples/trace (stored)</b>	512	512	4000	180; 1800 switchable	512
<b>Bits/sample</b>	12	8	8	7	8
<b>Equivalent-time mode</b>	Random	Random	Random	Sequential	Random
<b>Effective samples/sec</b>	2.5G	2G	10G (100-psec resolution)	150M	1G
<b>Captured-glitch width</b>	40 nsec	See note 8	50 nsec at all sweep speeds	No glitch capture	100 nsec at slowest sweep
<b>Time/div (min, max)</b>	10 nsec, 60 sec	25 nsec, 50 sec	2 nsec, 5 sec	0.1 usec, 200 sec	5 nsec (magnified), 200 sec
<b>Volts/div (min, max)</b>	1m, 1k (probe)	2m, 5	2m, 5 (50 with probe)	5m, 20 (2-kV probe)	222A: 5m, 50; Others: 50m, 200
<b>Display type</b>	EL back-lit LCD	CRT	CRT	LCD	CRT with stroke vectors
<b>Display size</b>	84 × 84 mm	NS	7 in. diagonal	60 × 113 mm	NS
<b>Display resolution</b>	240 × 240 pixels	NA	255 × 500 points	128 × 180 pixels	NA
<b>Isolation voltage<sup>2</sup></b>	600V rms; 4 kV peak	Not isolated	Floating ground NOT recommended	See note 10	222 PS: 600V rms; Others: 400V peak
<b>Hard-copy provisions</b>	Isolated RS-232C	Integral plotter	RS-232C, IEEE-488, parallel modules	Accessory printer	Yes, see note 11
<b>Affects isolation?</b>	No	NA	NA	No	No
<b>Extended data storage</b>	Months	About 1 month	With optional module; duration NS	1 month	Several months
<b>Retains panel setups?</b>	Yes, 10	No	Yes, 16	No (has autoseup)	Yes, 4

**Notes:**

- The first figure is the number of signals the unit can acquire and simultaneously display. The second figure is the largest number of traces displayed at one time. Some units can display signals acquired and stored earlier, in addition to those being acquired.
- The highest common-mode voltage you can safely apply between the scope's chassis and its Y-axis input terminals.
- The 90 series also includes the 93 and 95, which offer fewer features at lower prices.
- Unit can also run from nonrechargeable Alkaline cells.
- NS = Not specified.
- Because of the need to sample a signal several times per cycle to reconstruct it with reasonable accuracy, the usable bandwidth for single-shot events is approximately 6 MHz.
- NA = Not applicable.
- 1 μsec at 100-μsec/div sweep speed.
- Weight shown is without batteries.
- Withstands 1.1 kV between either DMM input and scope ground and also between DMM voltage and common inputs. Withstands 250V between DMM ohms and common inputs. DMM mA input is fused. Scope Y-axis inputs withstand 400V to ground without a probe and 600V with a probe. Trigger inputs withstand 100V to ground. All withstanding voltages are dc + p-p ac for 1 minute.
- The \$295 WP200 provides a parallel interface to Epson FX-compatible printers. The \$395 CAT200 allows an MS-DOS PC to control the scope. With this package, you can obtain waveform printouts on a graphics-capable printer connected to the PC.

tage of any of these scopes' vertical bandwidth, you must use their equivalent-time modes.

The Gould 465 has a real-time sampling rate of 200 Msample/sec—high enough, in theory, to let you view single-shot events whose frequencies extend over its full 100-MHz bandwidth. However, you're well advised to limit your viewing of single-shot signals to those whose frequencies don't exceed 50 MHz. Observing this precaution will provide 4 samples/cycle, the minimum most scopes need to reconstruct waveforms well enough for you to make sense of what you see. (Although 4 samples/cycle is a usable rate, several scope vendors recommend rates of at least 10 samples/cycle. Using that figure, you should limit the bandwidth of single-shot events you view with the Gould 465 to 20 MHz.)

Similarly, the Leader 300's maximum 30-Msample/sec rate (when digitizing one channel) is theoretically adequate to capture signals having components at 10 MHz (the full bandwidth). But at 3 samples/cycle, signal reconstruction would not be adequate, so the scope switches to the sequential equivalent-time mode at sweep speeds that let you observe the details of 10-MHz signals.

These units represent some of the best examples of how today's DSOs exhibit both higher performance and lower prices than were obtainable in instruments introduced only a few years ago. Still, these scopes are somewhat more expensive than analog scopes whose key electrical specifications are similar. Therefore, you have good reason to ask why you shouldn't choose a less-expensive battery-powered analog scope in place of a battery-powered DSO.

In the case of the Fluke/Philips and Leader units, no analog scopes offer equivalent performance and features in similar packages (see



**Although it resembles a pint-size version of a conventional scope, the Tektronix 224 is not conventional. It offers 60-MHz bandwidth, and its two inputs are ohmically isolated—not just from the chassis but from each other.**

box, "Some notable features"). Moreover, the Tektronix scopes, in addition to their small size and high performance, offer inputs that are ohmically isolated not just from the chassis but from each other. Not only is such isolation unique among the scopes in **Table 1**, if it is available at all in analog scopes, it isn't easy to find.

Isolation is particularly important when you work with high voltages. When you connect a source of high common-mode voltage to an isolated scope input, you can touch the instrument's controls without fear of receiving a shock, provided the voltage doesn't exceed the scope's breakdown rating. The only currents that flow across the isolation barrier are small leakage currents, due mostly to the barrier's nonzero isolation capacitance.

With nonisolated inputs, including differential ones, the usual way to measure signals at high common-mode voltages is to disconnect the scope's chassis from ground (for example by connecting the scope to the ac line with a "cheater" 3-prong to 2-prong adapter). With such a connection, you risk a possibly le-

thal shock if you touch any of the scope's metal parts. Obviously, scope manufacturers don't sanction such operation.

In some applications that require isolation, the classic reasons for choosing a DSO rather than an analog scope are particularly important. When displaying phenomena that occur infrequently, most analog scopes present dim, flickering images; observing these dim traces at best requires a viewing hood. Sometimes, the only way to see such displays is by photographing them with very fast film. Low repetition-rate signals are common in power-supply and motor-control work where high voltages often necessitate isolation. Among analog scopes, only storage scopes provide bright displays of low repetition-rate phenomena. But most storage scopes are large and costly, and few operate from batteries or offer isolation.

#### Isolation and battery power

One reason that isolation and battery power seem to go together is that, although you can certainly design a power supply with no resis-

**BATTERY-POWERED DSOs**

tive path to its output from the ac line, designing a supply with line-to-output capacitance (isolation capacitance) of only a few pF is a challenging task that usually increases its cost. By eliminating the line connection, battery operation lowers isolation capacitance and allows higher common-mode voltages than economical ac-powered instruments

can withstand. Stated another way, even if your battery-powered scope works when connected to ac, when you take advantage of its isolation capability, you'll get the best results if you run it from its batteries.

If you don't need isolation but need portability and want to save captured waveforms indefinitely—say, on a floppy disk—the idea of

plugging an ISA-bus DSO card into a laptop PC, thus turning the PC into a battery-powered DSO, seems an obvious solution. As far as EDN could find out, though, no such configuration operates completely from batteries. We know that notebook PCs (which are even smaller than laptops) are out of the question; they lack bus slots. On the other

**Some notable features**

**Fluke 97**—Simultaneously acts as DMM (3000 counts full-scale) and scope through same leads. Adds, subtracts, multiplies, inverts, filters, and integrates waveforms. Also functions as sine/square-wave generator.

Numeric display capabilities: Voltage differences; time differences; frequency; maximum, minimum, p-p, rms, rms + dc, and mean voltage; phase; rise time; fall time; time from trigger to cursor; ratio; dBm; dBV; dBW; resistance.

**Gould 465**—Any two traces can be added, subtracted, or multiplied. In persistence mode, simultaneously displays all acquisitions over a period of time. Auto-setup mode evaluates inputs, chooses appropriate ranges, and displays settings on screen. A plotter option (\$600 if purchased with the scope; \$695 if you add it after purchase—you can install it yourself) provides hard-copy output capability within scope. The identical scope, without battery power, costs \$3490. You can later add battery power for \$1275.

Numeric display capabilities: Cursor measurements of rise time, frequency, duty cycle, overshoot, p-p voltage, period, pulse width, area, and rms voltage.

**Hewlett-Packard 54600A/601A, 85901A**—Fast (250 X per sec) updates and familiar control layout produce a DSO with "analog feel" but, when displaying low repetition-rate signals, without the faint, flickering traces of analog scopes. Autostore mode displays the average of many waveforms at full brightness and the envelope of all measurements at half brightness. Optional modules allow expanding the scopes' capabilities, for example to add an RS-232C, parallel, or IEEE-488 interface; long-term waveform storage; or limit-testing.

Numeric display capabilities: Automatic and cursor-based measurements of average, rms, peak, p-p, and minimum voltage; frequency; period; duty cycle; rise time; fall time; time a signal is positive; and time a signal is negative.

**Leader 300**—Incorporates 3200-count DMM whose input is separate from the scope channels, making it, in a sense, a 3-channel unit. With optional logic probe, functions as 8-channel 15-MHz logic-timing analyzer. Logic-analyzer memory depth is 180 words when sweep speed is 5  $\mu$ sec/div or faster and 1.8k words at slower sweep speeds. Optional credit-card size battery-backed memory card stores 80 normal-length (180-word) DSO traces, eight 1.8k-word traces, 10 screens of 8-channel  $\times$  180-word (or one screen of 8-channel  $\times$  1.8k-word) logic-analyzer data. Uses sequential equivalent-time sampling to achieve a 5 to 10X improvement in sampling rate at the highest sweep speeds. Also offers a "strip-chart" or "roll" mode for low-speed signals.

Numeric display capabilities: Range and mode information appears continuously at left side of screen and on screen printouts produced by accessory printer.

**Tektronix 222A, 224, 222PS**—The 222PS has a motor-control trigger feature that provides a stable display of variable-frequency waveforms that normally cause triggering problems. Because of the stroke-vector display and  $\frac{1}{30}$ -sec update speed, the display resembles that of an analog scope. Channels are separately isolated from chassis and have separate ADCs. (Some competitive scopes provide isolation between the chassis and all inputs as a group. Such scopes tolerate only limited common-mode voltages between their inputs and the floating ground.) The 220-series scopes are listed by Underwriters' Laboratories (UL) and Canadian Standards Association (CSA). The 222PS withstands 6-kV common-mode transients.

Numeric display capabilities: These scopes do not provide numeric displays of measured quantities. They do display range settings on their CRTs.

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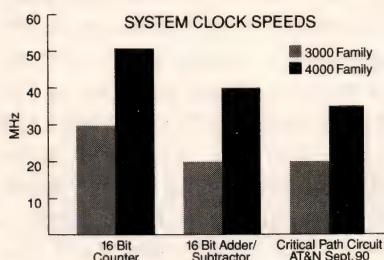
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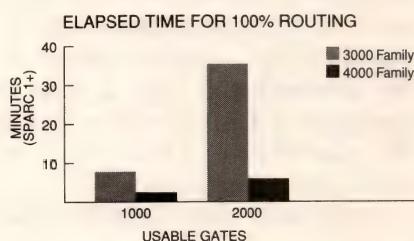
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**BATTERY-POWERED DSOs**

hand, some laptops do have slots (usually a single slot). We inquired of two vendors of PC-based scope hardware—Rapid Systems (Seattle, WA) and Gage Applied Sciences (Montreal, PQ, Canada)—to see if they knew of a laptop PC and a scope card or scope accessory that would work together under battery power.

The few laptops that have slots seem not to have the full-length slots needed to accommodate DSO cards. Moreover, the bus connectors of some of these laptops don't deliver the normal supply voltages that DSO cards need. The laptops that allow you to use a full-length ISA-bus board require you to bolt an accessory unit to their lower surfaces. Such combinations are still quite small and light and provide large high-resolution screens. Unfortunately, although the PCs operate from internal batteries, the accessory units' supplies require ac. So, although you may be able to configure a DSO around a laptop PC, your PC-based scope won't operate without ac power.

If you could construct a PC-based



**A different approach to battery-powered DSOs is embodied in Gould's 465. You can purchase this small scope with or without the battery pack. The vendor intends the scope primarily for operation where ac is available, but with the batteries, it will run for two hours or more away from the power line.**

battery-powered digital scope, with appropriate software, its disk drives would provide a feature not available in any of Table 1's DSOs: *truly* nonvolatile waveform storage. Although none of the scopes has a disk drive, most of the units offer fairly long-term storage, even when you have drained their batteries so much that you need fresh batteries or an ac source to continue scope operation. (See the row "Extended

data storage" in Table 1.) In some cases though, if you retain a critical waveform, you limit the scope's ability to acquire additional signals.

Of the listed scopes, only the Leader 300 can transfer waveforms to a credit-card-size, battery-backed RAM card. Such cards store data for years. Although RAM cards sometimes can function as media for exchanging data with other units—for example, suitably equipped PCs—you shouldn't assume that all such cards are interchangeable. Leader's Joe Fisher says that the main purpose of the 300's RAM cards is to extend the scope's storage. Your PC most likely will not be able to read waveforms from the 300's RAM cards.

With the other scopes, if you want to save a waveform indefinitely, you must transfer it elsewhere, say to a desktop PC's hard disk. Several of the scopes provide ports through which you can transfer the data. In some cases, you have a choice of the type of port—RS-232C, parallel, or IEEE-488. The Fluke and Tektronix scopes allow you to use the serial port without affecting the scope's input-to-output isolation.

However, using an RS-232C port to save a waveform is not an ideal

**For more information . . .**

For more information on the battery-powered DSOs discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you read about their products in EDN.

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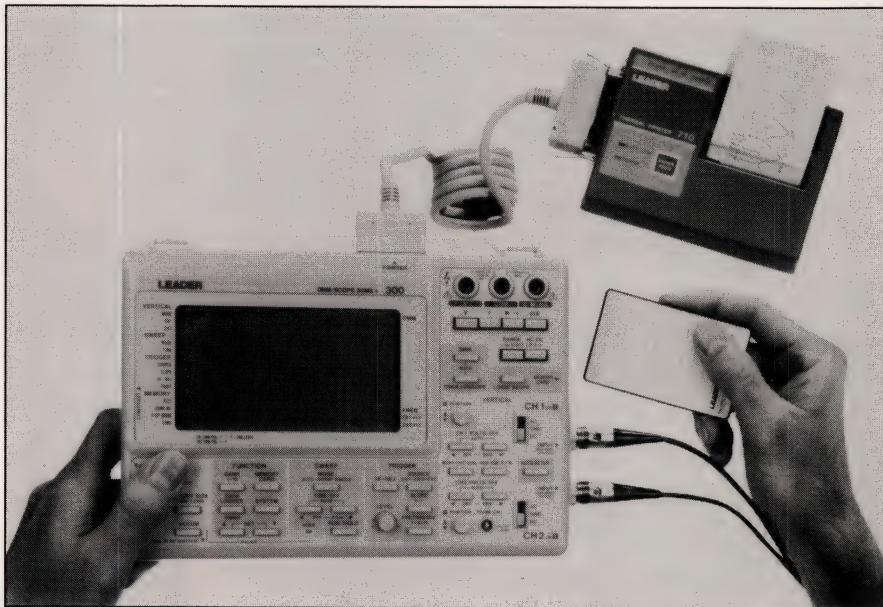


Component Solutions For Your Power System

## BATTERY-POWERED DSOs

solution. Usually, this approach requires you to be near the computer to which you will transfer the data. Connecting a small modem to the scope's serial port might save the day when the computer is some distance away, but remember, the scope is not a PC. The scope won't run your favorite telecommunications software package. On the PC, a package designed to download waveforms from your scope may not work with a modem.

If you can't save waveforms as files on a disk, perhaps the best alternative is printing them out. Your computer may not be able to read the printouts, but you will be able to, and the printouts will last a while. Mostly, if you want a printout, you must rely on communicating via a serial, parallel, or IEEE-488 port. The Leader 300 offers a



Extended data storage in credit-card-size, battery-backed RAM cards and the ability to print out waveforms on a dedicated accessory printer are just two of the Leader 300's features. The unit also includes a 3000-count DMM and, with an accessory probe, converts to an 8-channel logic-timing analyzer.

## A battery of batteries for battery-powered DSOs

Among manufacturers of battery-powered equipment, there is no unanimity on which battery chemistry system is "the best." The reason, not surprisingly, is that "best" means different things to different people. Even when the products perform similar functions and are used by people in similar jobs under similar conditions, product designers can have radically different views of the relative importance of various aspects of performance and cost. As a result, the scopes in **Table 1** use NiCd, Nickel-metal-hydride, and sealed lead-acid rechargeable batteries as well as nonrechargeable Alkaline cells. (Technically, a battery consists of several cells. Despite what people commonly call them, most cylindrical "batteries"—for example, the C and AA sizes—really are individual cells. On the other hand, a 9V "transistor-radio" battery really is a battery because it contains several cells.)

The designers of Fluke's 90 series had flexibility in mind. They chose C-size NiCd cells as the units' usual power source, but designed the scopes (or "Scopemeters," as Fluke calls them) to work from C-size Alkaline cells too. That way, if you don't spend the money for an extra set of NiCds and you exceed the four hours of operation you can expect from the rechargeable cells, you can remove the NiCds and substitute a set

of Alkaline cells. C-size Alkaline cells are quite inexpensive and are available in supermarkets and variety stores. Moreover, Alkaline cells have a shelf life measured in years and will run the Scopemeters longer than the NiCd cells will—perhaps twice as long.

Fluke has not yet stated that you can substitute Nickel-metal-hydride cells for the NiCds. Nickel-metal-hydride cells are only just now starting to appear commercially. They are still quite expensive, but in applications that draw moderate discharge currents (and that includes the majority of battery-powered electronic equipment), they will usually run the equipment for a period significantly longer than NiCd cells will (that is, for nearly as long as Alkaline cells will run it). On the other hand, Nickel-metal-hydride cells discharge themselves more rapidly than NiCd cells do, and NiCds exhibit faster self-discharge than Alkaline cells. In other words, if you use rechargeable batteries, to maximize their operating time, you should, if possible, keep them "float charged" (so they don't self discharge) until just before you use them.

The designers of Leader's 300 did not give top priority to using rechargeable batteries. They built the scope to run first of all from Alkaline cells (AA size), but you can substitute NiCd or Nickel-metal-hydride cells for

separate accessory printer designed for use with the scope. Its printouts show the measurement ranges in use. The larger Gould 465 provides the most convenient solution: It accommodates a color plotter, and installing the plotter doesn't increase the scope's size. You can order the scope with the plotter or easily add the plotter yourself after purchase.

### No time left

If you are in the middle of taking important data when your scope's batteries are about to run down, you'd probably like some warning and maybe you'd like to replace the batteries with a freshly charged set. Most of the units provide a low-battery indication on their displays. Usually, the warning occurs when enough operating time remains for you to print out the contents of the

waveform memories—if a printer is handy.

Some of the scopes use separate batteries to retain data after shutdown, so you can replace the main batteries and resume operating pretty much as if there had been no power interruption. In some cases, if you don't have more rechargeable batteries ready, you can substitute nonrechargeable ones. (See **box**, "A battery of batteries for battery-powered DSOs.")

Stacked up against larger and more expensive DSOs, these units set no performance records, but the availability of very respectable performance in small, rugged, relatively inexpensive packages is definitely noteworthy. When you consider that these instruments operate without ac power (and in some cases, provide isolated inputs)

and that some of them offer useful features rarely found in scopes (full-featured DMMs in the Fluke and Leader units, a logic-timing analyzer in the Leader 300, a sine/square-wave generator in the Fluke 97), you're justified in calling them quite remarkable.

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the Alkaline cells. Unlike the Fluke units, which let you recharge the NiCd cells inside the scope, with the Leader unit you must remove the cells to recharge them. Although having to use an external charger may seem like a disadvantage, it does let you match the charger to the type of cells you are using. In the case of Leader, though, this flexibility means that the scope vendor doesn't supply chargers, nor did it indicate charger prices. Leader did emphasize, however, that chargers are readily available and multiply sourced. Because charging times depend on both the batteries and the charger, Leader did not provide information on charging times.

Obviously, external chargers vary in price. The \$200 price of the charger for the Tektronix 220 series scopes includes—besides a charger that can charge two batteries at once—a spare battery, a viewing hood, an extra ac adapter, and an automobile cigarette-lighter adapter.

### A battery of battery prices, too

The price of the batteries varies from \$40 to \$250, although the cost of nonrechargeable batteries—if your scope can use them—is considerably less. The Gould 465's battery is a special case. Its \$250 price

includes the factory's labor. The battery, which is sealed within a unit that includes the charger, is not replaceable in the field. You must return the entire unit, and perhaps the scope, to the factory for a replacement. Gould says that an EE with a soldering iron and a screwdriver should have no trouble installing the battery unit on a scope not originally equipped with it. The unit, which attaches to the bottom of the scope case, is no harder to remove than to install. Hence if the battery fails, you probably won't have to go without the scope while the factory replaces the battery.

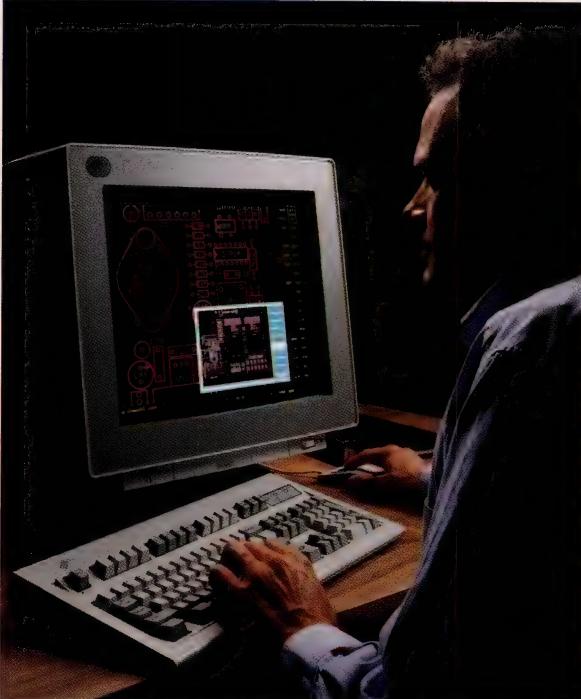
All of the scopes operate from ac as well as from batteries. In some cases, ac operation requires an external unit, such as a transformer that plugs into a wall outlet. In **Table 1**, the row "Supply needed for ac?" tells whether an external unit is needed. The next row, "Supply price" shows the cost of the supply.

The row marked "fastest recharge time" presents the times required to recharge the units' batteries to full charge from a state of discharge that causes the unit to shut down. These times apply with the scope not in use. With the scope in use, recharging times under otherwise similar conditions are generally longer and appear on the row labeled "Charging time (scope on)."

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# Coupling DRAM and bus technology yields 500-MHz burst transfers

The dynamic RAM (DRAM) bottleneck in high-performance computer systems may become a thing of the past if Rambus Inc's RAMbus interface and DRAM design gains acceptance. The interface uses a 9-bit synchronous-data link between processor and DRAM memory, achieving burst data-transfer rates as great as 500 Mbytes/sec.

Physically, the interface is straightforward. It has 28 wires, of which 15 are active, 8 are ground, and 5 are power. The 15 active lines include 9 data bits, bus control and enable signals, 250-MHz transmit and receive clocks, and a voltage reference. Data transfers occur at both edges of the clock signals.

Data transfer along the interface begins with the generation of a request packet by the CPU or bus master. The packet is 6 characters long and contains a transaction code, a 36-bit memory address, and an 8-bit block length. The bus-control line serves as a start bit, signaling the other devices on the bus that a request has begun.

All memory devices on the bus monitor the bus control and data lines, but respond only if the request falls within their address space. The addressed device must respond within 36 nsec either with an acknowledge code, indicating that it can handle the request, or with a negative-acknowledge code, if it cannot handle the request. If the response is negative, the bus master will re-issue the request until it receives an acknowledge.

The timing differs for read and write data transfers. When reading, the bus master will begin receiving data 36 nsec after the request packet ends. When writing, the bus master can begin supplying data 4

nsec after the request packet ends. During a write transfer, therefore, the memory's response arrives after data transfer has begun. If the response is negative, the bus master simply aborts the transfer and reissues the request.

To be able to transfer data on both edges of the 250-MHz clocks, the interface must have carefully controlled electrical characteristics. The interface uses a variety of techniques so that you don't have to work too hard to use RAMbus-based devices.

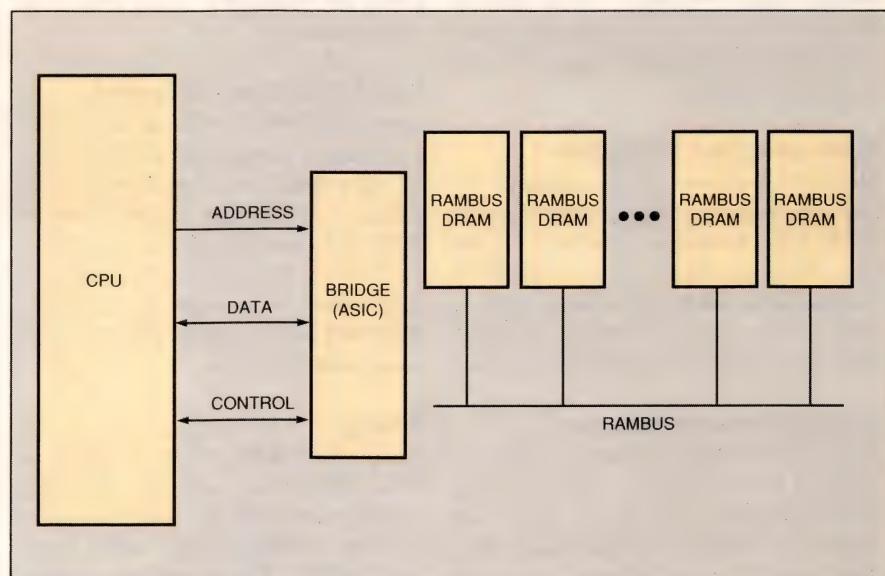
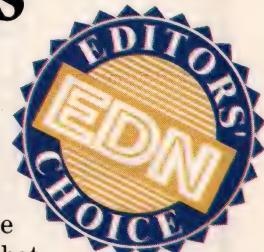
To begin with, the interface's mechanical details are completely defined, including specifications for circuit-board trace widths and lengths and component layout. The interface's capacity is limited to 32 memory devices. RAMbus-based devices must connect in a straight line, with the bus master at one end of the circuit.

To minimize clock-to-data skew,

the 250-MHz receive clock enters the circuit at the end away from the bus master so that it propagates toward the bus master alongside the data that it clocks. The transmit clock is simply the receive clock looped back at the bus master, so that the master's data and the transmit clock propagate together to the memory devices.

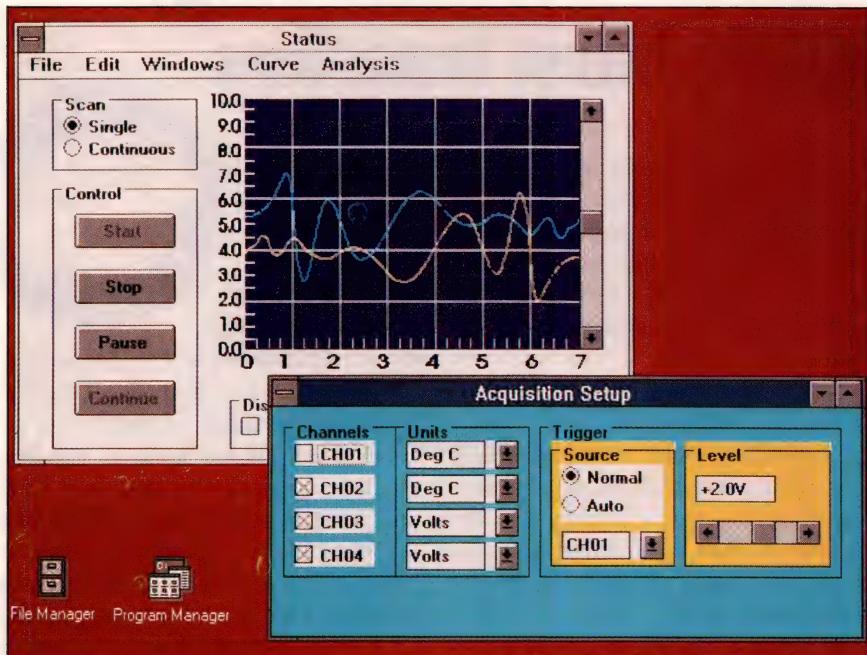
To achieve the 500-MHz data clocking rate with currently available DRAM technology, the interface's output signal swing is restricted. Signals on the interface swing  $\pm 300$  mV about a nominal 2V reference voltage. That reference voltage is included in the interface's 15 active signals so that all devices on the bus work from the same standard.

A memory subsystem built on the RAMbus interface possesses a num-



**By utilizing small signal swings and by having the clocks and data signals propagate together, the RAMbus interface achieves burst transfer rates of 500 MHz. The RAMbus DRAMs use their sense amplifiers to provide two 1k  $\times$  9-bit internal caches.**

# New IEEE 488.2 Control for Microsoft Windows



**IOtech's Personal488/WIN includes a DLL driver with C and Visual Basic support**

**IOtech's new Personal488/WIN** includes a DLL (dynamic link library) that enables IEEE 488.2 control from Microsoft Windows applications. Personal488/WIN includes either IOtech's 8- or 16-bit IEEE 488.2 interface boards for PC, AT, and EISA bus computers. It features easy-to-use HP style commands for IEEE 488 control and is compatible with an array of Windows development languages, from Visual Basic to Microsoft C, QuickC, Turbo C, and Borland C++.

#### Multitasking Bus Arbitration

Microsoft Windows allows multiple test applications to concurrently access the same IEEE 488 instrument network. Unlike other Windows drivers, Personal488/WIN automatically arbitrates among applications, letting users run multiple applications concurrently without fear of data loss.

#### SRQ and Error Handling in C

Personal488/WIN conforms to Windows standard event-handling system, passing IEEE 488 events such as bus errors and instrument interrupts to Windows as standard messages, thus ensuring consistent handling of IEEE 488 and user-interface events.

#### Interactive C Code Generation

Personal488/WIN includes a Windows application for interactive IEEE 488 instrument control and C code generation. Users can employ this application's menus and dialog boxes to select, configure, and execute IEEE 488 applications interactively, and then directly paste the generated code into their source code.

#### Visual Basic Custom Control

Personal488/WIN adds an IEEE 488 event tool to VisualBasic's GUI (graphical user interface) development tool palette. Use of this tool to insert an IEEE 488 event object into an application allows Visual Basic to automatically create procedures for servicing IEEE 488 events such as bus errors and instrument interrupts.

#### Pricing

Personal488/WIN, which includes an 8-bit IEEE 488.2 interface, is \$395; Personal488AT/WIN, which includes a 16-bit, 1 Mbyte/s IEEE 488.2 interface, is \$495. **For more information, call IOtech at (216) 439-4091 or fax your request to (216) 439-4093.**

ber of unique characteristics. For one, the DRAMs have the same pinout and behavior regardless of their size, so you don't need to change your circuit board in order to upgrade to higher-density devices as they become available.

Another characteristic of the subsystem is the caching nature of the RAMbus DRAMs. When accessed, the RAMbus DRAM uses part of the address to activate one 1-kword row of its internal array and caches the data in its sense amplifiers. You can cache two rows simultaneously. The remainder of the address selects which words get transferred over the serial data link. The first access to a row takes between 160 and 210 nsec. If the new access uses the same row, a read hit, the RAMbus DRAM can begin sending data within 36 nsec of the request.

When not being accessed, the RAMbus DRAM retains its cached data. A memory subsystem composed of several devices, then, has multiple independent caches active. The larger your memory array becomes, the more cache lines you have active and the greater the chance for a read hit.

The company does not produce ICs itself. Instead, it licenses its technology and provides design support to semiconductor vendors and ASIC foundries. The company already has several licensees, including Fujitsu, Toshiba, and NEC. Initial products from these companies, to be released this year, will include 512k × 9-bit RAMbus DRAMs and an ASIC that connects the RAMbus to a conventional μP.—**Richard A Quinnell**

*Rambus Inc, 2465 Latham St, Mountain View, CA 94040. Phone (415) 903-3800. FAX (415) 965-1528.*

**Circle No. 730**

# 160MHz VIDEO MUX/AMPS PIXEL SWITCH IN 15ns

**Drive 75Ω Coax, 0.03°/0.04% Diff. Phase/Gain**

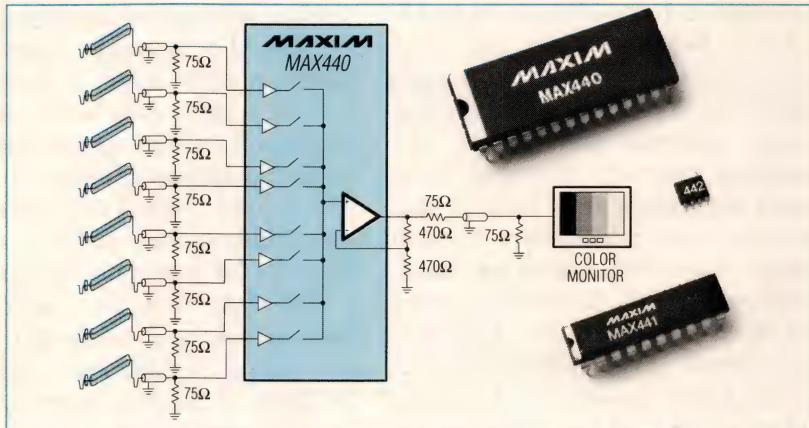
Maxim's new MAX440/MAX441/MAX442 combine a 160MHz, unity gain stable video amplifier plus a 2-, 4-, or 8-channel multiplexer in a single DIP or SO. Pin-selectable frequency compensation allows the amplifier's AC response to be optimized without external components and output-disable allows multiple MAX440s to be paralleled for larger switch matrices. These new mux/amps provide lowest cost broadcast quality and 15ns pixel switching from ±5V supplies.

## SPEED

- ◆ 160MHz Unity-Gain Bandwidth
- ◆ 110MHz Bandwidth ( $A_v = 6\text{dB}$ )
- ◆ 370V/ $\mu\text{s}$  Slew Rate
- ◆ 15ns Channel Switching Time

## PRECISION

- ◆ 4pF On-Channel Input Capacitance
- ◆ 0.025Ω Output Resistance
- ◆ 70dB Crosstalk At 10MHz



Single IC multiplexes 8/4/2 channels and drives 75Ω coax cable.

**Choose the Lowest Cost, Highest Performance ±5V Solutions**

Device	Feature	Bandwidth (MHz)	Slew Rate (V/ $\mu\text{s}$ )	Diff Phase (°)	Diff Gain (%)	Price*
<b>MAX440</b>	8-Ch Mux/Amp	160 110 (6dB)	250 370 (6dB)	0.03	0.04	\$ 8.95
<b>MAX441</b>	4-Ch Mux/Amp	160 110 (6dB)	250 370 (6dB)	0.03	0.04	\$ 5.90
<b>MAX442<sup>†</sup></b>	2-Ch Mux/Amp	160 110 (6dB)	250 370 (6dB)	0.03	0.04	\$ 4.70 <sup>†</sup>
<b>MAX404</b>	Video Amplifier	80	500	0.01	0.05	\$ 2.68
<b>MAX405</b>	Precision Buffer	180	650	0.01	0.03	\$ 4.25
<b>MAX456</b>	8x8 Crosspoint	35	250	1	0.50	\$19.98

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**8x8 Video Crosspoint Switch With Buffer And Pixel Switch**

**MAX440 MAX441 MAX442**

**MAX404 MAX405 MAX456**

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\*1000-up suggested resale, excluding freight and duty

† Available June, 1992

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# Modular unit combines functions of pulse and word generators

When selecting signal sources to stimulate digital systems or ICs—to verify system design or to perform production tests—EEs have had to choose between word and pulse generators. Word generators (data generators) provide wide data from many channels, each backed with pattern memory. However, most such generators allow little, if any, control over parameters such as edge placement, transition times, and pulse width. For precise control of signal characteristics, EEs have preferred pulse generators. But most pulse generators have few channels and, at best, offer limited pattern memory. Not only do Tektronix's HFS 9000-series modular Data Time Generators eliminate the need to choose, but they also cost less and are easier to use than a set of separate word and pulse generators.

A \$28,495 8-channel configuration of the Data Time Generator replaces a collection of word and pulse generators that cost three times as much and occupy many times the 7 in. of rack space used by the small Data Time Generator setup. According to the generator's manufacturer, this comparison doesn't involve choosing a particularly costly group of older instruments, and it doesn't reveal the dramatic reduction in setup time the new generators make possible (minutes vs days).

The user interface, based on a touch-sensitive monochrome CRT that displays timing diagrams and menus, is only part of the reason for the rapid setup. The major reason is a new architecture: The generators are not merely an amalgamation of classical word and pulse generators. Tektronix has replaced

nearly all of the analog functions of a pulse generator with the digital equivalents. Eliminating the analog circuits reduces interactions among controls. For example, there is no baseline shift when a pulse approaches 100% duty cycle. Among the benefits of the new architecture is the generator's ability to precisely and repeatedly simulate metastable states, which is a difficult feat for most pulse generators.

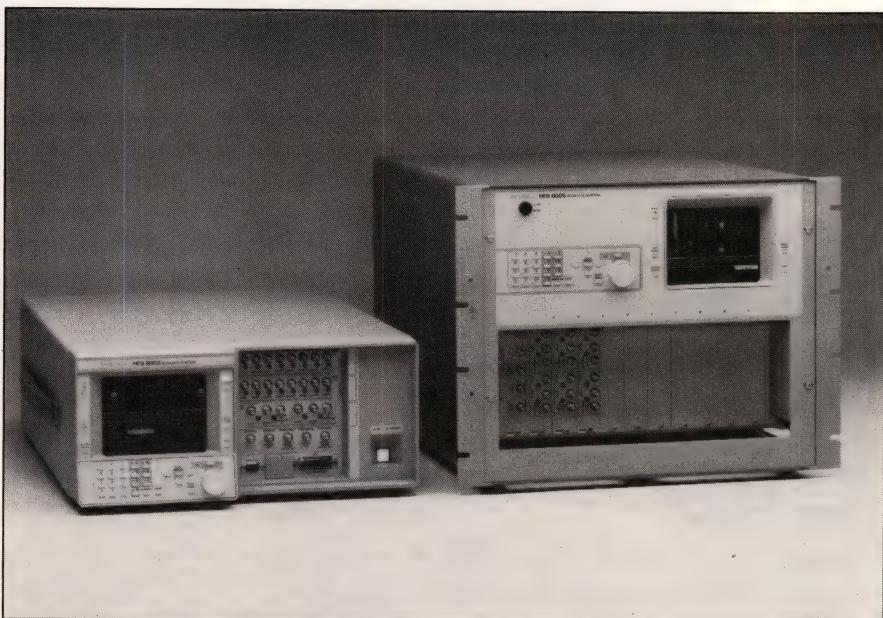
The Data Time Generators produce signals at rates to 630 Mbits/sec/channel. Behind each channel is 64 kbits of pattern memory. You specify the data format, for example NRZ (non-return-to-zero), on a per-channel basis. Similarly, you specify the placement of pulse edges within a clock period on a per-channel basis, and you can specify pulses wider than one clock period. The edge-position resolution, a minus-

cule 5 psec, allows precise de-skewing of the multiple-channel outputs without resorting to techniques such as precise matching of cables' electrical lengths.

The modular system includes two generator units. An \$11,000 4-channel plug-in offers fixed rise and fall times of less than 250 psec. A \$7900 4-channel plug-in provides transition times that you can vary from 800 psec to 6 nsec. Tektronix offers two mainframes: a 3-slot (12-channel) unit that costs \$12,695, and a 9-slot (36-channel) unit priced at \$19,995. By using several mainframes, you can put together larger configurations having 640 or more channels. Delivery is 8 to 12 weeks, ARO.—Dan Strassberg

Tektronix Inc., Box 1520, Pittsfield, MA 01202. Phone (800) 426-2200.

**Circle No. 733**



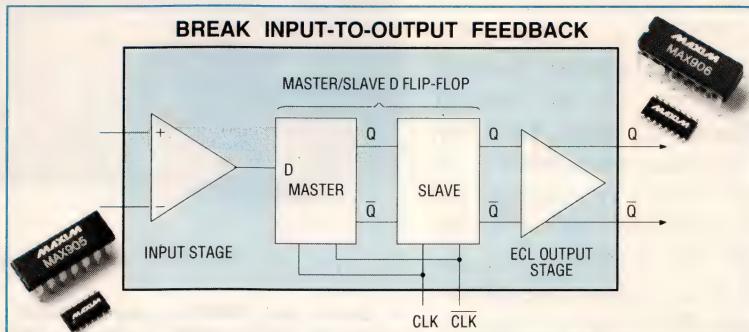
You can configure a combination word and pulse-generator from HFS 9000-series modules. Unlike systems built from classic word and pulse generators, which often provide full pulse-parameter control on only a few channels, these new instruments provide full parametric control—including 5-psec-resolution edge placement—on all channels.

# 2ns COMPARATORS RESOLVE 3mV SIGNALS WITH NO OSCILLATION

## Propagation Delay Independent of Overdrive

Maxim's new MAX905/MAX906 are the first ultra high-speed, precision, single and dual ECL comparators to eliminate oscillation caused by unwanted parasitic feedback. Unlike other ECL comparators, the master/slave architecture resolves input voltages as small as 3mV over its common-mode range, and propagation delay is independent of input overdrive. No dispersion!\* This eliminates synchronization problems common with industry standard comparators.

- ◆ Immune to Oscillation
- ◆ 2ns Propagation Delay
- ◆ Single or Dual Supply Operation
- ◆ 7.9V Input Voltage Range Includes Negative Rail



Master/slave D-flip/flop prevents oscillation and resolves signals as low as 3mV.

## Incomparable ECL Comparators For Your Application!

Device	Description	Comparators per Pkg.	Prop Delay (ns)	No Dispersion*	3mV Resolution	Input Range Includes Neg. Rail
MAX905	Edge-triggered master/slave architecture	1	2.0	✓	✓	✓
MAX906	Dual MAX905	2	2.0	✓	✓	✓
MAX9685	Higher-speed Industry Standard†	1	1.3			
MAX9687	Dual Higher-speed Industry Standard†	2	1.4			
MAX9690	Available in 8-pin DIP/SO	1	1.3			

\*Dispersion is the change in propagation delay from 3mV to 1V input overdrive.

†TTL also available.



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# \$20,980 DSO takes 2 Gsamples/sec on four channels simultaneously

With recent introductions from several vendors, digital storage oscilloscopes (DSOs) that sample transient phenomena in real time have gotten faster than ever. Now they have also become more affordable. Tektronix's TDS 640 has four channels, takes 2 Gsamples/sec/channel, and costs \$20,980 with four active probes. Although another recently announced scope, the HP 54720A (*EDN*, March 2, 1992, pg 114), takes 4 Gsamples/sec/channel, it does so only when you configure it with two channels. When configured with four channels—like the TDS 460—it also takes 2 Gsamples/sec/channel. With four probes, the HP unit's price exceeds \$50,000.

The TDS 640's display is high-resolution monochrome; the 54720A's is color. The 54720A has a plug-in architecture, a waveform memory exceeding 30 ksamples, and a built-in disk drive; the TDS 640 doesn't include a disk drive, stores 2 ksamples/channel, and comes in a fixed 4-channel configuration. (A 2-channel version, the TDS 620, costs \$13,540 with two probes.) Both the TDS 620 and TDS 640 have a 0.5-GHz bandwidth for transient and repetitive phenomena. They do not use techniques to enhance their effective sampling rate when they acquire high-speed repetitive waveforms; the HP scope does use such techniques, and its repetitive-signal bandwidth is 1.5 GHz.

Only you can decide whether, for your application, the difference in features justifies the 54720A's higher price. Of course, if you require single-shot bandwidth of "only" 250-MHz (with simultaneous 1 Gsample/sec real-time acquisition



A clever user interface and advanced triggering features characterize two new series within Tektronix's TDS family. The TDS 620 and 640 (left) take 2 Gsamples/sec in real time on each of two or four channels, respectively. The TDS 820 (right) is a 2-channel sequential-sampling digital scope with 6-GHz bandwidth and the ability to display pretrigger data (8-GHz bandwidth optional).

on four channels), you can find at least one other DSO at a price somewhat lower than that of the TDS 640. (Both the TDS 620 and 640 offer the option of deleting the active probes to reduce their prices by \$495 per channel in applications that don't require probes.)

Tektronix has also introduced the TDS 820, a 2-channel sequential-sampling digital scope that has 6-GHz repetitive-signal bandwidth (8 GHz optional) and 14-bit resolution. Sampling scopes, several of which offer bandwidths in the tens of gigahertz, have acquired a reputation as finicky beasts—ones you use only if you really need their exceptional bandwidth. The vendor's intent with the TDS 820 is to provide very high bandwidth and very high sensitivity (2 mV/div max; 1 mV/div in the 8-GHz version) in an attractively priced, easy-to-use scope. Like all members of the TDS series,

the 820 offers a menu-driven interface based on both words and icons and extremely flexible triggering.

A TDS 820 feature that is unusual in sequential-sampling scopes is a delay line (not available in the 8-GHz-bandwidth version) that lets you view pretrigger information. Most sequential-sampling scopes can't display pretrigger information. In scopes that offer equivalent-time sampling, pretrigger displays are normally found only in units that use random repetitive sampling, a technique that doesn't provide the bandwidth of sequential sampling.

The TDS 820's price is \$19,100; delivery is eight weeks ARO. Delivery for the TDS 620 and TDS 640 is six weeks ARO.—**Dan Strassberg**

*Tektronix Inc, Box 1520, Pittsfield, MA 01202. Phone (800) 426-2200.*

**Circle No. 731**

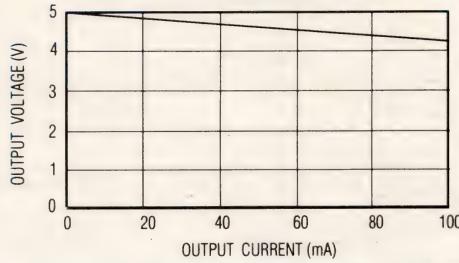
# NO INDUCTORS! +5V IN/-5V OUT INVERTER POWERS 100mA LOADS

## MAX660 Plus 2 Capacitors Deliver 95% Efficiency

Using two low-cost capacitors, Maxim's new MAX660 charge-pump voltage inverter converts a 1.5V to 5.5V input to a -1.5V to -5.5V output. The charge pump's 100mA output replaces switching regulators, eliminating the need for inductors and their associated cost, size and EMI. For instance, with a 5V input, the MAX660 delivers 100mA at -4.35V. Compact 8-pin DIP and SOIC\* packages coupled with a 95% power-conversion efficiency make the MAX660 ideal for battery-powered applications.

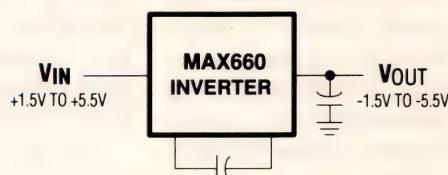
- ◆ Only 2 Capacitors, NO Inductors
- ◆ 10kHz and 45kHz Internal Oscillator
- ◆ Voltage Inverter Mode:  $V_{OUT} = -V_{IN}$
- ◆ Voltage Doubler Mode:  $V_{OUT} = 2 \times V_{IN}$
- ◆ 1.5V to 5.5V Input Voltage Range
- ◆ 200 $\mu$ A No-Load Supply Current
- ◆ Only \$2.95†

### 100mA LOAD CURRENT



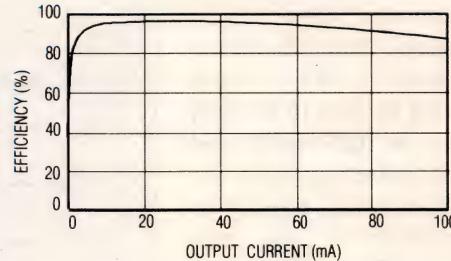
Maxim's new MAX660 voltage inverter powers 100mA loads.

### NO INDUCTORS



The MAX660 uses only 2 external components and is available in space-saving 8-pin DIP and SO packages.

### 95% EFFICIENCY



High efficiency makes the MAX660 ideal for portable applications.

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CIRCLE NO. 72

**M**A**X****I****M**

# Streaming-data protocol extends IEEE-488 standard to 5 Mbytes/sec

Over the past 15 years, the IEEE-488 communications protocol has become a true standard in instrumentation. Except for handheld, battery-powered units, a majority of modern instruments offer an IEEE-488 port—at least as an option. But the protocol has become a bit long in the tooth; it isn't very efficient for instruments that send or receive large blocks of data. Without obsoleting existing instruments, Capital Equipment Corp (CEC) has developed an extension to the standard, called 488SD, where SD stands for "streaming data." (Note that the IEEE has not yet made this extended protocol a standard.)

Hardware support for 488SD exists only in CEC's \$495 488EX IEEE-488 interface board and in a similar board from Keithley Metrabyte (Taunton, MA). These boards, designed for the 16-bit ISA bus, also work in half-length and 8-bit slots. CEC is betting that vendors of instruments that require or produce large blocks of data, such as arbitrary-waveform generators and digitizers, will want to speed up their products' operation by implementing this protocol.

The 488SD standard actually transcends IEEE-488. One of the goals of the VXIbus modular-instrumentation standard is to achieve much faster data transfer than is possible using IEEE-488. So far, though, most users of VXI have not been able to realize that goal. Using VXI's register-based and shared-memory protocols requires tackling software issues that few users have dealt with. The alternative—treating VXI as if it were IEEE-488, that is, using VXI's message-based (word-serial) proto-

col—is the approach most VXI users take. Because it's compatible with VXI, 488SD could enable VXI systems to achieve their speed potential without incurring major software hassles.

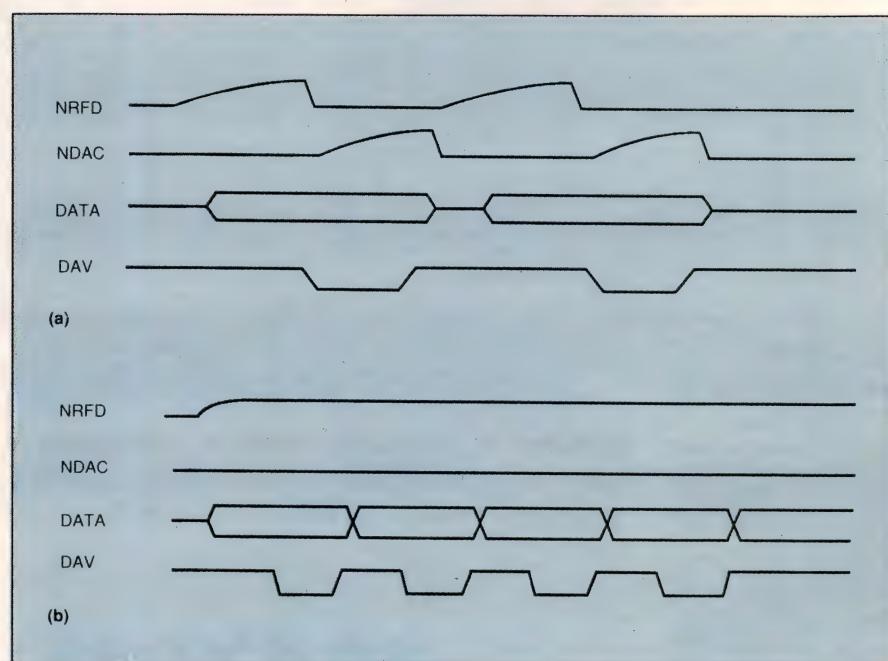
Moreover, the popular method of building systems that combine VXI and IEEE-488 instruments is to make a VXI mainframe an IEEE-488 device. In such mixed systems, the streaming protocol promises faster communication with cages full of VXI modules.

Equally important is the protocol's potential to head off "destandardization" in rack-and-stack instrumentation. Because of IEEE-488's throughput limitations, some vendors of instruments that require

high transfer rates offer alternative interfaces such as SCSI ports. Clearly, though, staying with a single interface for communication between computers and instruments contains system-hardware costs and simplifies software.

When an interface that supports the SD protocol tries to initiate a streaming interchange with an instrument that lacks SD support, an instrument that conforms to IEEE-488.2 will tell the interface that it doesn't support the transaction. This function even occurs with older instruments designed before this protocol existed.

You can expect that instruments offering 488SD support will continue to allow word-at-a-time trans-

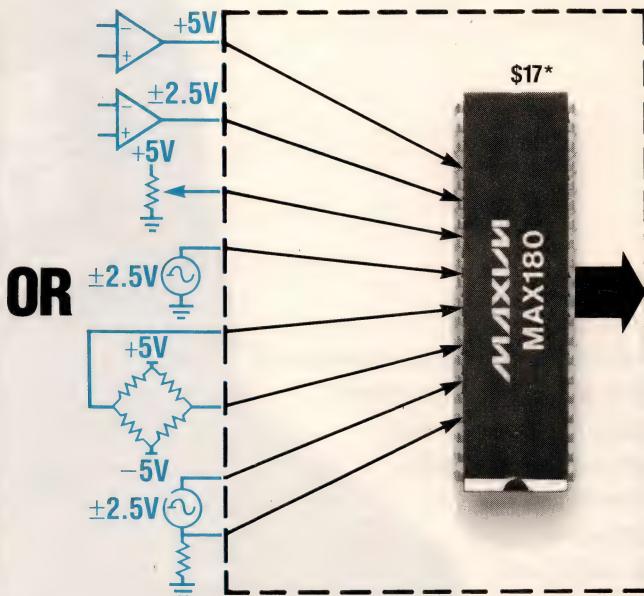
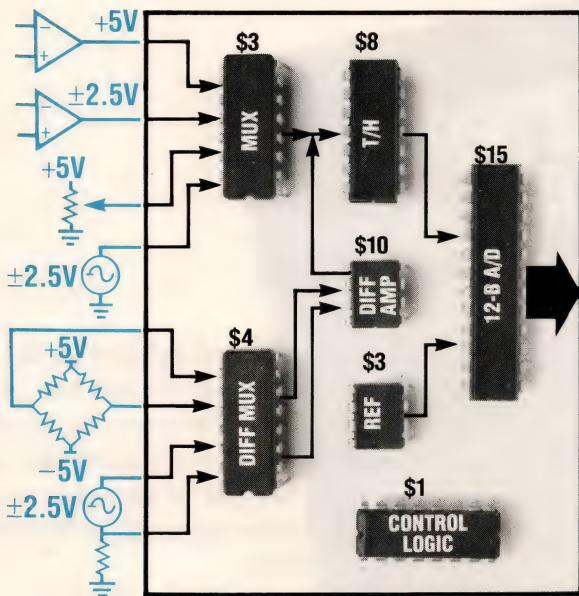


**Under the existing standard, (a), when a listener makes NRFD (not ready for data) false, a talker can send one byte. The listener then makes NDAC (not data accepted) false. Each time NRFD or NDAC becomes false, you must wait for the driver circuit to charge the bus capacitance. Under the streaming-data protocol, (b), after NRFD becomes false, a talker can send an unlimited number of bytes. In some circumstances, the result is a 5-fold speed increase over the best IEEE-488 data-transfer rates currently possible. (Note: DAV = data valid.)**

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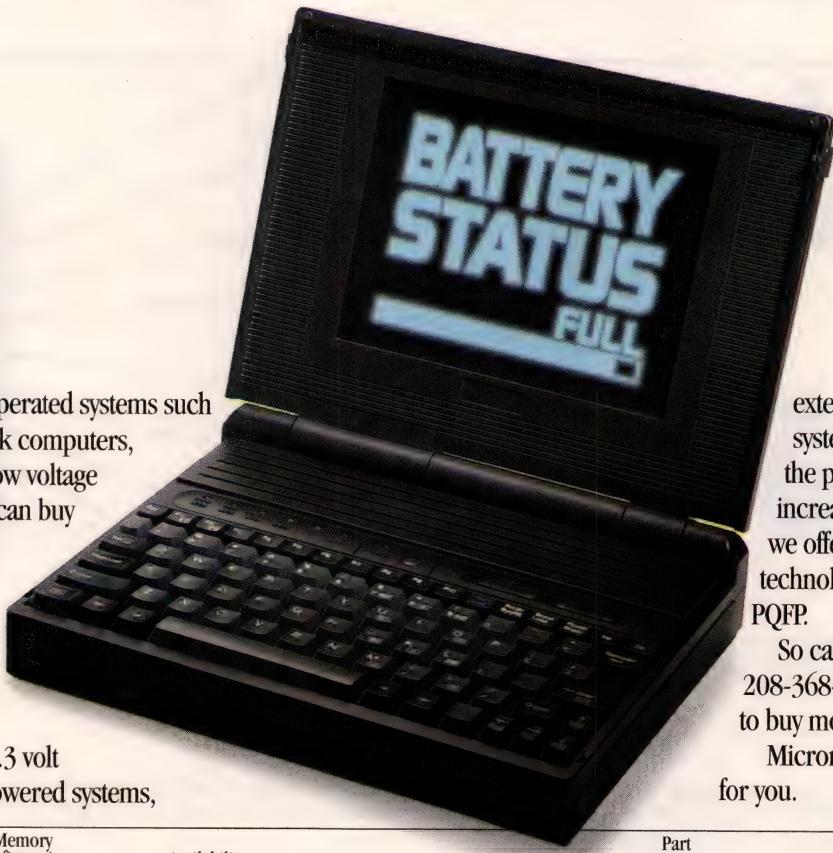
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MT4LC4001 L	1 Meg x 4	4Q92	MT5LC2516	Latched 16K x 16	Now	
MT4C4256 VL	256K x 4	Now	MT58LC1616	Synchronous 16K x 16	Now	
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MT4C4001J L	1 Meg x 4	Now	MT5C1001 LP	1 Meg x 1	Now	
MT4C8512 L	512K x 8	3Q92	MT5C1005 LP	256K x 4	Now	
MT4C16256 L	256K x 16 DW <sup>1</sup>	3Q92	MT5C1008 LP	128K x 8	Now	
MT4C16257 L	256K x 16 DC <sup>2</sup>	3Q92	MT5C2561 LP	256K x 1	Now	
MT4C1024 L	1 Meg x 1	Now	MT5C2564 LP	64K x 4	Now	
MT4C4256 L	256K x 4	Now	MT5C2565 LP	64K x 4 $\overline{OE}^5$	Now	
MT4C1664 L	64K x 16 FPM <sup>3</sup>	Now	MT5C2568 LP	32K x 8	Now	
MT4C1670 L	64K x 16 SC <sup>4</sup>	Now				

\*Self Refresh

<sup>1</sup>DW—Dual Write Enable

<sup>2</sup>DC—Dual CAS

<sup>3</sup>FPM—Fast Page Mode

<sup>4</sup>SC—Static Column

<sup>5</sup> $\overline{OE}$ —Output Enable

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fers. Thus there won't be compatibility problems between newer instruments and older interfaces, although achieving streaming speeds requires support by both instruments and interfaces.

The protocol's simplicity ensures freedom from constraints on the depth of a device's memory. At any time during a streaming transfer, a device can stop the transfer by asserting the NRFD (not ready for data) signal. If your test system contains a device whose output needs checking at some minimum rate, you need not worry about streaming transfers that cause you to miss critical data. You can set up the system's software to limit the duration of the streaming transfers, allowing you to check the critical device.

The best throughput will occur if you don't interrupt streaming transfers. CEC claims that with a 1m-long cable, you can achieve transfer rates of 5 Mbytes/sec, which is 5× greater than the best performance claimed by other vendors for standard IEEE-488. With a cable 10m long, the transfer rate is 2.5 Mbytes/sec.

An indexed manual describing 488SD—with state and timing diagrams and signal definitions—is free of charge. CEC will update this manual as the protocol evolves. The 488EX board includes a universal software driver for languages that support file I/O, a software analyzer that detects and suggests corrections to programming errors, a library of sample programs, and a programming and applications manual.—**Dan Strassberg**

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CIRCLE NO. 49

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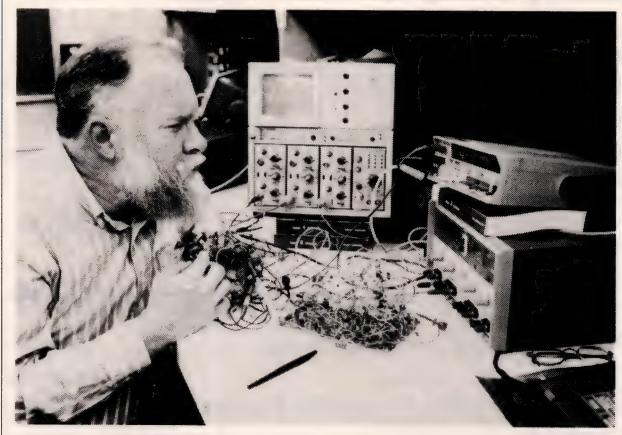
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TCAHNERSUS

# 24-bit DSP processor runs at 40 MHz

DSP processor clock rates are climbing. Motorola's 56002 is the second generation of the 24-bit, fixed-point 56001. The 56002 runs to 40 MHz, whereas the 56001 topped out at 33 MHz; this speed increase yields an improved performance of more than 20%. The 56002 peaks at 20 MIPS and 120 million operations/sec: it performs a MAC (24-bit add and multiply, result to 56-bit accumulator) with X and Y data transfers.

The 56001/2 is the only 24-bit, fixed-point DSP processor currently available. It provides higher accuracy and performance than basic 16-bit DSPs, without the larger memory of a 32-bit fixed- or floating-point DSP.

The 56002 incorporates the 56001's core and peripherals. However, the 56002 uses Motorola's universal-design-rule technology, which enables designs to move from process to process easily. The current implementation is on 1.0- $\mu$ m CMOS but eventually will be moved to 0.8- $\mu$ m CMOS. The design is

## 56002 DSP processor

Clock . . . . .	to 40 MHz internal (PLL input, to 4096x)
Instruction cycle . . . . .	2 clock cycles, 50 nsec
Registers . . . . .	2 24-bit; 2 56-bit accumulator
Address space . . . . .	3 64-kbyte $\times$ 16 bit: program, X, Y
On-chip memory . . . . .	512 $\times$ 24-bit ROM (Instruction) 2 256 $\times$ 24-bit RAM 2 256 $\times$ 24-bit ROM
Arithmetic . . . . .	56-bit ALU (24-bit logic) 48-bit multiply (24 $\times$ 24)
Interrupt . . . . .	3 external interrupts
I/O . . . . .	24 pins
Serial . . . . .	asynchronous serial interface synchronous serial interface A/D, D/A, AES/EBU
Other . . . . .	automatic loop control, on-chip emulation, host and DMA interfaces
Package types . . . . .	132-pin pin-grid array or plastic quad flatpack
Price . . . . .	\$79 (sample qty)

fully static with clocks to dc frequencies. The PLL is programmable with a clock multiple to 4096.

Motorola added on-chip-emulation features of the 32-bit 96002 to the 24-bit DSP. Using on-chip emulation, designers can debug their application code, controlling the DSP processor via a 6-wire serial interface. Thus, engineers can opt to start and stop the processor, set breakpoints, and monitor and change memory and register values. Breakpoints trigger on program or data access, either ad-

dresses or address ranges. On-chip-emulation features include a breakpoint or pass counter to trigger a breakpoint on the  $n$ th compare iteration; the features also furnish a trace counter, specifying the number of instructions to be executed for each trace step.—Ray Weiss

*Motorola Inc, Microprocessor and Memory Technologies Group, 6501 William Cannon Dr W, Austin, TX 78735. Phone (512) 891-2000. FAX (512) 891-2652.*

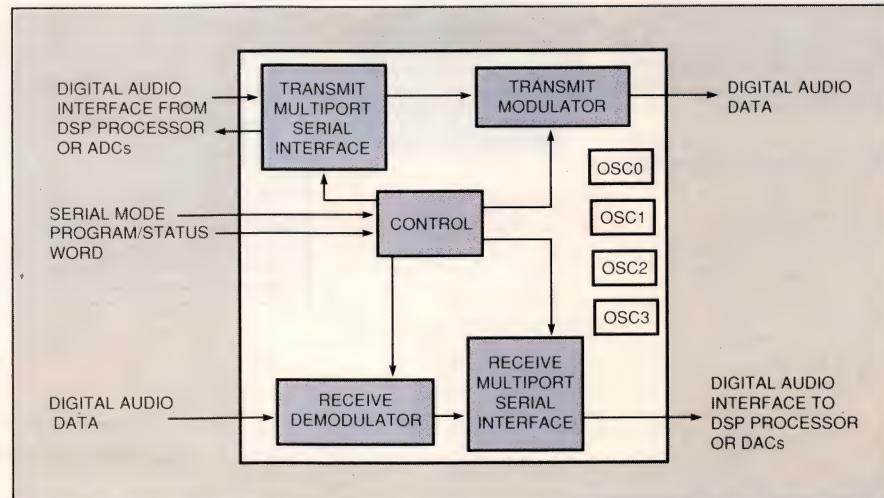
Circle No. 713

## Chip links DAT devices and DSP μPs

Digital audio brings the ease and interchangeability of today's plug-in audio jacks. Motorola's single-chip digital audio chip, the DSP56401, links DAT (digital audio tape) devices to DSP processors. The chip acts as a transceiver to multiple digital-audio devices, linking them directly to DSP56001/2 DSP processors.

The device meets the AES/EBU and EIAJ CP-340 digital-audio standards. It takes in unidirectional, self-coded, stereo digital-audio formats in a single serial channel. It acts as a DAT transmitter and receiver and contains a transmit serial interface, transmit demodulator, receive demodulator and a receive serial interface with a common clock generator. The transmit and receive serial interfaces can be clocked independently if needed. The hardware implements preamble detection and synchronization, parity and CRC checks, and block and frame synchronization.

A phase-locked loop (PLL) detects and recovers the bit clock from the modulated serial input. For



With this single-chip digital-audio transmitter/receiver, you can link DAT devices to DSP processors, ADCs, and DACs.

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2.5x5x10"	400W	5V/50A	12-15V/15A	12-24V/3.5A	5-15V/6A	
2.5x5x10"	400W	5V/50A	12-15V/15A	12-24V/3.5A	2-6V/6A	
2.5x5x11"	400W	2-6V/60A	5-15V/12A	5-15V/12A	2-6V/12A	
2.5x5x11"	400W	5-15V/24A	5-15V/12A	5-15V/12A	2-6V/12A	
2.5x5x11.5"	500W	5V/70A	12-15V/15A	12-24V/3.5A	5-15V/6A	
2.5x5x11.5"	500W	5V/70A	12-15V/15A	12-24V/3.5A	2-6V/6A	
3x5x14.25"	600W	5V/80A	5-24V/10A	5-24V/10A	5-24V/5A	5-24V/5A
3x5x14.25"	600W	5V/100A	5-24V/10A	5-24V/5A	5-24V/5A	
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transmission, a modulator state machine generates the preambles, parity, and CRC data incorporated in the transmitted frame with audio and nonaudio data. DAT transmission uses the LSB-first, biphase-mark Manchester decoding for transmission and receive. Multiple DAT devices interface to a single DSP56401. Combined with the DSP56001/2, it provides two chips for processing DAT applications.

In addition, the chip interfaces directly to Motorola D/A and A/D converters. The chip includes four oscillators and a jitter clock recovery system.

The DSP56401 comes in a 64-pin

plastic quad flatpack and costs \$25 (sample qty). An evaluation board is available from Spectrum Signal Processing Inc (Burnaby, BC, Canada). This 5 × 5.75-in., 4-layer board includes DAT input/output ports as well as ports to the DSP56001/2 and to audio converters such as those made by Burr-Brown. Audio connectors for AES/EBU optical lines, balanced-line XLR connectors, and unbalanced RCA connectors are also available.—**Ray Weiss**

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**Circle No. 714**

80C51 RAM and ROM to 256 bytes of RAM and 8 kbytes of ROM.

An 8051 takes 12 external clocks (6 internal clocks) for an instruction cycle, which includes an instruction and a potential data fetch. At 33 MHz, a base instruction takes 360 nsec. The instruction access time for external memory is specified at 90 nsec, which under previous specs would have been 60 nsec.

Recharacterized 80C51 timing results in memory access times that are lower across the entire line: a 24-MHz 8xC51 now uses a 120-nsec memory, compared with 90 nsec previously required.—**Ray Weiss**

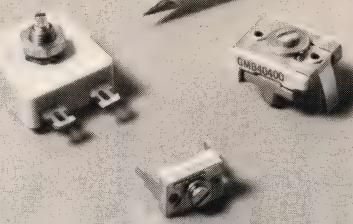
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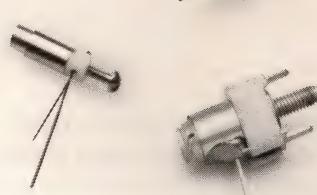
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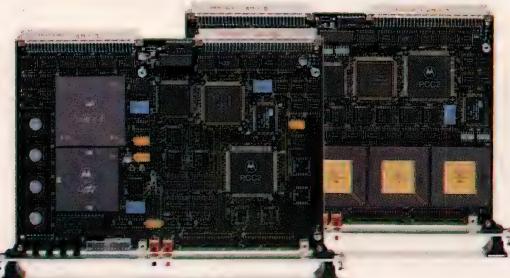
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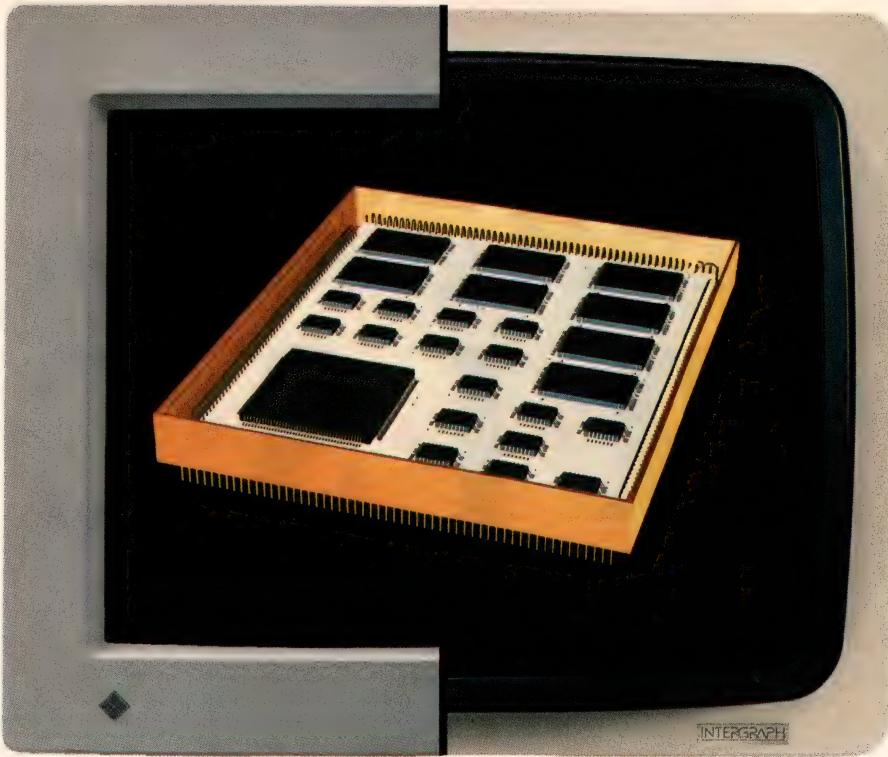
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# Third-generation R·I·S·C processors

**Ray Weiss, Technical Editor**

Third-generation RISC processors are moving into the technical world spurred by rising chip densities and higher clock rates. RISC (reduced-instruction-set computer) microprocessors delivering 50 to 100 VAX MIPS are here now; others will be available within the next six months.

First-generation RISC processors—the IBM 801, the Berkeley SPARC, and the Stanford MIPS—were research projects that laid the groundwork for the second generation. Second-generation RISC processors operate at 25 to 60 VAX MIPS. They have a single instruction pipeline, which lets them execute multiple instruction in sequence at one time. These processors issue one instruction per cycle but complete one instruction every 1.2 to 1.6 clock cycles. The problems that prevent these chips from completing the ideal of one instruction every cycle include data dependencies, register conflicts, instruction- and data-cache misses, and the occurrence of branch instructions.

Two design techniques are enabling third-generation RISC chips to crash through the performance barriers of the second generation. Superpipelining is the treating of pipeline stages as miniature pipelines. Thus, the stages can

start executing a second instruction before finishing the first, which speeds the performance of the processor as a whole. Superscalar RISC processors have two or more instruction pipelines running in parallel, which quickly increases instruction throughput.

However, superpipelined and superscalar architectures have their own set of problems. For example, the branch-related problem of second-generation chips are even worse for the third generation. And, third-generation chips require more-complex control logic and wider instruction bandwidths.

The superpipelined and superscalar architectures came from the world of mainframe and supercomputer designers, as do two techniques for easing third-generation chip problems: register scoreboarding and register renaming.

Every major RISC chip design is moving to either superpipelining or superscalar implementations to break out of the performance limitations of second-generation RISC processors. The Mips Computer Systems R4000, Sun SPARC, Motorola 88110, Intergraph Clipper, IBM RS/6000, Intel i960 and i860, National Semiconductor 32SF641, SGS-Thomson T9000

**Mainframe and supercomputer design techniques are pushing the performance of third-generation RISC processors to 70 VAX MIPS and beyond. These processors issue as many as three instructions per clock cycle and have clock rates ranging from 50 to 200 MHz.**

.....



Manufacturers are speeding RISC microprocessors' instruction throughput by using superpipelined and superscalar architectures. (Photo courtesy Mips Computer Systems Inc)

## THIRD-GENERATION RISC PROCESSORS

Transputer, and Digital Equipment Corp Alpha are all part of this next-generation of processing power.

RISC processors are pipelined so multiple instructions can execute in sequence at one time. A pipeline is a series of stages; each stage performs one of the micro-operations that make up an instruction. These micro-operations include instruction fetch, instruction decode, operand fetch, operation execution, and result writeback. The ideal is to have a balanced pipeline in which all stages take the same number of clock cycles to execute. Pipelining isn't new; IBM introduced the technique in its 7030 Stretch computer in 1960.

With careful hardware design, a pipeline that has  $n$  stages can concurrently execute  $n$  sequential instructions: fetching the next instruction in the first stage, decoding the current instruction in the second stage, fetching the operands for the previous instruction in the third stage... A new instruction starts at each pipeline cycle, but the instruction latency (the time for an instruction to finish) would be  $n$  cycles.

The maximum instruction throughput of an ideal pipelined RISC chip would be 1 CPI (cycles per instruction). At each clock cycle, the CPU would issue a new instruction and finish a previous instruction. In practice, second-generation RISC processors deliver throughputs of 1.2 to 1.6 CPI.

### Hang-ups and hurdles

Rocks and shoals limit RISC-processor performance. Data dependencies and resource conflicts can cause processing to stall or hang up. For example, a load instruction whose value is used by the following instruction can trigger an interlock. The second operation stalls until the data is available in the pipeline. Similarly, data dependencies—the result of one instruction being used by a following one—can cause a delay until the result is passed to the pipeline stage where it's needed.

Branches can cause worse problems, and most code has a lot of branches. In fact, branches often average as many as one every four to six instructions. The problem with pipelines and branches is self-evident: On each cycle the pipeline

fetches a new instruction, but which instruction should it pick following a conditional branch? The logic executing a branch instruction may not know which is the next instruction address for one or more stages. And if the logic chooses the wrong path, it will have to flush the pipeline to remove intermediate results.

Another hurdle for RISC chips to overcome is load and store delays. RISC architectures tend to limit memory accesses to load and store instructions. The CPU manipulates data in loaded registers. Some RISC processors, however, do have complex instructions: IBM's RS/6000 features multiple loads or stores.

Loads cause delays of as many as three cycles in second-generation RISC processors. If an instruction following a load uses the loaded value, it stalls until that value is available to the pipeline. In some third-generation RISC chips, such as the Mips R4000, an instruction can't use a loaded value until the third or fourth pipeline stage. DEC's Alpha chip, for example, has a 3-cycle delay for loads.

Store instructions can also cause significant delays, especially if they need a new cache entry or write to memory. Many third-generation RISC chips buffer stores to decouple memory accesses from the CPU pipeline, thus minimizing stalls. Another way to lessen store delays is to forward the buffered store data to downstream loads so the loads won't stall while waiting for the data.

### Pushing the clock

Probably the most obvious way to increase performance is to increase the base CPU clock rate, which is what RISC chip vendors have been doing. Second-generation RISC processor clock rates have peaked at 40 to 50 MHz.

Simply pushing up the clock rates has the advantage of minimizing mi-

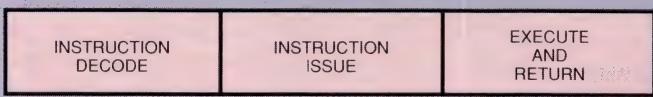
#### Intel i960CA

- ✓ 16-, 25-, 33-, 40-MHz clock
- ✓ 575,000 transistors
- ✓ 30 SPECmarks
- ✓ Superscalar, issues as many as 3 instructions per clock cycle
- ✓ 6-port 32×32-bit register file, 128/64 bit paths
- ✓ 1-kbyte 2-way set-associative instruction cache with 128-bit line size; 1.5-kbyte data/register-set cache
- ✓ 32-bit pipelined external memory interface; multiple memory regions, burst mode
- ✓ 3-stage pipeline, 2 stages for branches
- ✓ Four functional units: multiply/divide,

- instruction/fetch, integer, and address generation; no FPU
- ✓ Branch-prediction bit; out-of-order branch execution; speculative post-branch execution
- ✓ Pipelined store, 3-entry buffer
- ✓ Register scoreboard in scheduler
- ✓ 16-MHz version, \$69.90; 33-MHz version, \$107.65 (25000)

Comments: First commercial embedded RISC µP. Family targets embedded systems and data-handling chores. Military part has FPU, MMU, and 2-kbyte instruction and data caches.

#### PIPELINE



cro-architectural changes you'd otherwise have to make to get higher speeds. However, as internal clock rates go up, the nicely balanced, fixed-stage RISC pipeline

often starts to crumble. Designers can easily speed up and even double the rate of some stages; the rates of others, such as caches, can't be increased.

One way around the speed-up difficulty is to pipeline the individual pipeline stages. Thus, a pipelined stage, such as a cache or a multiplier, could accept a new instruction

## Mips Computer Systems R4000SC

- ✓ 100-MHz internal clock (50-MHz external)
- ✓ 1.1M transistors
- ✓ 70 SPECmarks
- ✓ Superpipelined architecture
- ✓ 64-bit architecture; 36-bit physical address space
- ✓ 32 × 64-bit integer registers, 16 × 64-bit floating-point registers
- ✓ Two direct-mapped 8-kbyte caches, 64-bit fetch, 16- or 32-byte line size
- ✓ PC version has 64-bit multiplexed, address/data bus; SC version has 128-bit data bus.
- ✓ Supports 128-kbyte to 4-Mbyte direct-mapped secondary cache
- ✓ Eight pipeline stages
- ✓ 3-cycle branch delay
- ✓ 2-cycle load delay
- ✓ 2-entry (64 bits each) store buffer
- ✓ Chip vendors are sampling (see manufacturers' box); prices vary from \$615 to \$1300, depending on version, quantity, and vendor.

Comments: Three chip versions: the low-end PC (179 pins); the SC, which supports secondary cache; and the MC, an SC that can do multiprocessing. The ISA architecture was designed by Mips; six chip vendors have signed up to produce the R4000, which is one of the ACE (Advanced Computing Environment) consortium CPUs.



\*ONLY FOR LOAD OR STORE INSTRUCTIONS

## RISC references

Here are five technical references to help you get up to speed on third-generation RISC microprocessor architectures:

- Microprocessor Report (triweekly newsletter, \$445/year), 874 Gravenstein Hwy S, Suite 14, Sebastopol, CA 95472. (707) 823-4004. FAX (707) 823-0504.

Edited by Michael Slater, this periodical is an excellent source for evaluating  $\mu$ P and  $\mu$ C chips. The newsletter provides in-depth analysis for new chips and architectures. The same organization also holds the annual Microprocessor Forum, which is where most companies present their major chip designs.

- Superscalar Microprocessor Design, by Mike Johnson, Prentice-Hall Inc, Englewood Cliffs, NJ, 1991, \$48. ISBN 0-13-875634-1.

This resource is the only technical book that completely addresses superscalar processor design. It provides a good, clear set of definitions and in-depth analysis of superscalar design techniques.

- Computer Architectures: A Quantitative Approach, by John L Hennessy and David A Patterson, Morgan Kaufmann Publishers Inc, Palo Alto, CA, 1990, \$64.95. ISBN 1-55880-069-8.

This book is rapidly becoming the computer designer's bible. Written by RISC pioneers Hennessy and Patterson, it is a textbook, a collection of design lore, and a RISC-based design example to study. This massive book contains some 700 pages of tutorial and design techniques and is an easy read as well.

- Cache and Memory Hierarchy Design: A Performance Directed Approach, by Steven A Przybylski, Morgan Kaufmann Publishers Inc, Palo Alto, CA, 1990, \$43.95. ISBN 1-55860-136-8.

If you need the numbers to evaluate cache designs, this book is for you. It provides detailed models of cache designs that are based on actual simulation and trace data. The book breaks down memory-level design and includes models for varying cache and line sizes, memory speed, and set size.

- IBM Journal of Research and Development, Vol 34, Number 1, January, 1990. IBM Corp, Armonk, NY.

This volume is a complete set of papers defining the IBM RS/6000 superscalar architecture. It provides a comprehensive system, hardware, and software view of superscalar design and implementations.

## THIRD-GENERATION RISC PROCESSORS

each clock cycle, even if the stage had not finished executing the current instruction. This technique is called superpipelining.

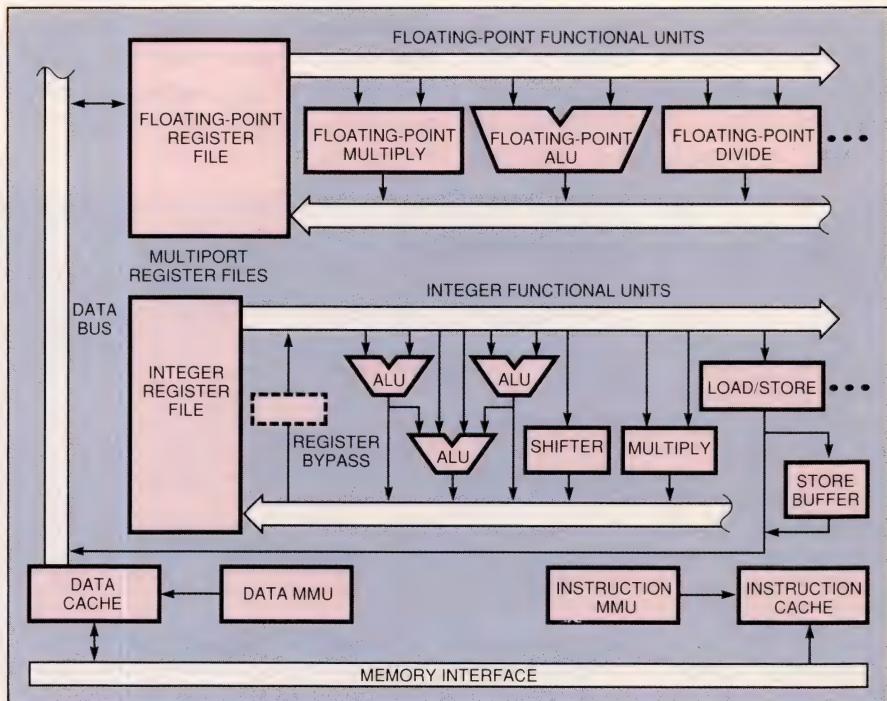
Superpipelining enables RISC designers to take advantage of higher clock speeds and still keep their basic pipeline stages. However, the technique only makes sense if the designer can raise clock rates dramatically, which is not possible every year.

Mips Computer Systems used superpipelining for its R4000. The R4000's base clock is 50 MHz, but the chip actually uses a 100-MHz internal clock. The Mips R3000's 5-stage pipeline grew to eight stages for the superpipelined R4000.

Superpipelining has its own costs. Each superpipelined pipeline stage must be latched. Functional units—logic that does one or more specific function—must be partitioned to match the basic clock rate, perhaps complicating the logic. In addition, the functional units' pipelined stages need their own level of control. Most new and emerging RISC processors include pipelined functional units. Intel's i860, introduced in 1989, has pipelined floating-point add, multiply, and graphics units, as does the IBM RS/6000's FPU (floating-point unit).

Another way to increase processor performance is to do more than one operation at a time. Superscalar RISC processors can issue, and ideally execute, more than one scalar instruction per clock cycle. In effect, such processors run multiple pipelines in parallel.

One of the benefits of using superscalar techniques is that designers can increase performance without necessarily raising clock rates. Typically, higher clock rates open up new difficulties in interfacing the CPU to the lower memory levels, such as main memory and disk storage. These memory media do not move as rapidly up the speed curve as processor silicon. So the faster



One way to get superscalar performance—a processor's issuing more than one instruction per cycle—is to have multiple functional units executing in parallel. You can even cascade functional units, as shown by the two parallel adders feeding a third adder their results.

a CPU goes, the larger the speed gap between the CPU and the various memory levels.

Thus, increased delays in memory and store accesses for cache misses and page faults can nibble away performance increases realized from faster clocks. One reason for the increasing use of secondary caches is that these caches provide a buffer layer between the high-speed on-chip caches and the slower system memories.

Superscalar techniques let you have your cake and eat it, too: You get more instruction throughput without a need for faster caches. These gains aren't free. Processor control logic must, by necessity, become more complex, although this logic will still be a small portion of the total chip transistor count.

Also, superscalar processors need wider memory accesses than second-generation, single-pipeline RISC chips so they can pump through groups of multiple instruc-

tions for execution. A superscalar processor of degree  $n$ —one that issues an average of  $n$  instructions per clock cycle—requires an instruction bandwidth approaching  $n$  times the scalar instruction bandwidth. Superscalar operation does not as heavily affect the data bandwidth because loads and stores are 10% or less of a typical RISC instruction mix. Memory interfaces are moving to 64 bits in most processors; some superscalar RISC processors have a 256-bit-wide memory bus.

### Evaluating the third generation

However, designing a high-performance third-generation RISC processor is more complex than just choosing between superpipelining and superscalar techniques. Implementation technology has changed the playing field. Yesterday's world of fixed-length pipelines and stages is gone. Second-generation RISC ALUs and caches

were major performance bottlenecks. But third-generation fast adders and multipliers and pipelined caches are changing that state of affairs. Today, RISC adders can do a full addition in what used to be half a stage clock. For example, the Mips R4000 does a 64-bit addition in one 50-MHz clock cycle.

Fast adders and pipelined caches have led to a confusing state of affairs. The previous way of evaluating RISC implementations by taking the functional-unit clock rate as a base won't work anymore. Many emerging RISC chips, such as the Motorola 88110 and the TI SuperSparc, no longer have functional units that all take the same number of clock cycles. Some stages take three cycles; others complete in one. The SuperSparc, for example, has three adders, two of which can feed into the third. All adds complete in one 50-MHz clock cycle; the individual adders operate in half a clock cycle. The IBM RS/6000, a multichip RISC implementation, has different-length pipelines to compensate for delays between

## National Semiconductor 32SF641

- ✓ 33-, 40-, 50-MHz internal clock; external bus half internal rate
- ✓ 1.1M transistors
- ✓ 100 native MIPS peak, 1024-item FFT in 1.5 µsec, single-cycle integer multiply takes 20 nsec; 2-cycle floating-point multiply
- ✓ Superscalar architecture, dual instruction fetch, dual pipelines
- ✓ 6-port register file; 32 × 32-bit general-purpose registers, 16 × 64-bit floating-point registers
- ✓ 4-kbyte, 2-way set-associative instruction cache, 64-bit line size; 1-kbyte, 2-way set-associative data cache, 128-bit line size; both are locking caches
- ✓ 64-bit external-memory interface
- ✓ Two pipelines with buses: 4-stage integer pipeline, 5-stage integer/floating-point pipeline

### PIPELINE

INSTRUCTION FETCH	INSTRUCTION DECODE	EXECUTE	MEMORY ACCESS FOR LOAD	STORE RESULT
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Comments: Chip suits embedded systems and math-intensive, DSP-type processing. 64-bit memory bus is dynamically sizable and designed for interleaved memory. C-like assembly language. Dual-processor mode for fault-tolerant operation.

functional units on different chips.

Thus, there's no clear dividing line between superpipelined and superscalar architectures. Super-

pipelining—the pipelining of functional units—is becoming universal. You can't evaluate the emerging third-generation RISC processors by looking at the basic clock frequency and calculating a CPI rating. The superscalar Mips R4000 delivers 70 Specmarks. In the old view, that performance would be considered good for a 50-MHz clock but mediocre for a 100-MHz clock. Many RISC chips always had internal clocks faster than their system clocks, but now the internal clocks are viewed as the instruction-cycle clock.

### Parallel functional units

Superscalar RISC processors are following the track pioneered by mainframe and supercomputer designers. Chip designers are dividing processor operations into separate, parallel functional units. These units can execute in parallel if there are no data dependencies or resource conflicts. CDC (Minneapolis, MN) introduced this technique in its

## IBM RS/6000 single-chip processor (RSC)

- ✓ 33-MHz clock
- ✓ 1.2M transistors
- ✓ 25.9 SPECmarks
- ✓ Superscalar architecture, issues dual instructions
- ✓ 32 × 64-bit register file, 32 × 64-bit FPU register file
- ✓ 8-kbyte combined instruction and data cache; 2-way set-associative write-through cache
- ✓ 64-bit data and 27-bit address buses, 32-bit I/O bus; glueless SIMM connection; 8-bit error-correction codes
- ✓ 5-stage pipeline
- ✓ Three functional units: fixed point, floating point, branch
- ✓ Static branch-prediction bit; automatic in-page instruction fetch

- ✓ 4-entry store buffer
- ✓ Microcoded I/O sequencer for I/O and DMA
- ✓ In-order execution
- ✓ 3.3V, 4W
- ✓ Proprietary—used in the IBM Powerstation 220

Comments: The RSC is the single-chip version of IBM's Power architecture, the RS/6000 multichip implementation. The Power architecture will also be extended for single-chip versions in a joint development with Motorola and Apple. The series, the PowerPC, will initially use the 88110 bus interface and be built by Motorola. PowerPC will handle 32- and 64-bit operations.

### PIPELINE

INSTRUCTION FETCH	INSTRUCTION DECODE	EXECUTE INSTRUCTION	EXECUTE SECOND FLOATING-POINT INSTRUCTION OR FIXED-POINT RESULT WRITEBACK	FLOATING-POINT RESULT WRITEBACK
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## THIRD-GENERATION RISC PROCESSORS

6600 mainframe, which had 16 functional units including four FPUs and seven integer units.

Most RISC superscalar processors issue two to three instructions per clock cycle. Thus, they can make do with as few as two or three parallel functional units. The i960, 32SF641, T9000, and DEC Alpha chips have four functional units each. IBM's multichip RS/6000 and single-chip RCS each have three functional units.

All functional units, however, are not alike. IBM's RS/6000 and Intel's i960 have a few, sophisticated functional units, which include multi-stage control logic. An example of such a unit is the RS/6000's instruction-cache unit, which handles branches and condition-code operations internally. It dispatches instructions to the fixed-point or floating-point functional units.

The alternative approach is to have more, less-sophisticated functional units. These units are more like the execution units that run the execute stage in a second-generation CPU pipeline. The 32SF641,

88110, and SuperSparc take this more egalitarian tack.

The 88110 has 10 functional units, including two ALUs, two graphics units, a bit-field unit, a floating-point add unit, a multiply unit, and a divide unit. The two remaining units—the load/store and superscalar-instruction units—are more control oriented. The load/store functional unit helps coordinate loads and stores. Its logic can easily check for loads that are dependent on pending stores. For example, the 88110 has a separate load/store execution unit. The 88110 also has seven spare functional-unit addresses for future expansion.

Integer ALU instructions make up the largest percentage of instructions executed by RISC processors. In some studies of the Mips architecture, ALU operations were 40 to 50% of all instructions executed. Thus, multiple ALUs provide a way to speed execution. Many third-generation RISC processors have implemented multiple ALUs, including the National Semiconductor 32SF641, which has two

separate pipelines each of which has an integer ALU, and Motorola's 88110, which also has two ALUs.

Problems, however, start with data dependencies between sequential instructions; for example, an add that is followed by another add that uses the results of the first add instruction. Multiple ALUs won't help in this case: The second instruction will stall until it can use the result of the first as an input. Software scheduling can make the best use of multiple parallel ALUs by sorting instructions to minimize data dependencies. The compiler can intermix instruction sequences with partial results held in registers or cache.

The Sun/TI SuperSparc design team went even further than hanging three ALU functional units on a general bus. It created an ALU hierarchy: The first two ALUs operate independently, and the resulting outputs can feed into the third ALU. Thus, the third ALU can add the results of two adds. Moreover, all three adds can be done in a single group of simultaneously issued instructions.

### One, two, many

Legend has it that one Pacific Aborigine tribe has a limited counting system of 1, 2, and many. That system is perfect for describing superscalar CPI rates. One for the second-generation RISC limit, two for the third-generation superscalar limit, and many for future RISC processors.

It's just not that easy for a superscalar RISC chip to consistently issue multiple instructions. Dependency problems become worse than those of chips with a single pipeline because you've got more instructions to worry about at any given time. Issuing more instructions means having more-complex control logic. Techniques like register scoreboard and register renaming help to detect and minimize data

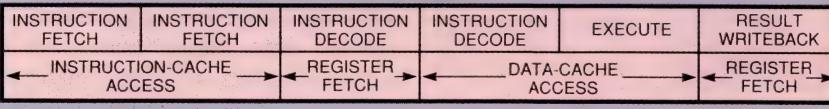
### Intergraph C400

- ✓ 50-MHz internal clock
- ✓ C411 integer unit, 160,000 transistors; C421 FPU, 140,000 transistors
- ✓ 42 SPECmarks
- ✓ Superscalar architecture, issues as many as 2 instructions per clock cycle; superpipelined functional units; C411 integer unit
- ✓ 5-port 32 × 32-bit register file
- ✓ Separate FPU chip, C421, has 16 × 64-bit floating-point registers
- ✓ External, direct-mapped unified cache as large as 128 kbytes
- ✓ Separate input and output buses: 64-bit output bus, 32-bit address/input bus
- ✓ Variable-stage pipeline: 3 to 5 stages
- ✓ Four functional units: ALU, multiplier, divider, shifter

- ✓ Compare and branch instruction takes 2 delay-slot cycles and has no condition codes; branch-prediction bit
- ✓ Pipelined loads and stores
- ✓ Register scoreboard stalls instructions until resources are available.
- ✓ In-order execution
- ✓ 7W chip has off-chip drivers/receivers; multilayer PGA
- ✓ \$1000 (1000) for C411 and C421 chip set

Comments: The C400 is the latest version of the Clipper RISC chip. Separate FPU on- and off-chip caches. Minimal RISC design suits multichip implementations. Company is working on a 64-kbyte cache/MMU chip for a multichip module.

Pipeline



dependencies and register conflicts.

In register scoreboard, which was pioneered by the CDC 6600 mainframe, a table or scoreboard tracks register use. A register scoreboard has a bit for each processor register. If the bit is set, the register has a pending update (a result coming). When the register is updated, the bit is cleared, opening the register up for use. Intel's i960, Motorola's 88110, and DEC's Alpha all use register scoreboard. The Alpha also uses scoreboard to check for resource and load/store dependencies.

Current superscalar chips issue multiple instructions, but in object-code order. The instructions issue in order, although they can finish out of order. The CPU checks for data dependencies before issuing the instructions. In-order execution minimizes control logic but limits instruction throughput. The hard-

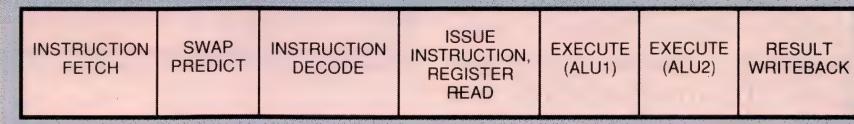
## Digital Alpha

- ✓ 200-MHz internal clock
- ✓ 1.68M transistors
- ✓ 100 SPECmarks (estimated)
- ✓ Superscalar architecture, issues as many as 2 instructions per clock cycle; pipelined functional units
- ✓ 64-bit processor
- ✓ 32 × 64-bit register file, 32 × 64-bit FPU register file
- ✓ 8-kbyte, 2-way set-associative instruction cache; 8-kbyte data cache; 32-byte line size
- ✓ Supports secondary cache
- ✓ 7-stage pipeline, 10 cycles for floating-point operations
- ✓ Four functional units: load/store, integer, FPU, branch
- ✓ Branch/data replacement operation: can load one of two values without taking a branch

- ✓ Function stack (four return addresses)
- ✓ 4-entry, 32-byte store buffer; 3-cycle load delay; store bypass
- ✓ Register scoreboard detects data dependencies and does result forwarding
- ✓ In-order execution for operations; single-cycle add, two sequential add cycles in pipeline
- ✓ Programmable modes for interfaces: ECL, TTL/CMOS; 128- or 64-bit data and secondary-cache interfaces
- ✓ 3.3V, 30W, 441-pin PGA
- ✓ Proprietary; introduced at ISSCC; hardware by end of 1992.

Comments: The Alpha RISC µP was developed by DEC as a replacement for the VAX and RISC CPUs. Designed for multiprocessing and VAX emulation.

### Pipeline



## Manufacturers of RISC processors

For more information on RISC processors such as those described in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

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## THIRD-GENERATION RISC PROCESSORS

ware is stuck with the instruction parallelism inherent to the instruction stream. It cannot reorder the stream for better parallelism.

Issuing instructions out of order is certainly possible, but the technique imposes a heavy hardware complexity cost because of the number of different possible instruction combinations that could occur ( $n$  fetched instructions  $\times m$  issued instructions  $\times p$  pipeline stages).

Register renaming is a hardware technique to minimize conflicts for register resources. The concept was introduced in the IBM 360/91 mainframe in 1967. Compilers convert high-level languages to assembly code, and in the process assign registers to hold values. In a superscalar processor, an operation may request a register before a prior instruction is finished using that register. This condition is not a data conflict. The downstream operation doesn't need the register value, just a register, and the operation

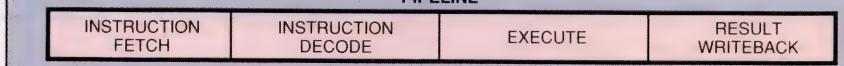
### Motorola 88110

- ✓ 50-MHz clock
- ✓ 1.3M transistors
- ✓ 63.7 SPECmarks (80 with secondary cache, both figures estimated)
- ✓ Superscalar architecture, issues as many as 2 instructions per clock cycle
- ✓ 8-port  $32 \times 64$ -bit register file,  $32 \times 64$ -bit or  $32 \times 80$ -bit FPU register file
- ✓ 80-bit internal data paths
- ✓ 8-kbyte, 2-way set-associative instruction cache; 8-kbyte data cache with 64-bit fetch; 32-byte line size
- ✓ 32-bit address, 64-bit external interfaces; split transaction (can start new cycle while waiting for access); 8-word burst bus, bus snooping
- ✓ 88410 chip is 256-kbyte to 1-Mbyte secondary-cache controller
- ✓ 4-stage pipeline, different-length stages
- ✓ Ten functional units: 2 ALUs, bit field,

- floating-point add, multiply, divide, load/store, superscalar execution, and two graphic units
- ✓ Static branch prediction; taken-branch, target-instruction buffer
- ✓ Load/store reordering, 3-entry store buffer
- ✓ Register scoreboard for detecting data dependencies; history buffer holds speculative results.
- ✓ In-order, speculative execution
- ✓ In development; release in second quarter 1992

Comment: Second-generation 88000 chip. Has powerful bus interface and can run with or without secondary cache. Has two 3-D graphics functional units: a pixel-pack and a pixel-add unit.

#### PIPELINE



will stall until a register is free.

The idea is to pick a free register, rename it to match the instruction

parameter, and let the instruction use it. A fast look-up table, usually an associative memory, translates the map or renames the register.

Register renaming is not yet in general use by most third-generation RISC processors. One reason is that third-generation processors are issuing small numbers of instructions concurrently. The SGS-Thomson T9000 can issue a group of as many as eight instructions, but it is a stack-oriented machine and doesn't need register renaming. IBM's RS/6000 uses register renaming in its FPU.

### Beating branches

Conventional branch-delay slots won't work well for superscalar RISC chips. A branch delay can be two cycles, but a superscalar chip that issues  $n$  instructions per clock cycle must find  $2n$  instructions to plug into the empty pipeline execution slots. Using branch delays has been relatively successful for a single branch in a single-pipeline RISC chip, but the technique's effectiveness falls off rapidly as more in-

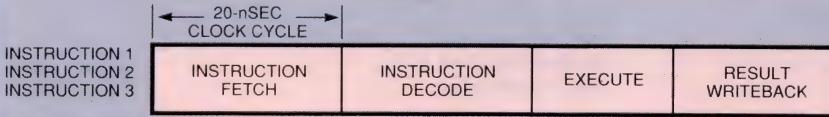
### Texas Instruments SuperSPARC

- ✓ 50-MHz base clock, 100-MHz clock cycle
- ✓ 3.1M transistors
- ✓ 75 SPECmarks (estimated)
- ✓ Issues 3 instructions per clock cycle
- ✓ 8-port  $32 \times 32$ -bit register file
- ✓ 20-kbyte, 5-way set-associative instruction cache; 128-bit instruction fetch; 16-kbyte, 4-way set-associative data cache; single 64-entry TLB (translation look-aside buffer) for both caches.
- ✓ 64-bit memory interface designed to Mbus-level II interface
- ✓ Cache-controller chip (2.2M transistors) handles as much as 2 Mbytes of direct-mapped secondary cache.
- ✓ 4-stage pipeline; different-length stages (2/3/2/1 clock cycles)
- ✓ Eight functional units: 3 integer ALUs, shifter, load/store, branch, floating-point multiply, floating-point divide

- ✓ Branch-prediction bit, taken branches optimized; loads branch target address on instruction fetch
- ✓ Fast load from cache, can use data in same group; 8-entry store buffer; load bypass
- ✓ Speculative execution; 2 instruction buffers: 8-word instruction prefetch, 4-word branch target prefetch; can stop and squash target instructions before writing values
- ✓ Sampling to SPARC International members

Comments: Most sophisticated, largest superscalar RISC processor to date. Joint development by Sun and TI. First superscalar SPARC chip. Both uniprocessing and multiprocessor configurations.

#### PIPELINE



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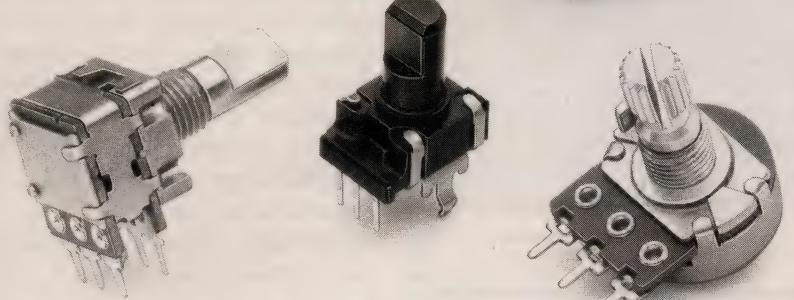
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**CIRCLE NO. 124**

## THIRD-GENERATION RISC PROCESSORS

structions are needed to fill empty slots.

The second-generation Hewlett-Packard PA chip limits branch delays by using built-in branch prediction. The CPU predicts that forward branches (tests) will not be taken and that backward branches (loops) will be taken. A 1-cycle stall results when the prediction is incorrect. SGS-Thomson takes a simpler approach for its T9000 Transputer. The processor predicts that all branches will not be taken and incurs a 5-cycle penalty for taken branches.

Other RISC processors use branch-prediction bits the compiler sets into the branch instruction word to predict taken or nontaken branches. The i960, C400, RCS, and 88110 all use branch-prediction bits.

Speculative execution takes branch prediction one step further. Not only does the processor pick a path to succeed the branch instruction, but it then begins filling the pipeline with the path's instructions and executing them. If the wrong branch path was taken, pipeline

### SGS Thomson T9000 Transputer

- ✓ 50-MHz clock (external 5-MHz clock)
- ✓ 3.2M transistors
- ✓ 70 SPECmarks (estimated)
- ✓ Superscalar architecture; issues as many as 8 instructions per clock cycle (prefix bytes count as instructions)
- ✓ 8-bit instructions
- ✓ Register file: Three integer stack registers, three floating-point registers, three ports (two read, one write)
- ✓ Local cache for local variables (256 bytes or 32 words)
- ✓ 16-kbyte cache RAM in 4 banks, fully associative; 4-word (16-byte) line size
- ✓ Memory interface: 32-bit address, 64-bit data buses; four 32-bit crossbar buses (1 for each cache bank); glueless 8-Mbyte max SIMM connection

- ✓ 5-stage pipeline
- ✓ Four functional units: two address generators, ALU, FPU
- ✓ Optimizes non-taken branches; 5-cycle penalty for taken branches
- ✓ Pipeline checks for dependencies and interlocks
- ✓ In development; sampling third quarter of 1992

Comments: Four 100-Mbyte/sec link ports to CPUs. Has two control links. Companion C104 chip for dynamic routing. Has 4-region MMU and fast context switch (local cache is write-through). Built-in hardware process-scheduling kernel.

#### Pipeline



execution for the post branch instructions halts, and the processor state rolls back to the branch point.

Another way to cope with branch indeterminacy is to use branch-target caches to hold branch-target

addresses. Typically, on the first pass the CPU takes the branch-delay penalty. On subsequent executions, the CPU takes the previously calculated branch address, thus eliminating any pipeline delays. This tactic is effective for loops; AMD pioneered this technique in RISC µPs with its second-generation 29000. The 88110 has an on-chip, 32-entry branch-target cache for holding target addresses. The cache holds instruction pairs for both taken and nontaken branch paths.

National Semiconductor's designers store the target address in a different place. The 32SF641 caches the branch-target address with the branch instruction in the instruction cache. Accessing the branch instruction brings up the target address. TI's SuperSparc uses branch prediction to select which branch path to execute. The CPU places branch-target instructions into a branch-target cache and then executes them. If the branch is wrong, the alternate path's set of instructions is also ready for execution,

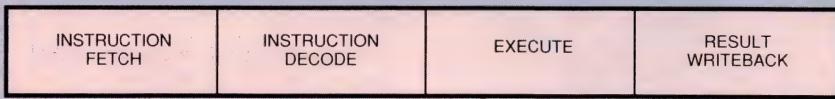
### Intel i860XP

- ✓ 25-, 40-, 50-MHz clock
- ✓ 2.55M transistors
- ✓ 42 SPECmarks
- ✓ VLIW (very-long-instruction-word) architecture: issues 2 instructions—1 scalar and 1 floating point—per clock cycle; FPU instruction can schedule 2 FPUs.
- ✓ 32 × 32-bit register file, 16 × 64-bit FPU register file
- ✓ 4-way set-associative 16-kbyte instruction and 16-kbyte data caches; 32-byte line size
- ✓ 64-bit memory interface, 2 clock cycles per transfer, burst mode; uses MESI (modified, exclusive, shared, or invalid) cache-coherency protocol
- ✓ 4-stage pipeline
- ✓ RISC core and three functional units—

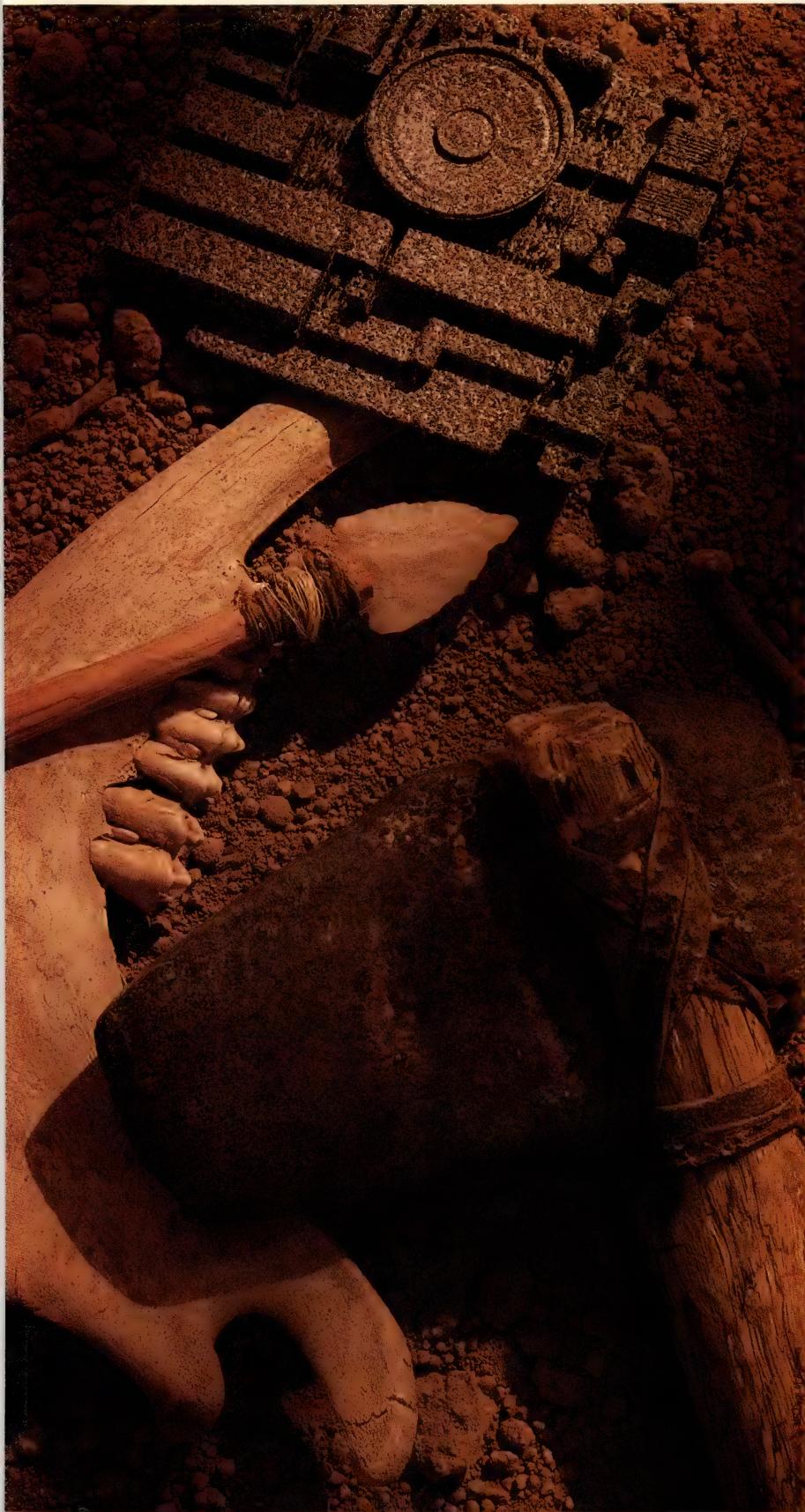
- multiply, add, and graphics (all pipelined)—in FPU
- ✓ Compiler-filled branch-delay slots
- ✓ Pipelined floating-point load instruction bypasses cache with 128-bit load.
- ✓ Single- or dual-instruction mode
- ✓ Built-in support for PAX (parallel architecture extension) for medium grain parallelism.
- ✓ Built-in graphics functional unit for pixel and Z buffer manipulation
- ✓ \$132, \$327, \$551 (1000) for 25-, 40-, and 50-MHz versions, respectively.

Comments: New XP version has faster clock, write-through caches, bus snooping, and built-in hooks for medium grain multiprocessing.

#### Pipeline



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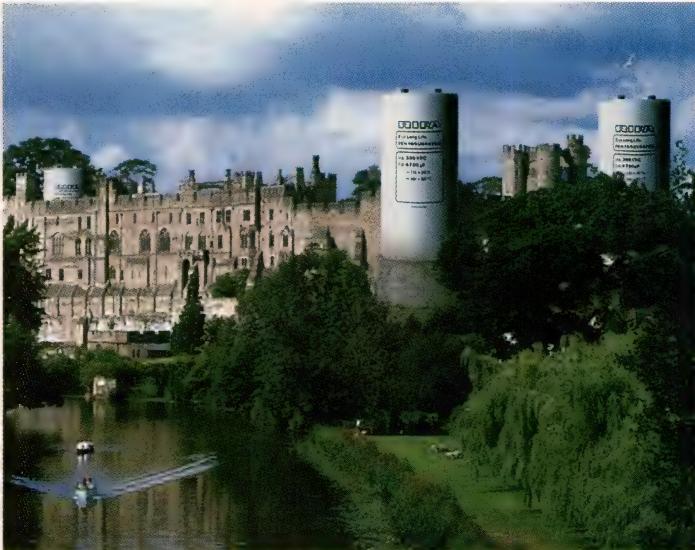
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## RISC PROCESSORS

which minimizes the cost of the CPU's predicting wrong.

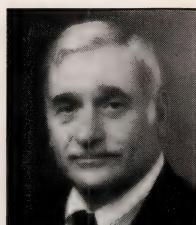
The DEC Alpha architecture has combined instructions: The processor can do a value selection—setting one value or another depending on a test—without needing to use a branch. The first instruction sets the first value. The second instruction tests another value and will load a second value if specified by the test results. This instruction sequence eliminates the need to use a branch to set alternative values, which in turn avoids pipeline interruptions.

Conventional condition codes can become a real problem with superscalar execution. Multiple instructions, such as two adds, could set conflicting condition codes. Designers needed a way to handle multiple conditions without conflict. IBM took the tack of creating separate condition-code registers in its instruction-cache unit. Multiple conditions can be tested using a single branch.

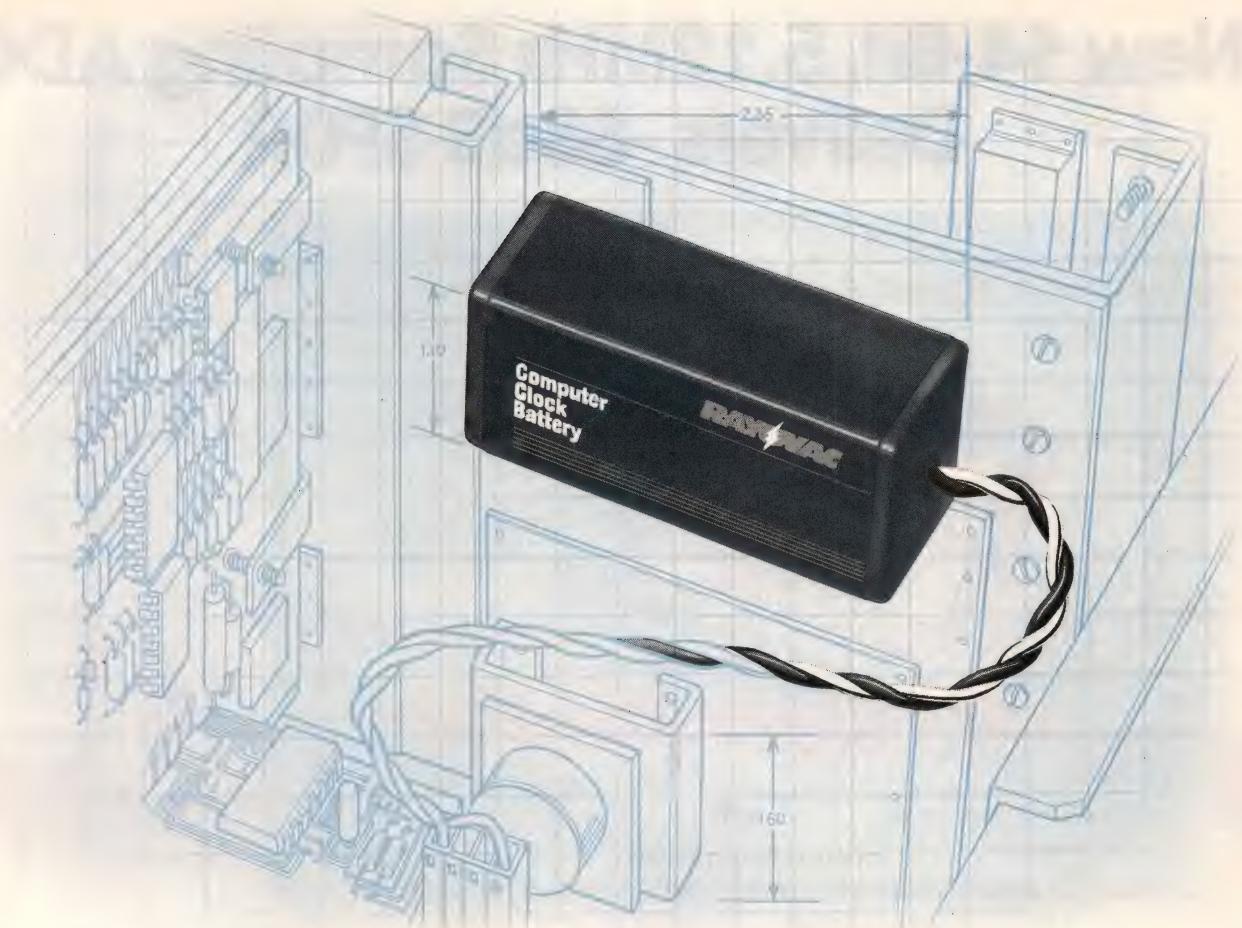
Some RISC processors take a different approach to condition codes by eliminating them entirely and placing ALU and test results into an addressed register. The Mips RISC chips and the 88110 use this approach.

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*Ray Weiss, Technical Editor, can be reached at (818) 704-9454; FAX (818) 704-7083.*



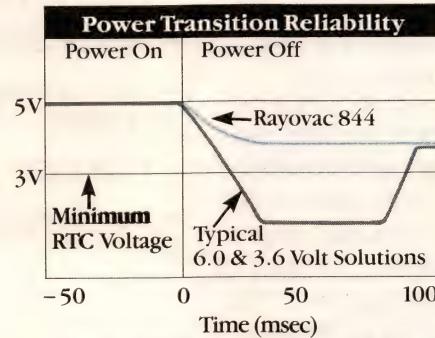
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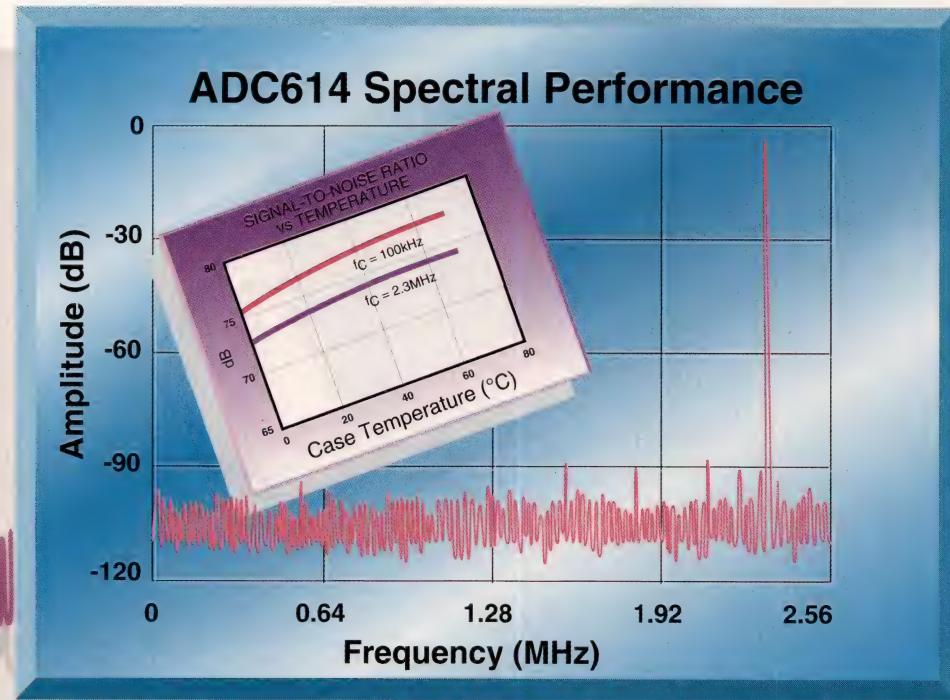
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# Time-domain techniques enhance testing of high-speed ADCs

**Michael J Demler, Micro Networks**

*Designers commonly use DSP techniques to characterize the dynamic performance of high-speed A/D converters, but these tests often yield an incomplete picture. Adding a sine-wave curve-fitting algorithm or beat-frequency test provides the missing description of sampling accuracy in the time domain.*

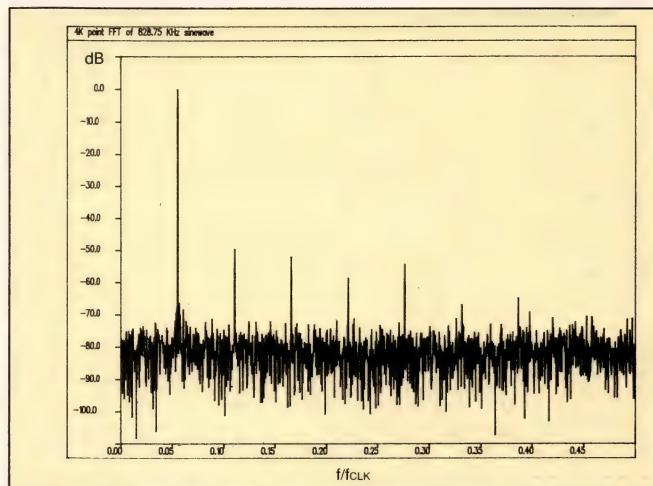
The increasing availability and applications of high-speed A/D converters has led most manufacturers to include specifications for dynamic performance in their data sheets. Limiting dynamic testing to DSP techniques such as FFTs or statistical modeling such as sine-wave histograms does not portray the complete picture of a device's performance. Designers can employ a sine-wave curve-fitting algorithm or beat-frequency test techniques to add measurements in the time domain for a more comprehensive analysis. Time-domain analysis allows an engineer to evaluate test results without the limitations inherent in transforming sampled signals into other forms.

The most common DSP test uses a fast Fourier transform (FFT) to do a spectral analysis of an ADC's digital output. Fig 1 shows the FFT obtained by testing the Micro Networks MN5902, an 8-bit CMOS flash ADC. The ADC was sampling a full-scale 828.75-kHz sine wave at 15 MHz. The test was a 4k-point FFT. The ratio of signal amplitude to noise plus distortion was 44.1 dB.

Spurious-free dynamic range (SFDR) is a measure of the usable dynamic range of an ADC. SFDR is

defined as the difference, in decibels, between the amplitude of the fundamental and that of the largest spurious component in the FFT spectrum. In the example, the SFDR measured 49.6 dB between the fundamental and the second harmonic at 1.66 MHz.

An equation that expresses the signal-to-noise ratio (S/N ratio) of an ideal ADC with a resolution of n bits is  $S/N \text{ ratio} = 6n + 1.8 \text{ dB}$  (Ref 1). Because the S/N ratio of an ideal 8-bit ADC is 49.8 dB, the spurious-free range of 49.6 dB illustrated in Fig 1 depicts an ADC that exhibits a usable dynamic range of 8 bits. A parameter called the effective number of bits (ENOB),



**Fig 1**—This plot shows the result of a 4k-point fast Fourier transform (FFT) performed on the MN5902 8-bit flash A/D converter. The ADC was sampling a full-scale 828.75-kHz sine wave at 15 MHz. FFT plots graphically illustrate parameters such as S/N ratio and spurious-free dynamic range (SFDR).

## TESTING HIGH-SPEED A/D CONVERTERS

which is commonly derived from an FFT, provides a measure of dynamic resolution. To find the ENOB of an equivalent real ADC, the equation for S/N ratio is rearranged so that  $\text{ENOB} = (\text{S/N ratio} - 1.8)/6$ .

Using the data from the example FFT, with an S/N ratio of 44.1 dB, the effective number of bits would be approximately 7. One problem with this calculation is that all manufacturers do not use the same technique for measuring S/N ratio. Many measure the S/N ratio by first eliminating all harmonics and intermodulation products from the FFT. In such cases, the manufacturer should also report these distortion products separately.

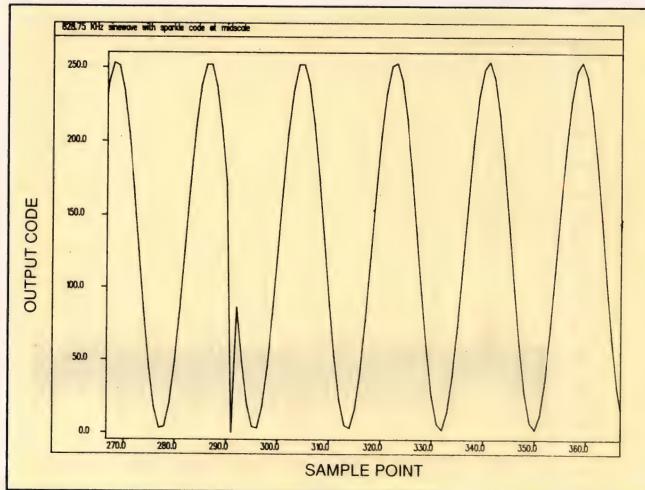
In the Fig 1 example, the S/N ratio without harmonics was 47 dB, which results in an effective bit calculation of 7.5. The problem exemplified by this erroneous 0.5-bit improvement is that the S/N ratio measurement doesn't reflect the actual resolution and accuracy of the individual samples taken by the ADC. If your interest is only in frequency-domain processing, the error may not matter; but if the accuracy of dynamic measurements is important, you'll want to include the harmonics and other spurious components in the ENOB calculation.

To show how severe the ENOB error can be when relying solely on the frequency domain, the data used to calculate the FFT in Fig 1 was edited to create a spurious code at one of the zero crossings in the data record. Fig 2 depicts a portion of the edited sine wave. Instead of producing the code 128, the data was changed to produce code 0. Such spurious codes often occur and are called sparkle codes. The high slew rate

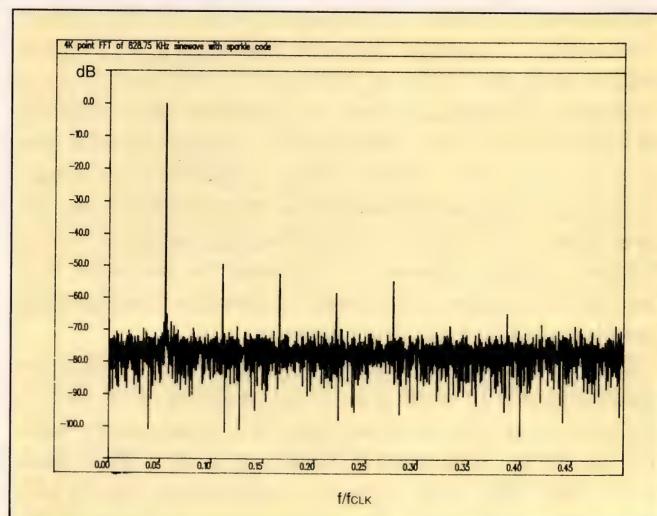
of the input signal near the mid-scale point of the waveform can cause problems in the encoding circuitry of some flash ADCs. These problems result in glitches in the digital output. Fig 3 shows the result of reproducing the 4k-point FFT with the corrupted data. The spectra differ very little. The signal-to-noise measurement of the Fig 3 spectrum indicates less than 2 dB of loss, which shows up as a slightly elevated noise floor. The SFDR did not change significantly, and the ENOB was reduced by only 0.3 bits.

Using a long data record, such as the 4k points in the example, is a common way to accurately measure an ADC's S/N ratio. An undesirable result of this method is that small numbers of large errors, such as the mid-scale glitch, are averaged out with no indication of the severity of the error in the frequency domain. Shorter FFTs can have other problems because the higher noise floor that results from taking fewer samples can mask many small coding errors. For this reason, multiple FFTs are often performed so that the spectra can be averaged together to remove random noise and clearly discriminate harmonics. Of course, this averaging further conceals information about sampling errors unless you examine the actual acquired data.

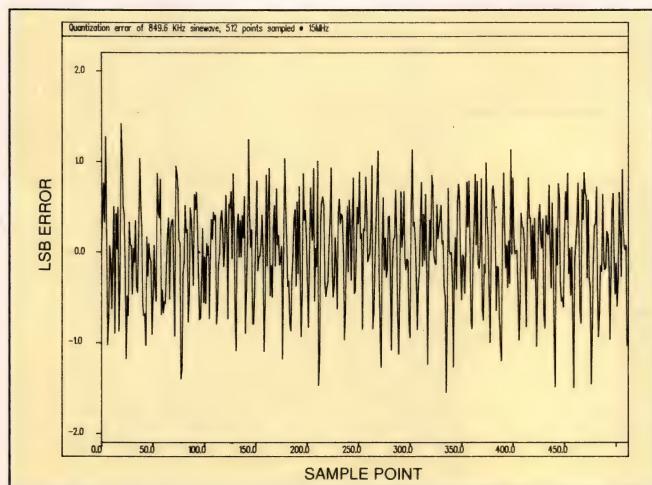
An alternative method of calculating effective bits is to use an algorithm that will find the sine wave that achieves the "best fit" to the data from the ADC (Ref 1). A sine-wave-fitting algorithm recursively calculates the amplitude, offset, and phase of an ideal sine wave that results in the minimum rms error when compared with the actual quantized waveform. Using the same



**Fig 2**—The data used to calculate the FFT in Fig 1 was edited to create a spurious code (code 0 instead of code 128) at one of the zero crossings in the data record. This plot depicts a portion of the edited sine wave, which exhibits corrupted data in the form of a sparkle code.



**Fig 3**—The result of reproducing the 4k-point FFT of Fig 1 using the corrupted data of Fig 2 shows very little difference when compared with the original. The main difference is the corrupted-data plot's slightly elevated noise floor.



**Fig 4—**This quantization-error plot of the flash ADC first tested in Fig 1 provides a graphical measurement of the time-domain errors under dynamic conditions. As is evident, the samples are generally within  $\pm 1$  bit of the ideal.

flash ADC tested in Fig 1, 512 data points were collected to produce an FFT and a best-fit sine wave. Subtracting the best-fit waveform from the original quantized data produced the dynamic-quantization-error plot of Fig 4. The plot provides a graphical measurement of time-domain errors under dynamic conditions.

As you can see, the samples were generally within  $\pm 1$  bit of the ideal, with worst-case errors of  $\pm 1.5$  bits. By including all of the nonlinearity and noise effects of the ADC, this method gives a true indication of the device's dynamic resolution. You should not confuse the dynamic-error plot with "dynamic linearity," which some manufacturers specify in their data sheets. Dynamic linearity is usually based on histogram techniques, which can hide time-domain errors. In contrast, looking directly at the quantization error plot, both large and small errors, which could be lost in an FFT or sine-wave histogram, are immediately evident.

The rms quantization error ( $V_e(rms)$ ) in Fig 4 is 0.55 bits. In an ideal ADC with a uniform distribution of all codes, the rms quantization error would be  $q/\sqrt{12}$ , where  $q$  is one quantization step, or LSB. This relationship leads to an alternative equation for effective bits:

$$V_e = \frac{V_{REF}}{2^{ENOB} \cdot \sqrt{12}}$$

$$ENOB = \log_2 \left( \frac{V_{REF}}{\sqrt{12} \cdot V_e(rms)} \right),$$

where  $V_{REF}$  is the full-scale range of the ADC.

Because this method includes all harmonics and spurious components, it is better for calculating the effective number of bits than the FFT-based technique. When you analyze data digitally, as in the quantization error plot of Fig 4, you can convert the equation for ENOB to units of bits rather than volts:

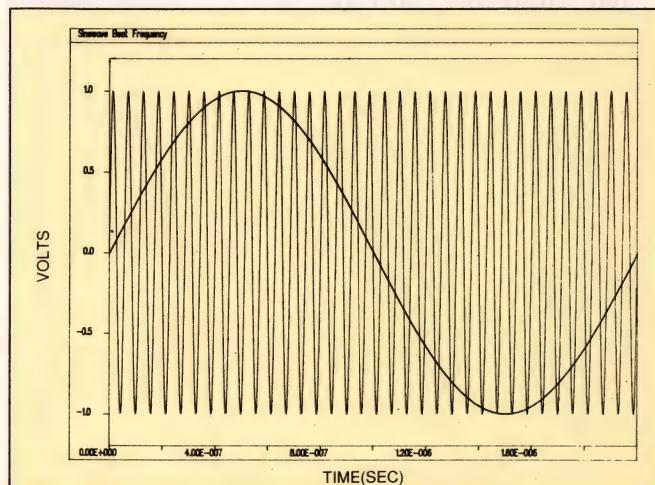
$$ENOB = \log_2 \left( \frac{\text{MAX CODE} - \text{MIN CODE}}{\sqrt{12} \cdot \text{rms BIT ERROR}} \right).$$

Converting to the more convenient base-10 logarithm yields

$$ENOB = 3.32 \cdot \log_{10} \left( \frac{\text{MAX CODE} - \text{MIN CODE}}{\sqrt{12} \cdot \text{rms BIT ERROR}} \right).$$

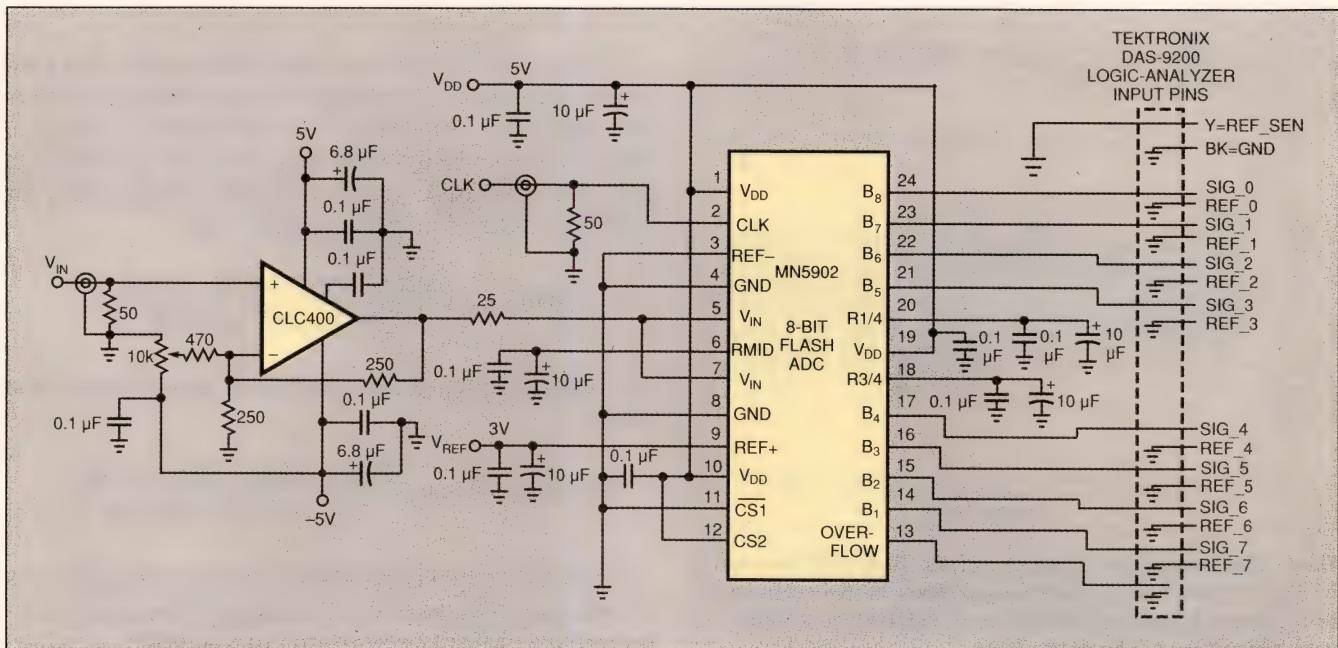
A disadvantage of sine-wave curve-fitting algorithms is that they may have long execution times and sometimes have difficulty converging to a solution. An alternative that is fast and can provide a quick graphical interpretation of performance, as well as supply data for more quantitative measurements, is the beat-frequency test. This test is the ultimate stress test of a flash A/D converter in the time domain. The beat-frequency test directly measures input signal bandwidth, reveals sampling errors that result in spurious or out-of-place codes, and provides a measure of aperture errors.

Designers familiar with sampling theory know that the Nyquist criterion requires that you sample a signal



**Fig 5—**This single-tone beat frequency is the result of using an input sine wave slightly higher in frequency than the sampling clock, and connecting the sampled data points in a continuous time record. To guarantee that you exercise all the codes, calculate the input frequency to produce a change of less than 1 bit in the beat tone at the maximum slewing point. This point is set at the mid-scale point of unipolar ADCs.

## TESTING HIGH-SPEED A/D CONVERTERS



**Fig 6—**You can use this test circuit to demonstrate the ADC beat-frequency measurements Figs 7 through 10 show.

at a rate greater than twice the signal's highest frequency component. Signals that do not adhere to this limitation result in "aliases." Aliases are the result of high-frequency signals at an ADC's input that are transferred to lower-frequency signals within the output bandwidth of one half the sampling rate. Beat-frequency testing exploits this phenomenon by deliberately producing low-frequency representations of high-frequency signals.

You should note that many flash A/D converters are

specified for a "full-power bandwidth" that is less than the Nyquist rate. Often this specification describes the point where gross errors occur on the ADC's output.

During a beat-frequency test, the ADC digitizes input signals that are multiples of the sampling rate. If you use an input sine wave just slightly higher in frequency than the sampling clock, the sampling point will change in relative phase at a rate equal to the difference in frequency between the two signals. By connecting the sampled data points in a continuous time record, the single-tone beat frequency is traced out as Fig 5 shows. To guarantee that you exercise all the codes, calculate the input frequency to produce a change of less than one bit in the beat tone at the maximum slewing point. This point is set to the mid-scale point of unipolar ADCs. The calculation is

$$\frac{dV_{IN}}{dt}(\text{MAX}) = 2\pi \cdot A \cdot f_{BEAT}$$

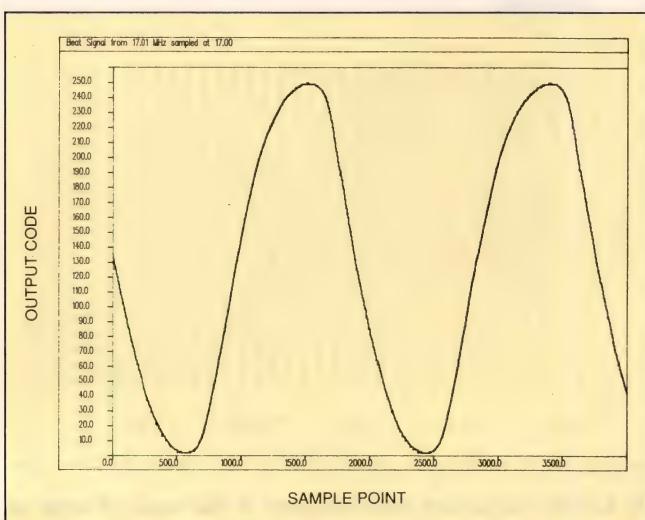
Set A to half the full-scale range of the ADC, which is \$V\_{REF}/2\$ for a unipolar converter. For a change of one bit per sample at the maximum slewing point:

$$\frac{dV_{IN}}{dt} = \frac{2\pi \cdot V_{REF} \cdot f_{BEAT}}{2}$$

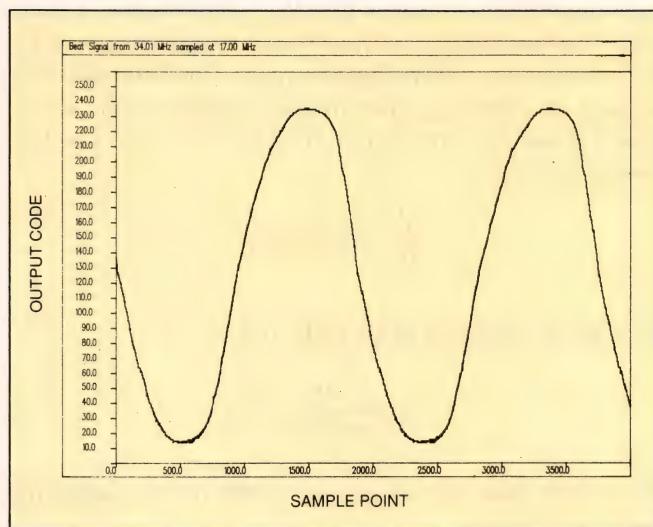
$$\text{and } f_{IN} = \frac{f_{CLK}}{2^N \cdot \pi} + x \cdot f_{CLK},$$

where x is an integer.

To demonstrate the technique, a series of beat-

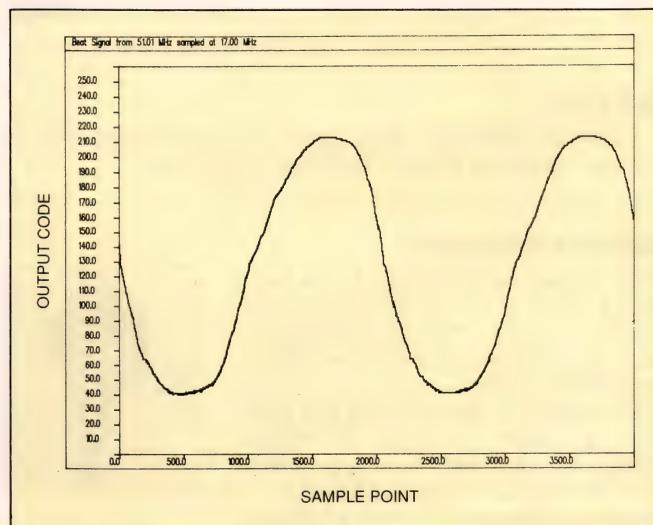


**Fig 7—**This plot shows the 10-kHz beat-frequency results of digitizing a full-scale input at 17.01 MHz with the ADC sampling at 17.00 MHz. The peak-to-peak amplitude of the output code is -0.275 dB relative to full scale, and the beat waveform shows no evidence of spurious codes.

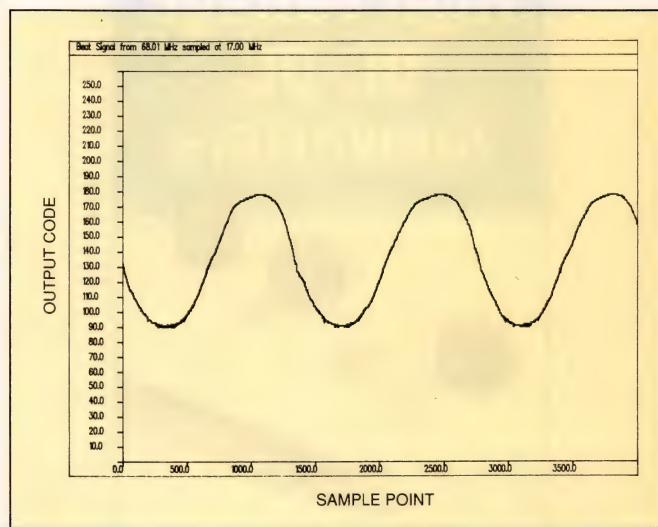


**Fig 8**—In this test, the input frequency was doubled to 34.01 MHz while the sampling rate was kept at 17.00 MHz. Again, the plot shows a 10-kHz beat, but with a peak-to-peak attenuation of 1.24 dB.

frequency tests were performed using the MN5902 CMOS flash ADC in the test circuit of Fig 6. The beat tests started by digitizing a full-scale input ( $f_{IN}$ ) of 17.01 MHz with the ADC sampling at a 17.00-MHz clock rate ( $f_{CLK}$ ). This test produced the 10-kHz beat frequency evident in the Fig 7 plot of digital output codes. In this plot, the horizontal axis represents the number of data points, and the vertical axis represents the 8-bit code. The peak-to-peak output-code amplitude was  $-0.275$  dB relative to full scale. An examination of the beat waveform shows no evidence of spurious codes.



**Fig 9**—In this third test, the input frequency of 51.01 MHz is three times the clock rate. Under these conditions, there were still no spurious codes present, and the peak-to-peak output was attenuated by 3.4 dB. The attenuation of the beat frequency gives an accurate indication of the overall  $-3$ -dB bandwidth of the composite sampling system.



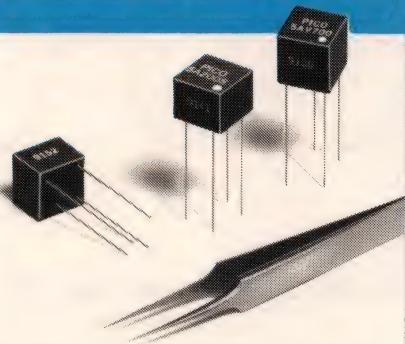
**Fig 10**—In this final test, the input frequency of 68.01 MHz is four times the sampling rate. The frequency increase attenuated the output amplitude by 9.28 dB but generated no sparkle codes.

You can also derive the beat waveform from signals that are offset in frequency from harmonics of the sampling rate. In the second test, which Fig 8 shows, the input frequency was doubled to 34.01 MHz while the sampling rate was kept the same. Once again the 10-kHz beat was obtained, with a peak-to-peak attenuation of 1.24 dB. In the third test, which Fig 9 shows, the input frequency is increased to three times the clock rate for an input of 51.01 MHz. Under these conditions, no spurious codes were present, and the peak-to-peak output was attenuated  $-3.4$  dB. Although these results include effects caused by the large-signal-bandwidth roll-off from the input-signal amplifier, attenuation in the beat frequency gives an accurate indication of the overall  $-3$ -dB bandwidth of the composite sampling system.

Finally, in Fig 10, the input frequency was increased to 68.01 MHz, or four times the sampling rate. This increase reduced the output amplitude by 9.20 dB but did not result in any sparkle codes. Although you may observe increased distortion as you approach an ADC's performance limits, it is more important to users that a device degrades gracefully and has no abrupt onset of gross sampling errors. If more accurate measurements are required under extreme undersampling conditions, you can lock the two signal sources to a common reference to reduce phase jitter, which can corrupt the low-frequency beat. No attempt to do so was made for the tests described here.

You can use the extremes of input frequency to measure the margin of aperture uncertainty a flash ADC is capable of providing. If there is a small variation in the sampling point of the ADC's adjacent comparators, high-frequency signals will slew through mul-

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multiple quantization levels while the circuit makes a decision. The resulting ambiguity can cause large errors in the encoding of the digital output. To determine the amount of sampling aperture uncertainty that would produce coding errors greater than 1 bit, use the following equation:

$$\frac{dV}{dt} = 2\pi \cdot A \cdot f_{IN}$$

To scale in fractions of an LSB, use

$$dt = \frac{dV}{\pi \cdot 2^N \cdot f_{IN}}$$

For a full-scale signal and an error in the sampling voltage of 1 bit:

$$dt(\text{MAX}) = \frac{1}{\pi \cdot 2^N \cdot f_{IN}}$$

As an example, for the Fig 9 input signal of 51.01 MHz with an effective attenuation of -3 dB, the aperture uncertainty is less than 35 psec.

In addition to providing an immediate indication of large-signal bandwidth and sparkle immunity, sine-wave beat signals can be used to perform the other dynamic tests previously described. For example, you can use sine-wave-fitting algorithms to measure the quantization error of the beat waveforms. You can perform FFTs if you take aliasing into account and provide any required bandpass filtering at the input.

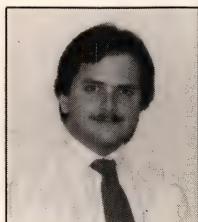
EDN

## Reference

1. Demler, Michael J., *High-Speed Analog-to-Digital Conversion*, Academic Press, San Diego, CA, 1991.

## Author's biography

Mike Demler has been with Micro Networks (Worcester, MA) for three years and is the manager of monolithic design engineering. Mike, who has been instrumental in the design of 6- and 8-bit flash A/D converters, also develops test systems for dynamic analysis. He holds a BSEE from the State University of New York at Buffalo and an MSEE from Southern Methodist University (Dallas, TX). In his leisure time, Mike enjoys home remodeling, photography, and sports.



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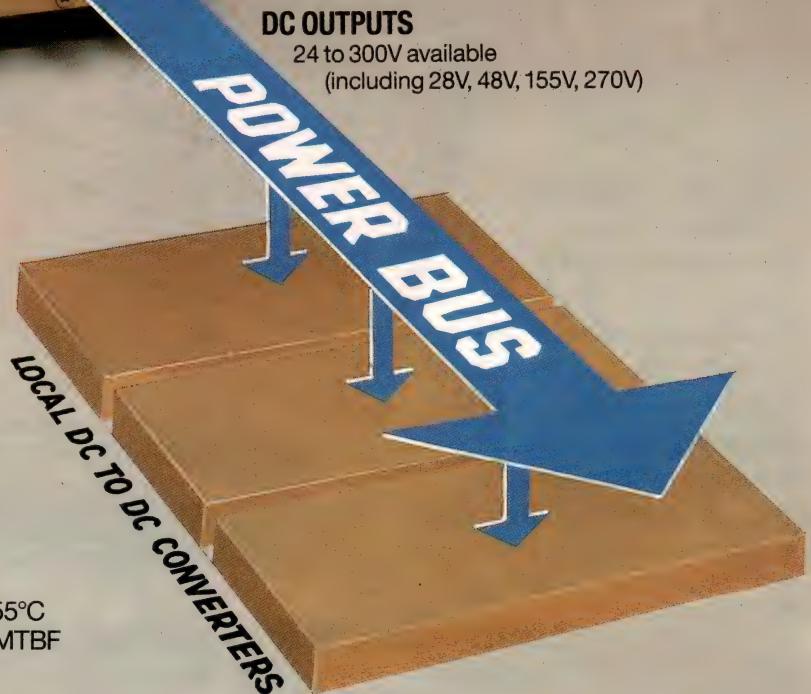


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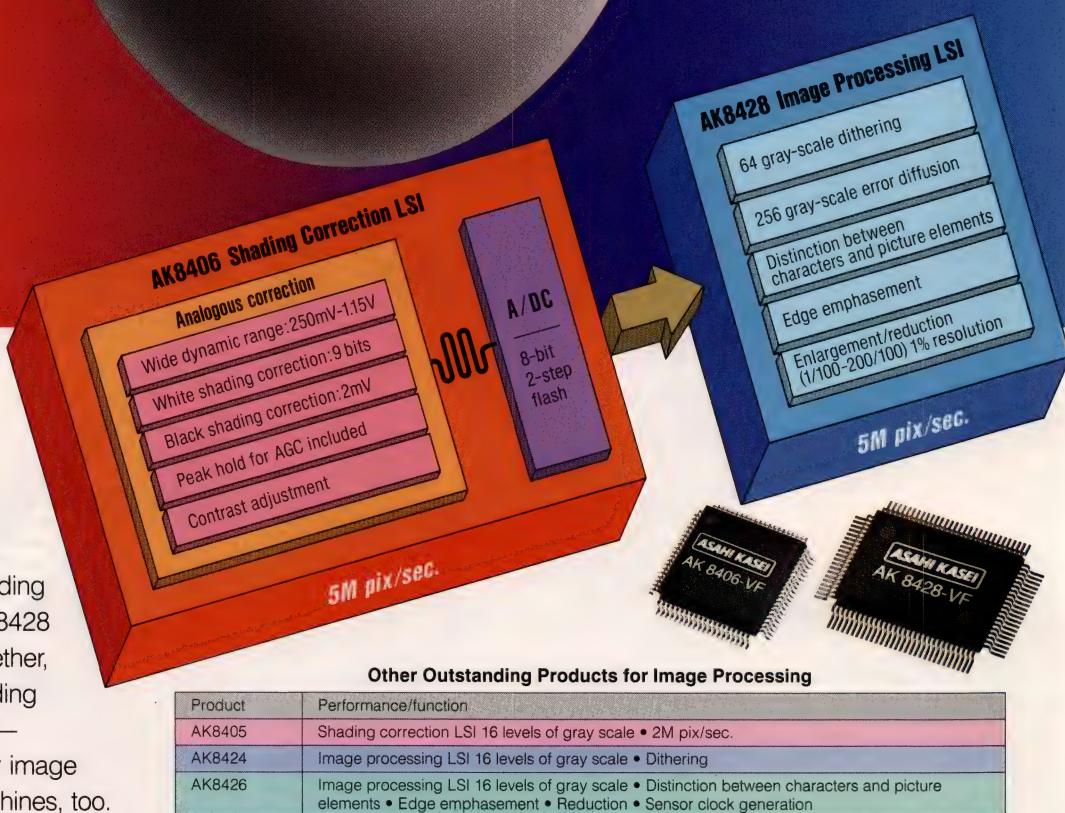
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# Use the analytic approach to avoid errors when probing CMOS circuits

Art Porter, Hewlett-Packard Co

*Heisenberg's uncertainty principle states that you can't measure a physical event without somehow affecting that event. This principle holds true for CMOS circuits, but armed with the right analytical techniques you can render those effects immaterial.*

When you're making measurements on CMOS circuitry, you must take probe characteristics into consideration. Probe resistance and probe capacitance can affect voltage measurements as well as the accuracy of delay-time measurements. However, using the right techniques can help you overcome these problems.

To understand how a probe's characteristics can affect measurements, you must look inside the device you're measuring. The output circuitry of any CMOS device consists of one or more FETs tied to the positive supply rail and one or more FETs tied to ground (Fig 1a.) In the high output state, the FETs connecting the gate's output pin to the power supply are turned on hard; in the low state, the FETs between the output and ground are turned on hard.

When you consider the addition of a pull-up resistor and add the resistance of the probe, the output circuit looks like Fig 1b. The first thing you'll want to know is how the dc voltage levels at the output node will change due to probe resistance.

In the low output state, no current will flow through the probe resistance because there is no voltage across it. Thus, you need only consider the high state. To

analyze the high-output voltage level, you need to understand the characteristics of a CMOS output. Fig 2 reproduces published high-level voltage vs current (E/I) characteristics for various CMOS devices.

The plot in Fig 2a depicts the output characteristics for a family of CMOS logic from Integrated Device Technology (IDT). The output E/I slope corresponds to an equivalent resistance of approximately  $25\Omega$  as long as the current does not exceed 100 mA. This impedance is the equivalent on-resistance of the on-chip FET between the gate's output pin and the positive power-supply rail. This output impedance is much smaller than any reasonable pull-up resistor you might design into a circuit using this FET, so you only need

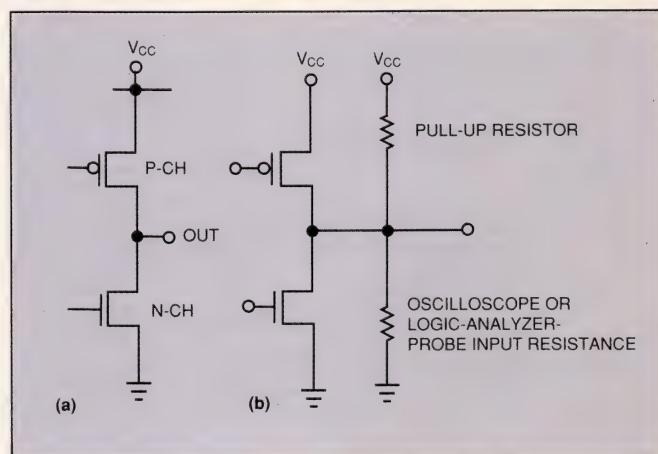


Fig 1—You can understand the effects of probe resistance on measurement accuracy best when you look at the output circuitry of CMOS devices (a). Addition of the probe resistance (b) creates a resistive divider and introduces error into level measurements.

## PROBING CMOS CIRCUITS

to consider the circuit, which consists of the FET's on-channel resistance and the probe resistance.

**Fig 2b** illustrates how the IDT FET's output voltage will vary as a function of the probe resistance when the supply voltage equals 5V. A 1-k $\Omega$  probe represents a 5-mA load on the output.

The same concepts apply to devices with steeper E/I output curves. For example, Cypress' CY7C909/CY7C911 microprogram sequencers have an output E/I slope (**Fig 2c**) that is very nearly linear and has an equivalent resistance of approximately 100 $\Omega$ . For these devices, **Fig 2d** illustrates how the high output level will react as a function of probe resistance.

These examples make one significant point—when the gate is in the active-high state, the effect of a probe's resistive loading depends on the on-channel resistance of the output-stage FET rather than on the value of the external pull-up resistor. These examples illustrate that an understanding of an IC's high-output-state E/I characteristics can be useful when deciding what measurement probe to use. In general, a probe resistance of 100 k $\Omega$  is adequate for virtually all types of CMOS circuitry, and some circuits can tolerate 1-k $\Omega$  resistive loads.

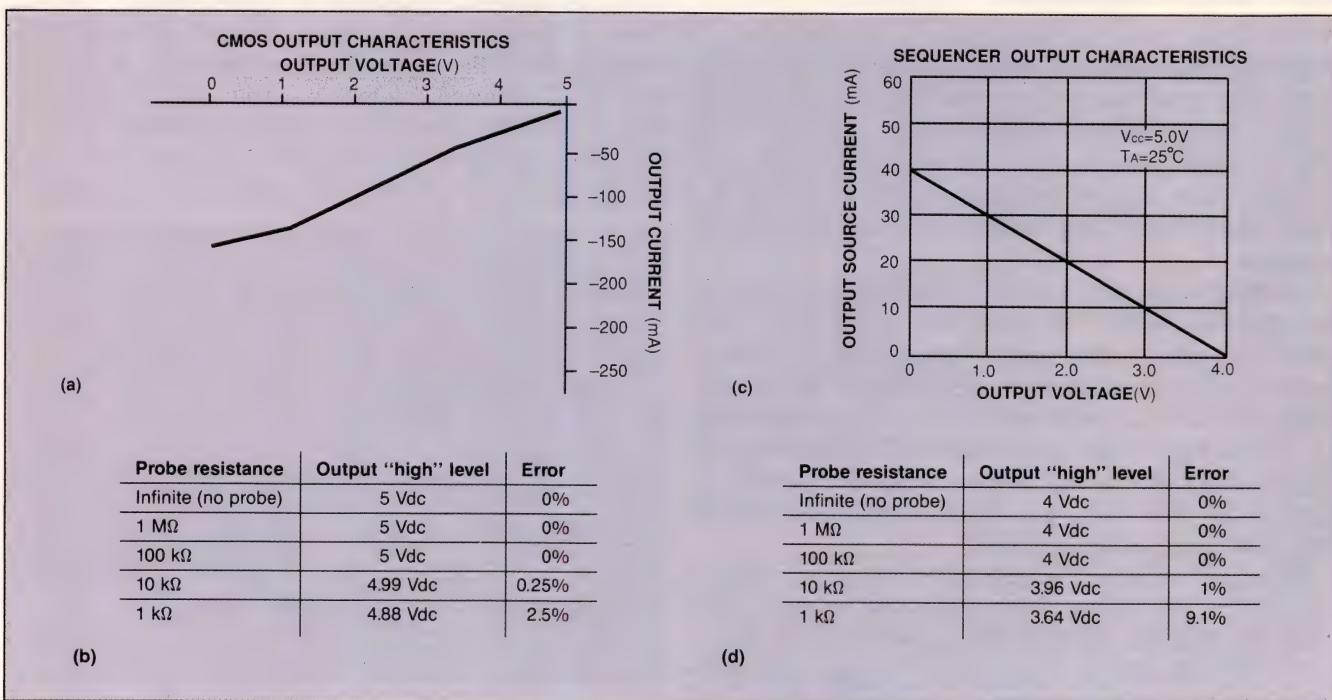
A probe's capacitance affects the accuracy of timing measurements. To change the output level from low to high or high to low, an IC's output stage must

source or sink current to charge or discharge the capacitive load. This load includes the capacitance of the probe, the input capacitance of any gates connected to the IC's output, and any parasitic capacitance associated with the pc board or other fixtures. Altering the charge on this capacitance takes a finite amount of time—it is not instantaneous.

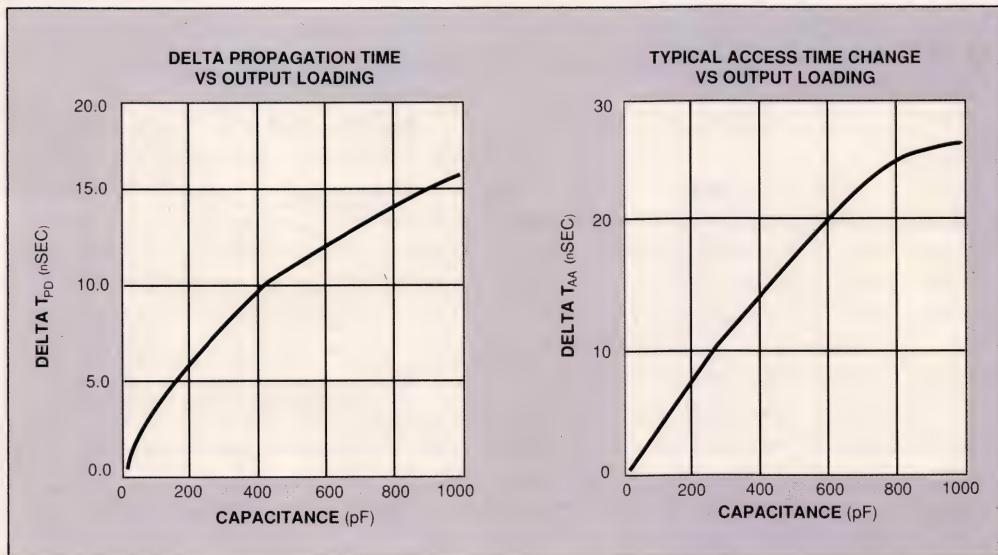
Some CMOS-device data sheets provide information on how propagation delays change with load capacitance. For example, **Fig 3** shows delay curves for the Cypress CY7C150 static RAM. For this device, a probe with a load capacitance of 8 pF will change the output-edge timing by about 0.4 nsec.

For vital timing measurements on very-high-speed CMOS circuitry (transition times of approximately 1 nsec), the probe capacitance can become critical. In these cases, choose the probe type with the lowest capacitance. A passive resistive-divider probe, designed to be terminated into 50 $\Omega$ , has the lowest capacitance (see box, "A probing primer"). A 20:1 resistive-divider probe designed for a 50 $\Omega$  termination will present an input resistance of 1 k $\Omega$  to the circuit under test. High-speed CMOS circuits are typically designed to have a relatively low on-channel resistance and can provide relatively high currents, so a 1-k $\Omega$  probe will introduce minimal voltage errors.

Probe resistance is not a significant factor in making



**Fig 2**—To analyze high-output voltage levels, you must look to the output characteristics of CMOS logic (a). The FET's output voltage will vary as a function of probe resistance (b). For CMOS devices with steeper I/O characteristics (c), the effects of probe loading are more pronounced (d).



**Fig 3—Propagation delay and access time both increase as the load capacitance increases. To minimize problems, always choose the probe with the lowest capacitance.**

accurate voltage-level measurements on CMOS circuits as long as the outputs are in an active-high or an active-low state. However, high-Z measurements can be problematic. Measuring the time it takes for a device's output to go into the high-Z state after its output-enable pin is negated can be difficult. It's even tougher to make a measurement when you suspect that some device's output is trying to drive a bus high or low when the bus should be in the high-Z state. Having several drivers connected to a bus makes it very tough to find the culprit.

The output impedance of a device should be infinite when it is in the high-Z state, so you might guess that you need a very-high-resistance scope probe to detect this state. You might at least assume that the resistance of the scope probe should be many times larger than that of the node's pull-up resistor. Neither of these assumptions is correct.

To approach this measurement, think about what it means for an output to be in the high-Z state and how the circuit behaves. When a logic output is in the high-Z state, no current should be flowing. Other components connected to the output node will therefore determine the voltage at the device's output pin. These components include the pull-up resistor, other device inputs or active outputs connected to the same node, and the capacitances of the pc-board trace and the components attached to the circuit node.

When all outputs on a circuit node are in the high-Z state, the voltage at that node will change only if the charge on the node's load capacitance changes. With all outputs in a high-Z state, the only current source available to alter the charge on the node's load capacitance is the pull-up resistor, if one is connected. The rate of voltage change will therefore be set by the

node's time constant, which equals the load capacitance value times the pull-up resistor's value. Typical CMOS devices have an input capacitance of 4 to 10 pF. Circuit-board traces can add several pF. For a bus with several devices connected to it, the total capacitive load might be on the order of 100 pF. For a 10-kΩ pull-up resistor and a 100-pF load capacitance, the time constant is 1 μsec.

Thus, when a device's output enters the high-Z state, we would not expect to see the output voltage level change significantly for tens or hundreds of nanoseconds. Of course, if the output were at a "high" level before going to the high-Z state, we would not expect the output level to change at all because the voltage is already as high as it can go. Therefore, voltage measurements will not tell you whether a device is really in the high-Z state or how long it takes to reach that state, regardless of the probe's resistance.

The best way to determine whether a particular device is trying to drive the bus either high or low is to measure the current in the device's output pin using a current probe and an oscilloscope. No current should flow through the device's output pin in either direction when the device is in the high-Z state. Make sure you select a current probe and oscilloscope with adequate bandwidth for this task (5 to 10× wider than the circuit's bandwidth).

Because the current probe introduces an unknown time delay, you should first de-skew the current probe and the voltage probe. Connect the equipment as shown in Fig 4a. Some digital oscilloscopes have internal de-skewing capabilities. If the scope you are using doesn't have the capability to automatically de-skew channels, record the amount of delay between the two

*Text continued on pg 125*

## A probing primer

Any time you connect a scope or logic-analyzer probe to a circuit, the probe becomes a part of the circuit under test and the probe's transfer function affects the overall measurement system's response. These probe effects will degrade measurement accuracy because the new circuit including the probe will behave differently from the circuit without the probe. But you cannot eliminate the probe's effect.

The probe contributes resistive and capacitive loading effects. Inductance in the probe's ground lead can also affect measurements. The probe's resistance to ground forms a divider network in conjunction with the source resistance of the circuit under test (**Fig A**), decreasing the signal amplitude and also reducing the dc offset. If the probe's resistance is nine times greater than the Thevenin-equivalent output resistance of the circuit under test, attaching the probe will reduce the output-signal amplitude by approximately 10%. In general, the frequency-independent amplitude errors and dc offset errors introduced by a probe's resistive loading are approximately proportional to the ratio of the probe's resistance to ground and the equivalent output resistance of the circuit under test.

The probe's tip capacitance (in parallel with the probe resistance) forms an RC circuit with the output resistance of the circuit under test. The RC circuit's time constant will slow the rise time of any signal transitions, increase the slew rate, and introduce delay in the actual time the transitions occur. As a rule of thumb, the rise time of a simple RC circuit is approximately  $2.2 \text{ RC}$ . Thus, for an output resistance of  $100\Omega$  and an  $8\text{-pF}$  probe tip capacitance, the real rise time at the node under test cannot be faster than about 1.8 nsec.

If the output of the circuit under

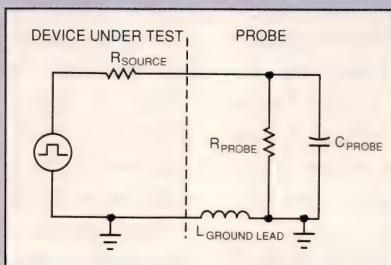
test is current limited (as is often the case for CMOS), the slew rate will be limited by the relationship

$$\frac{dV}{dt} = I/C.$$

The inductance of the probe ground lead forms an LC circuit with the probe's capacitance and the output capacitance of the circuit under test, (including any parasitic capacitance of pc-board traces and other stray capacitances). As a handy rule of thumb, a probe's ground wire has an inductance of about  $25\text{ nH}$  per inch. Neglecting circuit capacitance, a probe with a tip capacitance of  $8\text{ pF}$  and a 4-in. ground wire will have a ringing frequency of approximately  $178\text{ MHz}$ . Therefore, a signal with a rise time of less than 1.9 nsec may stimulate ringing.

### A look at system bandwidth

To obtain error-free time-interval measurements, the bandwidth of the combined oscilloscope-and-probe system must be wide enough to accurately reproduce the circuit's signal. If you use a scope-probe combination that has a combined rise time of 1 nsec to measure a signal with a 1-nsec rise time, the approximate measured rise time will be 1.41 nsec. This answer is in error by 41%. If you use a scope-probe combination with a system rise time of 330 psec to measure the same



**The amplitude of the output signal and the value of dc offset will both decrease because the probe resistance forms a divider network with the source resistance of the device under test.**

1-nsec actual rise time, the indicated rise time will be approximately 1.05 nsec—an error of only 5%.

You may find it useful to memorize three rules of thumb. First, the combined system rise time (oscilloscope and probe) should be less than  $\frac{1}{3}$  of the rise time of the signal you're measuring to keep errors below 5% and less than  $\frac{1}{2}$  of the rise time of the signal you're measuring to keep errors below 1%. Second, rise time and bandwidth are related by the following approximations:

$$\text{Rise time} \approx 0.35/\text{Bandwidth}$$

and

$$\text{Bandwidth} \approx 0.35/\text{Rise time}.$$

Finally, rise times add approximately as the square root of the sum of the squares.

For example, if the oscilloscope and the probe each have a 1-GHz bandwidth, the combined bandwidth is approximately 707 MHz and the combined rise time is roughly 495 psec. Therefore this combination could be used confidently to measure actual signal rise times of 1.5 nsec with a less than 5% error or 3.5 nsec with a less than 1% error.

Oscilloscope probes are available in three common types: low-impedance resistive-divider probes; compensated, high-resistance passive-divider probes; and active probes. Resistive-divider probes are designed for scopes with a  $50\Omega$  input impedance. The probe tip consists of a  $450\Omega$  or  $950\Omega$  series resistor. The probe's cable is a  $50\Omega$  transmission line. Because the cable is terminated by  $50\Omega$  at the scope input, it appears as a purely resistive  $50\Omega$  load at the probe's tip. Therefore the resistive divider is flat over a wide range of frequencies, limited primarily by the

parasitic capacitance and inductance of the  $450\Omega$  or  $950\Omega$  resistor and the fixture that holds it. The resistive-divider probe has the lowest capacitive loading. Its low capacitance and inherent wide bandwidth of several GHz make the resistive-divider probe the best choice for wide-bandwidth measurements or measurements where timing is the most critical parameter.

Relatively heavy resistive loading is a drawback of the resistive-divider probe. Not all circuits can drive  $500\Omega$  or  $1\text{ k}\Omega$ . Even for measurements in a relatively low-impedance circuit, the amplitude errors caused by a resistive-divider probe may be significant. When using this type of probe, keep in mind that the probe may cause changes in bias levels or operating currents that can cause the circuit's behavior to change.

Compensated passive-divider probes are the most common type of scope probe. Most logic ana-

lyzer probes also use this same general design. The  $900\text{-k}\Omega$  resistor in the probe tip forms a 10:1 voltage divider with a  $100\text{-k}\Omega$  resistor located at the other end of the probe cable. Some probe designs put a  $9\text{-M}\Omega$  resistor at the probe's tip, and the scope's  $1\text{-M}\Omega$  input resistance forms the other part of the voltage divider. To achieve a flat frequency response, the voltage divider must include compensation for the capacitance of the cable and for the scope (or analyzer) input capacitance. Because the input capacitance of the scope is unknown, one of the compensating capacitors should be adjustable so you can optimize the step-response flatness.

The compensated passive-divider probe has the highest input resistance of any probe type. However, it also has the highest capacitive loading and the lowest bandwidth. At 2 MHz, an 8-pF capacitance has a  $10\text{-k}\Omega$  impedance and at 100 MHz it is only  $200\Omega$ . Com-

pensated passive-divider probes are often referred to as high-impedance probes. This is a misnomer because these probes exhibit high input impedances only at relatively low frequencies.

An active probe has a buffer amplifier at its tip. This buffer amplifier drives a  $50\Omega$  cable terminated by  $50\Omega$  at the scope's input. Active probes offer the best overall combination of resistive loading, capacitive loading, and bandwidth, even though they don't have the highest resistance, the highest bandwidth, or the lowest capacitance available. The disadvantages of active probes are relatively high cost, relatively large tip size, a somewhat limited dynamic input range, and greater susceptibility to damage. You should handle them with care.

The perfect probe doesn't exist, so you must exercise some discretion when choosing the best type for each measurement. To make this choice, you must know the equivalent circuit for the circuit you're going to test, the approximate bandwidth or spectral content of the signal you'll be measuring, and the characteristic (voltage or time) you want to measure most accurately. Logic analyzers generally don't give you a choice of probes. Logic-analyzer probes are usually designed to be used with a particular analyzer. The **table** lists some characteristics of representative oscilloscope and logic-analyzer probes.

However, you still need to understand the effect of the probes on the measurement. The examples above used a simple resistance as the equivalent circuit for the circuit under test. For actual cases, you need a more complete model to understand the probe's effects. For truly demanding measurements you may find it worthwhile to simulate the effect of the probe using SPICE.

**Table A—Probe characteristics**

Manufacturer	Model number	Resistance	Capacitance	Bandwidth
<b>Resistive-divider probes</b>				
Hewlett-Packard	54006A	$1\text{ k}\Omega$ , $500\Omega$	0.25 pF	6 GHz
Tektronix	P6150	$500\Omega$	0.15 pF	9 GHz
<b>Compensated passive-divider probes</b>				
Hewlett-Packard	1043A 10432A	$1\text{ M}\Omega$ $10\text{ M}\Omega$	6.5 pF 7.5 pF	500 MHz 300 MHz
Tektronix	P6137 P6562	$10\text{ M}\Omega$ $10\text{ M}\Omega$	10.8 pF 10.3 pF	400 MHz 350 MHz
Fluke/Philips	PM8929/391	$10\text{ M}\Omega$	12 pF	325 MHz
<b>Active probes</b>				
Hewlett-Packard	54001A 54701A	$100\text{ k}\Omega$ $100\text{ k}\Omega$	2 pF 0.6 pF	1 GHz 2.5 GHz
Tektronix	P6203 P6204 P6205	$10\text{ M}\Omega$ $10\text{ M}\Omega$ $1\text{ M}\Omega$	2 pF 1.9 pF 2 pF	1 GHz 1 GHz 750 MHz
Fluke/Philips	PM8943Q	$1\text{ M}\Omega$	3.5 pF	650 MHz
<b>Logic-analyzer probes</b>				
Hewlett-Packard	1650B, 16510B 16515A, 16516A	$100\text{ k}\Omega$ $10\text{ k}\Omega$	8 pF 3 pF	NA NA
Tektronix	1230 Prism 30HSM	$1\text{ M}\Omega$ $165\text{ k}\Omega$	8 pF 11 pF	NA NA
Fluke/Philips	PM3580	$200\text{ k}\Omega$	7 pF	NA

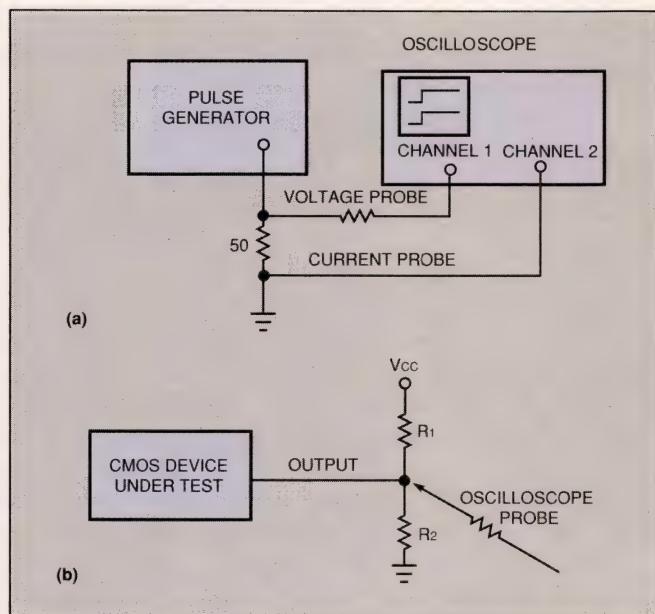
NA=Not applicable.

## PROBING CMOS CIRCUITS

channels and subtract that amount from subsequent measurements.

If you don't have a current probe, you can use an alternate method to measure the time required by a device to achieve the high-Z state after its output-enable pin is negated. Construct a relatively small-value resistive divider connected to the output as shown in Fig 4b. The combined parallel value of the divider resistors should be less than  $\frac{1}{10}$  of the probe's resistance. For example, for a 100-k $\Omega$  probe, the equivalent resistance of the divider should be less than 10 k $\Omega$ , so each divider resistor should be 20 k $\Omega$  or smaller. If you plan to use a 1-k $\Omega$  resistive divider probe, use the probe as one of the divider resistors ( $R_2$  in Fig 4b), and a 1-k $\Omega$  resistor for the other half of the divider.

Using this resistive-divider probe, you will measure an output level of  $V_{cc}/2$  when the device's output is in the high-Z state. When the output is not in the high-Z state, you will measure the normal high- or low-output levels. Using a normal probe, you can then connect another oscilloscope channel to the device's output-enable input to measure the delay between ne-



**Fig 4—**To account for probe time-delay characteristics when making high-Z-state measurements, you should de-skew the scope's current and voltage probes by adjusting the scope controls until the edges on channels 1 and 2 are coincident (a). When you don't have a current probe, you can use a resistive divider (b) to verify high-Z output-state conditions.

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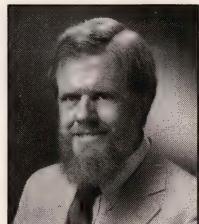
gation of the output-enable pin and the transition to the high-Z state. This technique will not identify the offending device in cases of bus contention. Any device driving the node will force the bus line to either the high or low state. You can only use the resistive-divider technique for verifying the delay between the negation of the output-enable pin and the onset of the high-Z state. You still need a current probe to trace bus-contention problems.

EDN

## Author's biography

**Art Porter** is a product marketing engineer at Hewlett-Packard Co (Colorado Springs, CO). He is currently involved with research and development activities in the planning of new products.

During his 29 years at Hewlett-Packard, Art has worked on the development of several oscilloscope product lines. In his spare time, Art enjoys photography, rock climbing, and cross-country skiing.



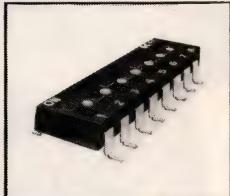
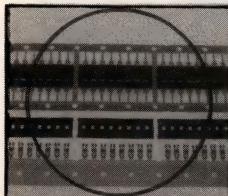
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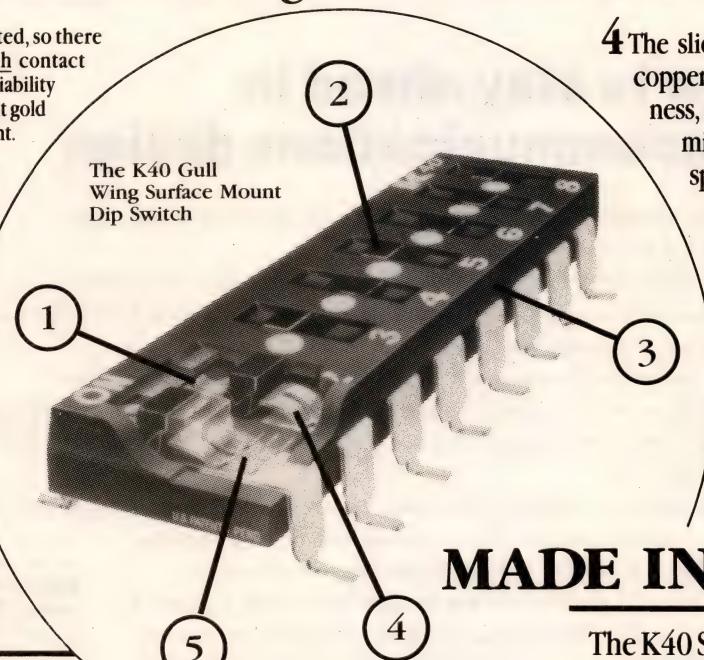
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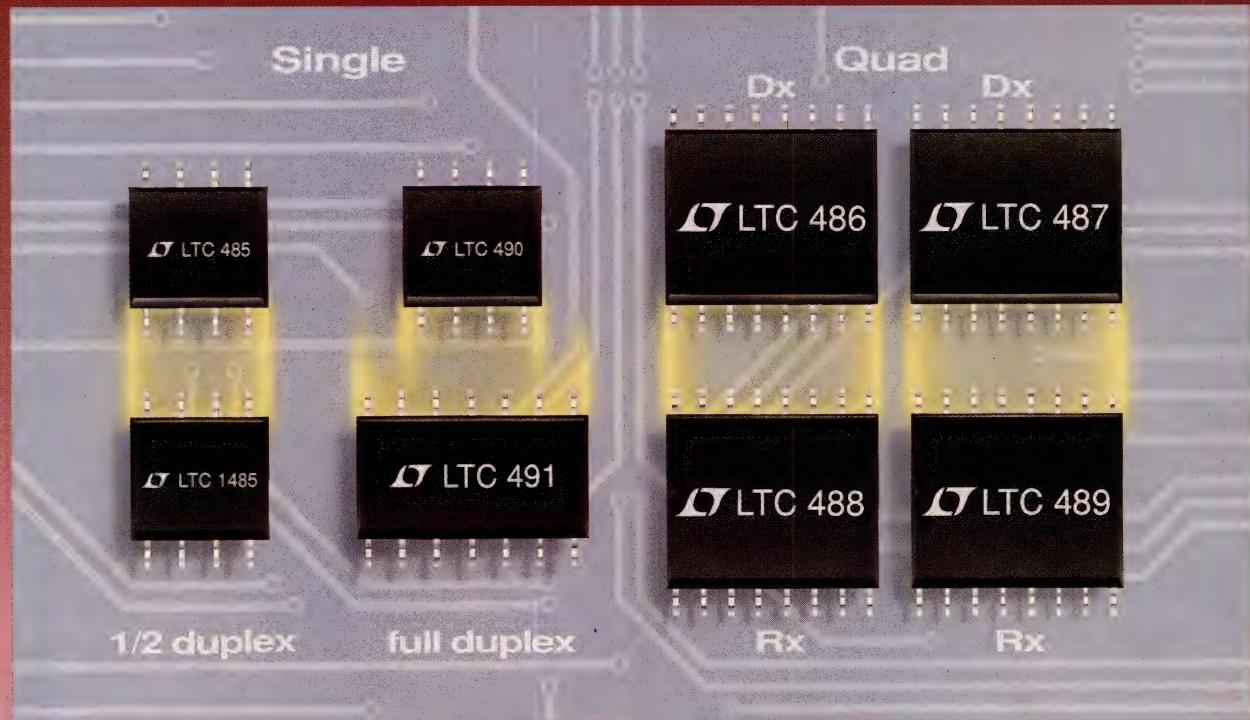
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LTC486	10Mbs Quad Driver	400X Lower	150 $\mu$ A	75172
LTC487	10Mbs Quad Driver	400X Lower	150 $\mu$ A	75174
LTC488	10Mbs Quad Receiver	7X Lower	10mA	75173
LTC489	10Mbs Quad Receiver	7X Lower	10mA	75175
LTC490	Full Duplex Transceiver	140X Lower	500 $\mu$ A	75179B
LTC491	Full Duplex Transceiver	60X Lower	500 $\mu$ A	75ALS180
LTC1485	10 Mbs Half Duplex Transceiver	8X Lower	3.5mA	75ALS176B

LTC490/491 are full duplex versions of the LTC485, containing a single driver and receiver. Power dissipation is the same as the LTC485 — a mere 2.5 milliwatts. The LTC1485 is a true 10Mbs version of the LTC485 with only 17.5 milliwatts of power consumption.

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## **CMOS logic creates precision waveforms**

**Michael A Wyatt, Honeywell SSO, Clearwater, FL**

The circuit in Fig 1 generates three different waveforms having frequencies less than 1 Hz: triangle waves, positive ramps, and negative ramps. At very low output frequencies, the stability of the circuit's input frequencies almost completely determines the output waveform's linearity.

XOR gate IC<sub>3</sub> beats input frequency  $f_{IN}$  against reference frequency  $f_{REF}$ , thus producing a train of pulses whose periods increase gradually until the frequency sources are completely out of phase. Then, the pulses' periods decrease until the sources are again in phase. Flip-flops IC<sub>1A</sub> and IC<sub>1B</sub> produce 50% duty-cycle inputs for XOR gate IC<sub>3</sub>.

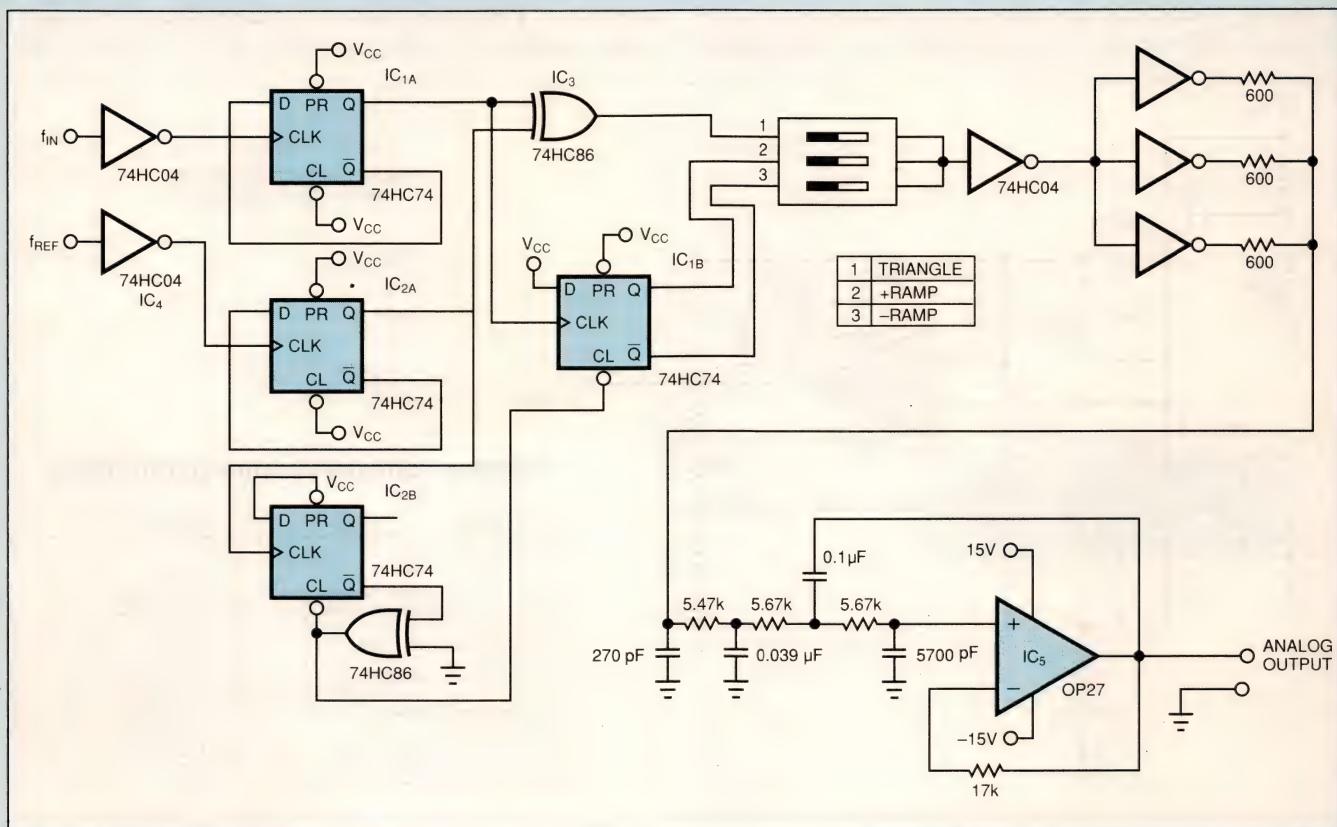
IC<sub>5</sub> and its surrounding components form a third-order, lowpass filter ( $f_c = 1$  kHz). The filter averages the output of pulse buffer IC<sub>4</sub> to produce a triangle waveform having a peak amplitude of V<sub>cc</sub> and a frequency of  $|f_{IN} - f_{REF}| \div 2$ . Be sure to select low-dielectric-absorption capacitors for the filter circuit.

The circuit generates ramp waveforms in a similar manner except that the SR flip-flop phase comparator formed by IC<sub>2A</sub> and IC<sub>2B</sub> replaces the XOR gate. The phase comparator sets on every other negative transition of  $f_{IN}$  and subsequently resets on every other negative transition of  $f_{REF}$ . If  $f_{IN}$ 's frequency is greater than  $f_{REF}$ 's, then the width of IC<sub>2B</sub>'s Q output pulse will gradually increase. This increase produces a positive-going ramp at the circuit's output. If  $f_{IN}$ 's frequency is less than  $f_{REF}$ 's, the output will be a negative-going ramp. Note that the filter's step response controls the ramp's reset time. Selecting a frequency greater than 100 kHz for  $f_{IN}$  and  $f_{REF}$  attenuates the pulse's ripple, which relaxes the reset-time restrictions.

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**Fig 1**—By beating two high-frequency input-pulse frequencies against each other and then integrating the resulting beat-frequency pulse train, this circuit produces low-frequency analog waveforms having good linearity.

# Voltage-reference circuit boasts low noise

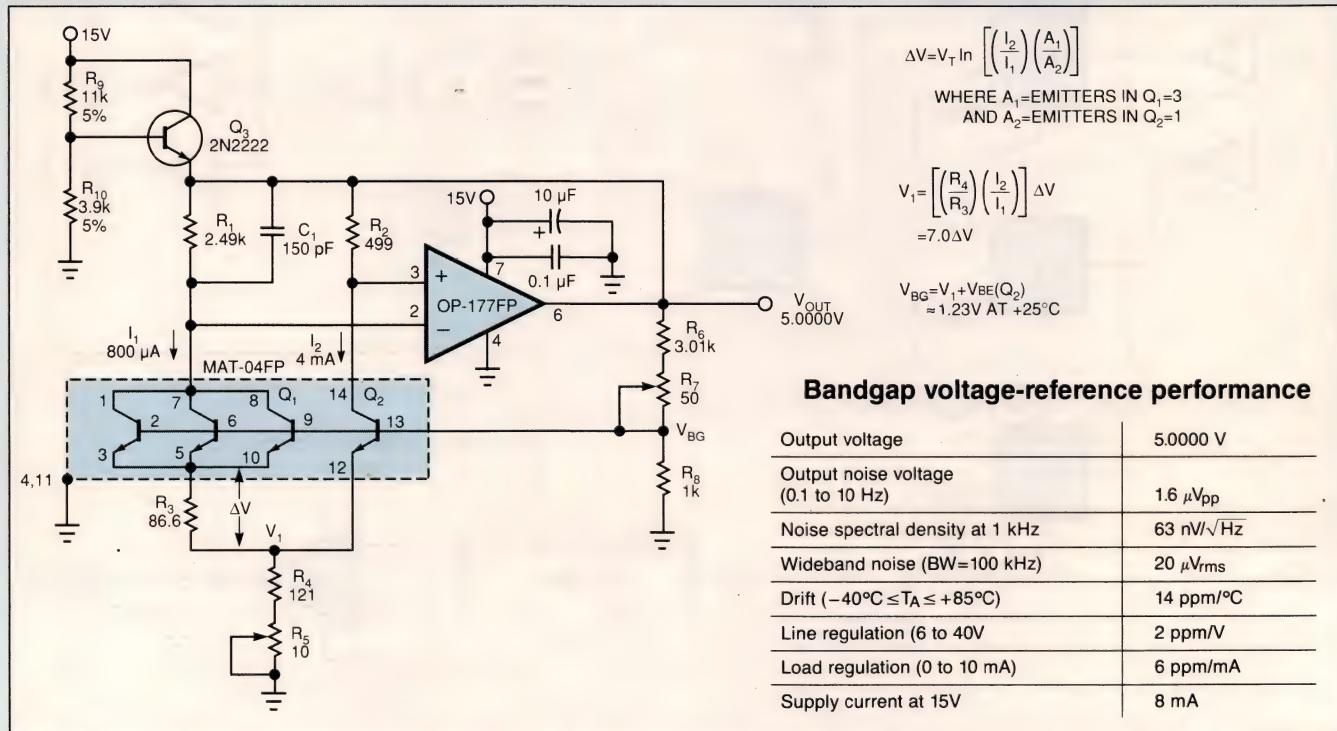
Adolfo Garcia, Analog Devices Inc, Santa Clara, CA

Noise is of critical importance in high-resolution, 16- to 20-bit, data-acquisition systems. The voltage reference can contribute the dominant share of the system's noise floor, thereby degrading system dynamic range and S/N ratio. To maximize these parameters, all external noise contributions should be much less than 1/2 LSB. Thus, the wideband noise contribution of a voltage reference and all other sources to 5V full-scale 16- and 18-bit systems should be less than 38  $\mu\text{V}$  rms and 9.5 V rms, respectively. Very few commercially available references exhibit low enough wideband noise without noise shaping or filters.

**Fig 1** shows a single-supply 5V reference design whose performance is summarized in the accompanying table. This design's noise is more than a factor of 2 lower than any 5V monolithic reference. In addition, the circuit's wideband noise in a 100-kHz bandwidth is 20  $\mu\text{V}$  rms, and therefore is suitable for 16-bit systems. The circuit uses very-low-noise matched transistors operating at high collector currents to keep their noise contribution low. The design also ensures that  $Q_1$  and  $Q_2$  operate at the same temperature. Any temperature differences between these two transistors

causes  $V_{BE}$  differences that will unbalance the bandgap reference's core. The MAT-04, a quad monolithic transistor, prevents  $V_{BE}$  temperature differences because all the transistors share a common substrate. Another dominant noise source is  $R_{33}$ , and by operating high currents in the bandgap core, its value is kept to a minimum. In this circuit topology, the lower the value of  $R_{33}$ , the lower the noise. To ensure repeatable low-frequency noise measurements, take care to shield the circuit from air currents. Any air movement around the circuit can create noise because of the thermoelectric differences between the IC's package leads and the copper traces on a pc board. A Styrofoam cooler works well to keep air turbulence from polluting noise measurements.

An important parameter in any voltage reference is drift over temperature. Careful layout and selection of components account for this reference's low drift. Much in the same way air currents can generate noise in the circuit, they can be a source of drift. Junctions formed by the IC's pins and the copper traces on a pc board can generate parasitic thermoelectric differences, which can be as large as 15  $\mu\text{V}/^\circ\text{C}$ . Packing the



**Fig 1—**Minimizing noise in high-resolution data-acquisition systems—no simple design task—starts with minimizing the reference's noise contribution. This circuit uses matched transistors and carefully selected resistors to implement a bandgap reference with noise of 1.6  $\mu\text{V}_{pp}$  in the 0.1- to 10-Hz band.

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MAN-1LN	0.5-500	28	1.0	+8	2.8	39	12/60	15.95
◊MAN-1HNL	10-500	10	0.8	+15	3.7	14	12/70	15.95
MAN-1AD	5-500	16	.05	+6	7.2	41	12/85	24.95
MAN-2AD	2-1000	9	0.4	-2	6.5	28	15/22	22.50
MAN-11AD	2-2000	8	0.5	-3.5	6.5	22	15/22	29.95

††Midband 10f<sub>L</sub> to f<sub>U/2</sub>, ±0.5dB    † 1dB Gain Compression    ◊Case Height 0.3 in.  
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components tightly on the pc board minimizes this error by making sure that all the components operate at the same temperature. Enclosing the circuit in a box is a good way to shield the circuit from air currents.

Since the circuit's output voltage and drift are sensitive to resistor tolerance and temperature coefficient, all fixed resistors are type RN55C (1%,  $\pm 50 \text{ ppm}/^\circ\text{C}$ ). Since  $R_1$  and  $R_2$  set the current ratio in the core, any mismatch in these components changes the current ratio, which affects  $\Delta V$  and introduces drift. Second, the ratio of  $R_4$  to  $R_3$  amplifies  $\Delta V$  with the current ratio. The result is voltage  $V_1$ , which adds to  $Q_2$ 's  $V_{BE}$ , thus producing a temperature-invariant bandgap voltage of 1.23V at the bases of  $Q_1$  and  $Q_2$ . Any mismatch in tolerance or temperature coefficient in  $R_3$  and  $R_4$  introduces drift by affecting  $V_1$  and  $Q_2$ 's  $V_{BE}$ . Last,  $R_6$  and  $R_8$  amplify the bandgap voltage of 1.23V to an output of +5.0000V. Any mismatch in these resistors changes the gain of the circuit and therefore changes the output voltage.

Another heavy contributor to the circuit's overall drift comes from the op amp's input-offset-voltage drift over temperature, which affects the bandgap core and introduces drift by changing the current ratio set by  $R_1$  and  $R_2$ . Therefore, choose an op amp first for its low input-offset voltage drift and second for its high open-loop gain.  $C_1$  provides compensation and stabi-

lizes the core by rolling off the op amp's high loop gain.

Although you can use low-cost cermet trimmers for  $R_5$  and  $R_7$ , keep in mind that these components typically have  $\pm 100 \text{ ppm}/^\circ\text{C}$  temperature coefficients. Therefore, use low-valued trimmers to keep the trim range narrow. Even mechanical changes that result from thermal expansion in the trimpot materials can be a large source of error. To trim the circuit, first adjust  $R_5$  so that the bandgap voltage equals 1.23V at  $25^\circ\text{C}$ . Second, use  $R_7$  to adjust the gain of the reference for +5.0000V at the output.

Bandgap references have a tendency not to start up when the power supply is turned on. You can avoid this condition by using a pair of resistors and an inexpensive npn transistor.  $R_9$ ,  $R_{10}$ , and  $Q_3$  form the start-up circuit. When the supply is turned on, there is no current in the bandgap core and the op amp's output is at 0V.  $Q_3$  then turns on, and its emitter current flows through  $R_6$ ,  $R_7$ , and  $R_8$ . When the output voltage reaches 3.2V, the op amp kicks in and stabilizes the operating point around 5V. This action shuts off  $Q_3$  because its base is set to 3.9V. For a wider range of supply voltages, you can replace  $R_{10}$  with a 3.9V zener diode to improve the start-up circuit's supply rejection.

**EDN BBS /DI\_SIG #1100**

EDN

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## Buffer goes solo in fast active filter

Michael Sedayao, Elantec Inc, Milpitas, CA

Active filters that drive low-impedance loads generally require a buffer with high output current at the filter output. If the filter doesn't require any gain, as in

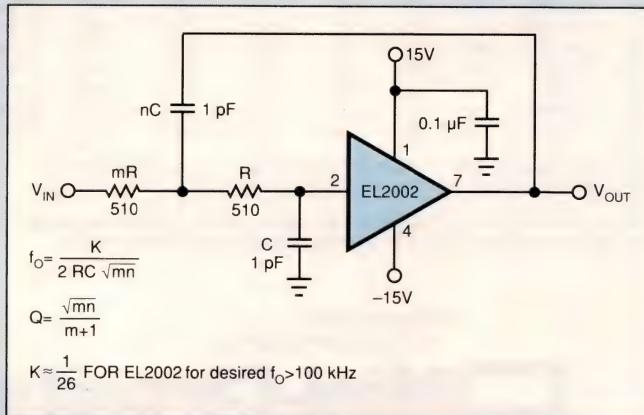


Fig 1—A single buffer implements this unity-gain Sallen-Key low-pass filter with a 12.2-MHz cutoff frequency.

unity-gain operation, you can synthesize the filter using only the buffer. Although you give up gain adjustment, you still retain the buffer's 100-mA output driver and 180-MHz bandwidth. And, you've saved the cost of an op amp.

Fig 1 illustrates a basic Sallen-Key low-pass filter using only one buffer. Resistor and capacitor ratios  $m$  and  $n$  and values  $R$  and  $C$  (see equations in Fig 1) determine the  $-3\text{-dB}$  frequency and  $Q$  of the filter. In this design, the  $-3\text{-dB}$  frequency is 12.2 MHz and the  $Q$  is 0.5. To change the low-pass filter to a high-pass filter, simply switch the resistor and capacitor locations. The resultant high-pass filter has a  $-3\text{-dB}$  frequency of 36 kHz and a  $Q$  of 0.5. This circuit will drive  $\pm 4.5\text{V}$  into 50 ohms and draws 5 mA of quiescent current. To achieve a Butterworth response, set  $Q = 0.707$ . **EDN BBS /DI\_SIG #1096**

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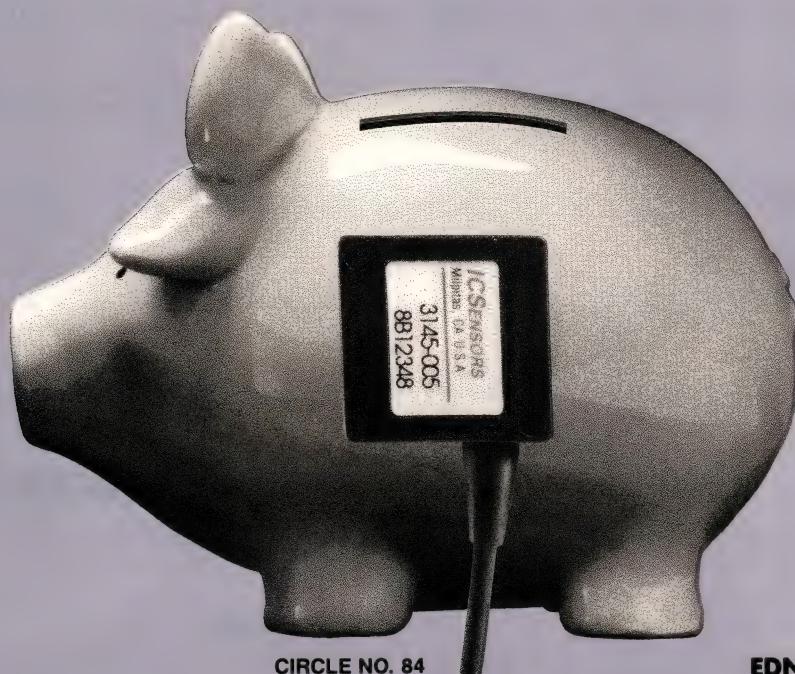
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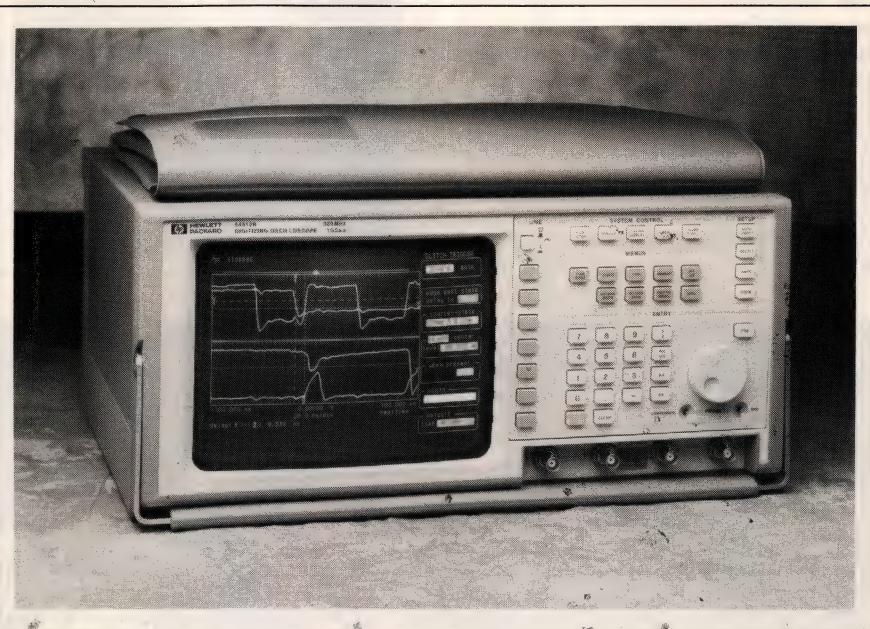
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clude mathematical operations, such as FFTs. 4-channel scope, \$17,990; 2-channel scope, \$11,950. Delivery, eight weeks ARO.

**Hewlett-Packard Co.**, 19310 Pruneridge Ave, Cupertino, CA 95014. Phone (800) 752-0900.

**Circle No. 351**

cent panel. It provides 20-nsec timing resolution, permits synchronous and asynchronous tracing at transfer rates above 10 MHz, and offers a 32k-event trace memory (128k optional). The tester, which performs passive synchronous/asynchronous and 4-edge request/acknowledge testing, is compatible with single-ended and optional differential versions of the SCSI bus. \$8550.

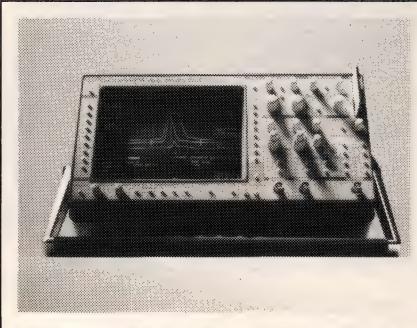
**Ancot Corp.**, 115 Constitution Dr, Menlo Park, CA 94025. Phone (415) 322-5322. FAX (415) 322-0455.

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- Works with five of the vendor's scopes
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**Circle No. 353**

### Attache-Case-Size Portable SCSI Bus Analyzer

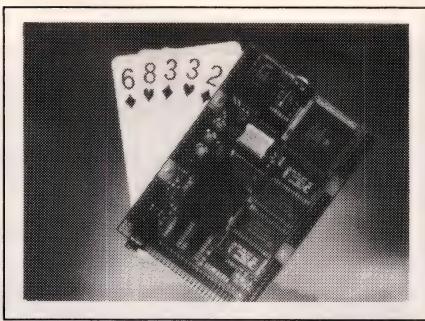
- Tests SCSI 1 and 2 Fast/Wide with 20-nsec resolution
- Has 32k-event trace memory (128k optional)

The DSC-216 is an attache-case-size tester for the SCSI bus. It handles SCSI 1 and 2 and tests fast and wide configurations of the bus. The stand-alone unit displays English-language messages on an 80-character × 24-line electrolumines-



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The 2784 analyzer is a 40-GHz instrument in a coaxial-cable environment and, using external mixers, a 1.2-THz (1200-GHz) instrument for waveguide work. You can set the resolution bandwidth from 3 Hz to 10 MHz. The display has 100-dB dynamic range. The rugged, portable unit has a color display based on a monochrome CRT and a liquid-crystal color shutter. \$79,500. Delivery, eight weeks ARO. **Tektronix Inc.**, Test & Measurement Group, Box 1520, Pittsfield, MA 01202. Phone (800) 426-2200.

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CIRCLE NO. 80

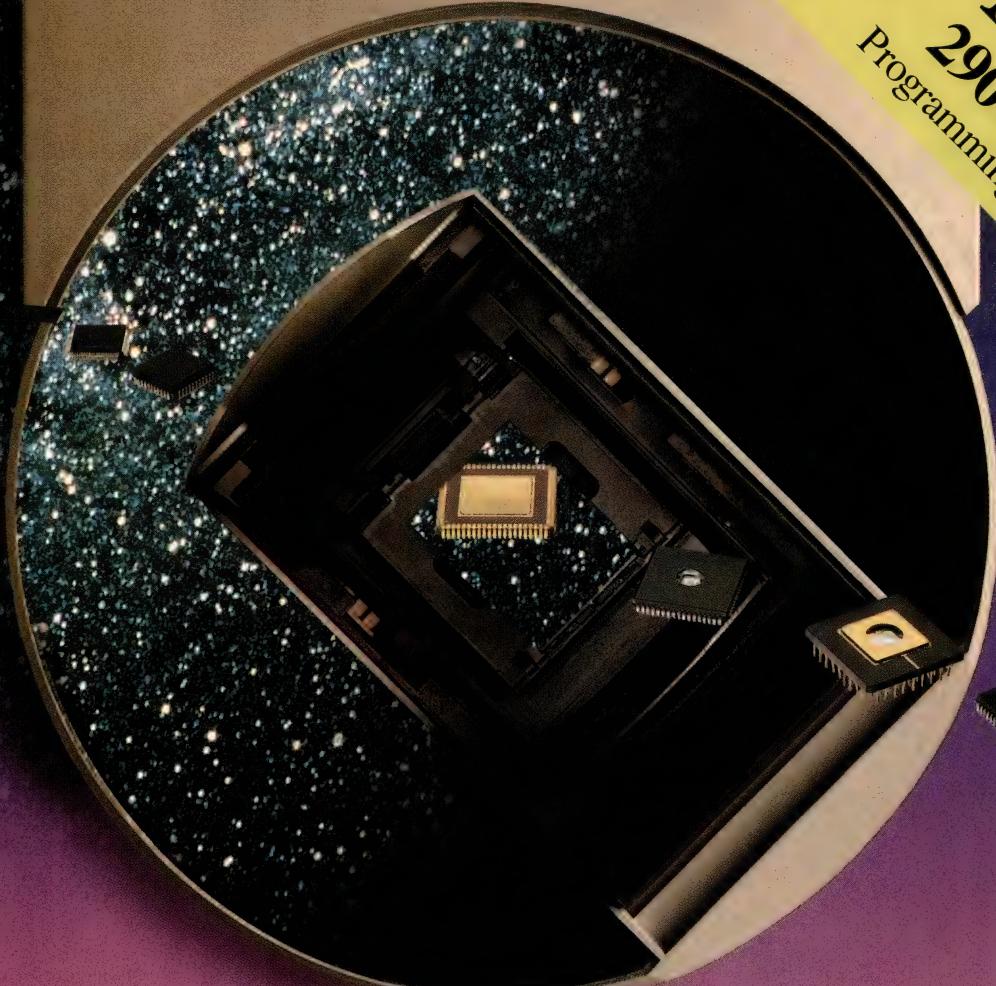
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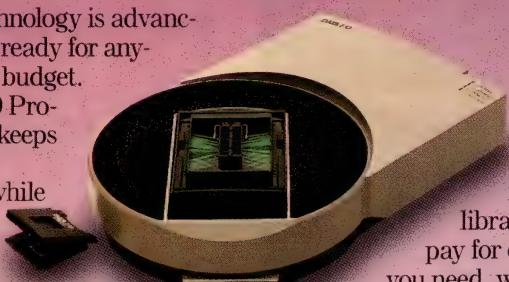
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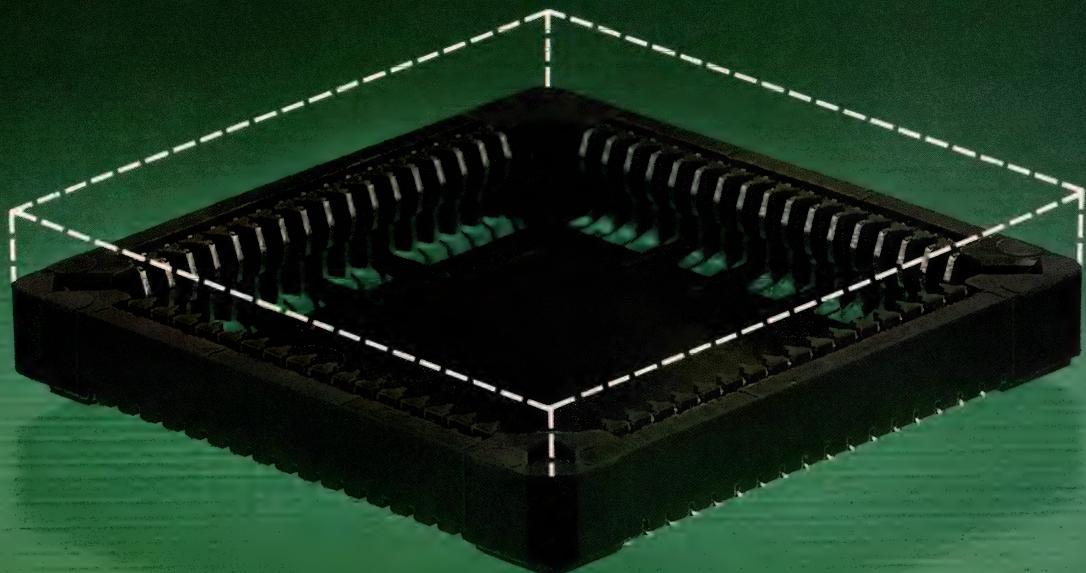
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MOV R5, #6000H
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# PLCC sockets. Now half off.



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## Common-mode Choke Coils at output sector

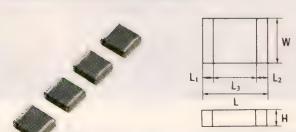
### EMC Chip Filters • M-600 Series



Common-mode chip filters ideal for surface-mounting on PC boards

## Ceramic Capacitor for Converters

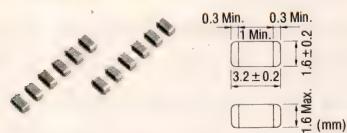
### Multilayer Ceramic Capacitors



Chip-type ceramic capacitor with large capacitance using Y5U materials

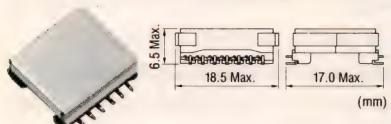
## Bead Inductors for eliminating switching/spike noise

### Solid Chip Inductors • NZ Series



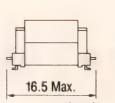
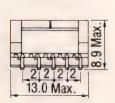
Thin, ultra-small, with monolithic structure and excellent frequency characteristics; designed for automatic mounting

• FEY15.3/13.0

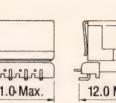


Superior magnetic circuit design technology ensures excellent frequency characteristics; compact, thin; ideal for ultra-high density mounting; SMD discrete monolithic structure

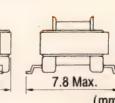
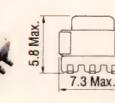
• FED11.6



• FEP7T



• FEE5



# TOKIN

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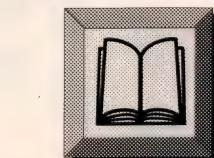
# Tap AMP.

*For connectors and help...from custom products to system design. This is AMP today!*



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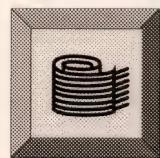
Need product specs? Drawings? Instruction sheets? Get all these and more, any time. Call our Product Information Center (1-800-522-6752) and choose the AMP FAX option at the voice prompt. All you need is a part or document number - the system will guide you from there, and fax the information you need in minutes!



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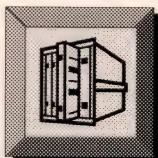
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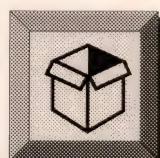
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AMP Packaging Systems offers state-of-the-art capabilities, with expertise in advanced, high-speed systems design. We build custom and semi-custom backplanes, card cages, and enclosure systems - with complete design, characterization, and fabrication as needed, to your specifications. Call 512-244-5100 for details!



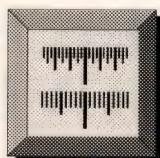
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The key to productivity? Connector and tooling designed together, to integrate into production. The key to continued productivity? Total support: installation and setup, training, and service. Your key to both? For AMP customers, the AMP Field Engineering Service Hotline, 1-800-722-1111. Help at your fingertips!



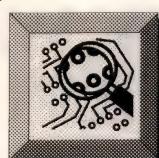
## **EXCELL-PAK Program**

We're shipping in new package sizes and new styles - smaller lots, more unit packaging, anti-static materials, and ergonomic design. We've also eliminated the use of CFCs and loose fill, and we're putting standard recycling codes - and bar code logos - on all packaging. Ask for our brochure!



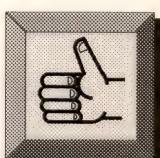
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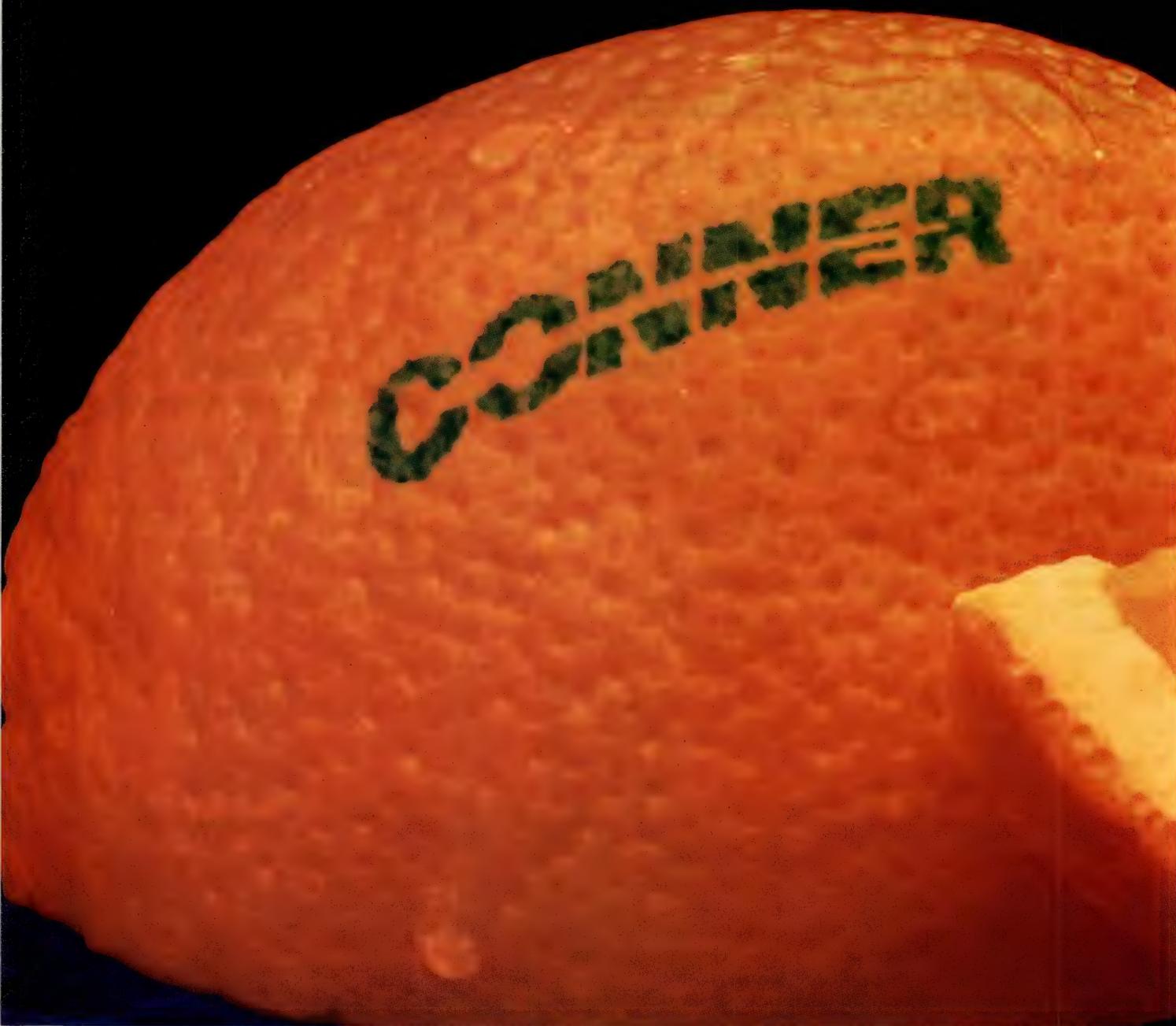
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CIRCLE NO. 48

# AMP

EDN March 30, 1992 • 149



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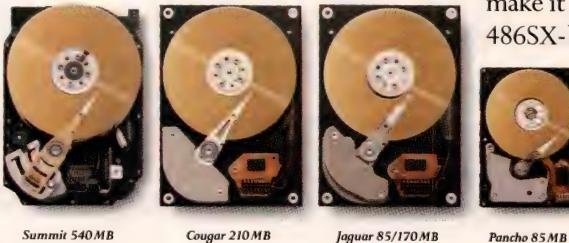
The squeeze is on. Today the PC market is rapidly concentrating into three segments: Notebooks, Desktops and Workstations. And once again, Conner has anticipated these changes.

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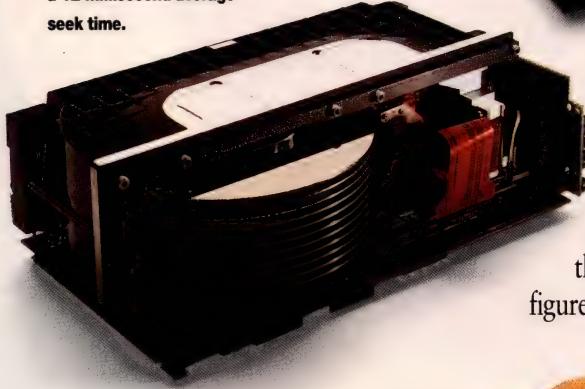
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The drives featured here are available now—setting performance standards in systems like yours all over the world.

The 5.25" Elite 1 offers gigabyte-plus capacity (1352 megabytes) at 5,400 RPM, for an average latency of only 5.56 milliseconds.

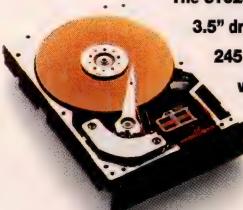


Today, as your competitive environment demands faster, less expensive processing than ever before, you need



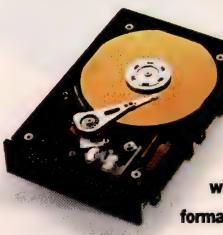
At 2.5", the ST9144 offers 127 formatted megabytes with a choice of AT and SCSI-2 interfaces and an average seek time of only 16 milliseconds.

drives like these. Because when you take a few milliseconds' performance advantage and multiply it by thousands of transactions a day... well, the results translate into some figures that might surprise you.



The ST3283 family of 1" high 3.5" drives holds more than 245 formatted megabytes, with a 4,500 RPM spindle which reduces latency to 6.67 milliseconds.

In fact, depending on the amount and nature of processing you do, high-performance drives like these can save you enough to pay back your disc drive investment within weeks—or days. For help in selecting the



The digital servo on this ST3600 family of low-profile 3.5" drives reduces average seek time to 10.5 milliseconds, with capacities up to 525 formatted megabytes.

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This full-height 5.25" Wren-9 (ST42100ND) offers up to 2.2 gigabytes of storage and a synchronous data transfer rate of up to 20 megabytes per second.

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The 3.5", half-height ST11200 family, with up to 1.2 gigabytes of storage, boasts a 256 kilobyte multi-segmented cache buffer and an average seek time of 10.5 milliseconds.

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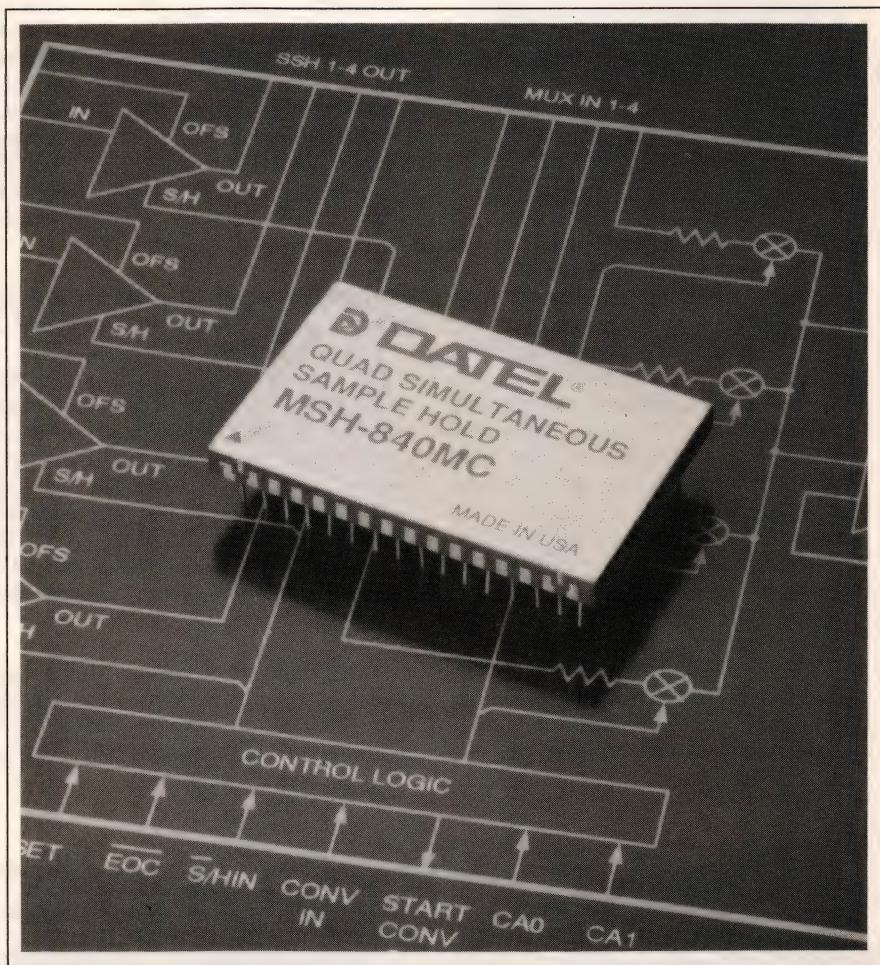
## 4-Channel, Simultaneous Sample/Hold Circuit

- Includes output multiplexer
- Features fast acquisition

The MSH-840 4-channel S/H circuit can acquire a 10V step to 0.01% accuracy in 775 nsec (including the settling time of the output multiplexer). The hybrid IC operates in two modes: single-channel or simultaneous sampling. In either mode, the use of the reset pin will set all the S/H circuits to the sample mode. Internal decoder circuitry allows channel selection to be digitized or the channel to be put into hold mode. The MSH-840 operates over a  $\pm 10$ V input range and has a maximum nonlinearity of  $\pm 0.01\%$ . Other specifications include -70-dB harmonic distortion, a 45V/ $\mu$ sec slew rate, and a 13-MHz small-signal bandwidth. The MSH-840 requires 5 and  $\pm 15$ V supplies and comes in a 32-pin package. From \$224 (OEM qty).

**Datel Inc**, 11 Cabot Blvd, Mansfield, MA 02048. Phone (508) 339-3000. FAX (508) 339-6356.

**Circle No. 364**



## 5V Regulator For $\mu$ P Functions

- Low dropout voltage
- Low quiescent current

Combining a  $5V \pm 4\%$  regulator with watchdog, enable, and reset functions, the CS-8140 gives the system's  $\mu$ P control over its own power. The low-dropout regulator (1.25V at 500 mA) has a quiescent current of 7 mA. A sleep mode reduces current drain to 250  $\mu$ A. A watchdog signal from the  $\mu$ P to the IC's enable input controls the  $\mu$ P's supply voltage. When the enable pin is high, the regulator's output stage is active. When the enable pin is low, and the watchdog signal falls outside user-programmable frequency limits, the IC's output turns off, setting the IC and the  $\mu$ P in sleep mode. The IC generates a re-

set signal when the watchdog signal falls outside its frequency limits while enable is high; when the IC's output voltage drops more than 4.5%; or when the IC power is on. CS-8140, in 7-pin TO-220 or 24-pin SOIC packages, from \$2.03 (1000).

**Cherry Semiconductor Corp**, 2000 South County Trail, East Greenwich, RI 02818. Phone (401) 885-3600. **Circle No. 365**

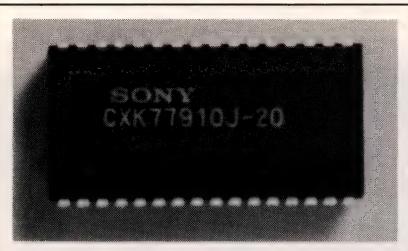
## High-Speed MOSFET Driver

- Sources 6A and sinks 3A
- Drives high-capacitive loads

The HV400 MOSFET driver can drive capacitive loads ranging from 5000 to 100,000 pF. With a 20,000-pF load, the monolithic IC achieves rise and fall times of 70- and 30-

nsec, respectively. The driver, which does not draw any quiescent current, can source peak currents to 6A via its high-side npn switch and can sink peak currents to 30A via its low-side SCR switch. This capability lets the IC switch four parallel-connected IR452 MOSFETs in 20 nsec. In floating applications, the HV400 can operate from a small pulse transformer driven by the system's PWM circuit. Using this pulse transformer and a few low-cost components, the driver provides its own power supply, isolation, level shifting, timing, and buffering. HV400, in 8-pin DIP and SOIC packages, from \$1.40 (100).

**Harris Semiconductor**, Box 883, Melbourne, FL 32901. Phone (800) 442-7747, ext 1047. **Circle No. 366**



**Self-timed SRAM.** Optimized for SPARC processors, the CXK77910J self-timed static RAM (SRAM) integrates 1 Mbit of memory with input and output registers. Organized as 128k-words  $\times$  9 bits, the SRAM comes in 16.6- and 20-nsec versions. Power consumption of the TTL-compatible device is 715 mW. In 32-pin SOJ package, from \$75 (1000). **Sony Corp of America**, Component Products Co, Box 6016, Cypress, CA 90630. Phone (714) 229-4197. FAX (714) 229-4333. **Circle No. 367**

**Power-factor preregulator.** The UC3852 allows 50 to 100W power supplies to operate at a 0.99 power factor. The IC regulates the output dc voltage by controlling switch on-time, and the

boost inductor controls the off-time. A zero-current sensing circuit activates the switching cycle. Other features include undervoltage lockout, current limiting, and output clamping. In 8-pin DIP and SO packages, from \$1.77 (100). **Unitrode Integrated Circuits Corp**, 7 Continental Blvd, Merrimack, NH 03054. Phone (603) 424-2410. FAX (603) 424-3460. **Circle No. 368**

**60-MHz op amp.** The EL2044 op amp features a 325V/ $\mu$ sec slew rate and a 60-MHz bandwidth. Operating from a  $\pm$ 15V supply, the IC has an output swing of  $\pm$ 13.6V. Output-current capability is 75 mA. The IC operates from a dual supply of  $\pm$ 2 to  $\pm$ 18V or a single supply of 2.5 to 36V. In 8-pin DIP and SO packages, from \$1.80 (100). **Elantec Inc**, 1996 Tarob Ct, Milpitas, CA 95035. Phone (408) 945-1323. FAX (408) 945-9305. TWX 910-997-0649. **Circle No. 369**

**Bus transceiver.** Designed for balanced transmission lines, the SN75-LBC176 bus transceiver meets EIA RS-485 and ISO 8482:1987(E) stan-

dards. The IC has a 3-state differential line driver and a differential line receiver, both of which operate from a single 5V supply. The bus lines, which are connected internally, can send or receive data over a common-mode voltage range of  $-7$  to  $+12$ V. In an 8-pin DIP, \$1.57 (1000). **Texas Instruments Inc**, Semiconductor Group (SC-92008), Box 809066, Dallas, TX 75380. Phone (800) 336-5236, ext 3990. Outside US and Canada, (214) 995-6611, ext 3990. **Circle No. 370**

**Analog filters.** The MAX274 eighth-order filter has four cascadable sections, and the MAX275 fourth-order filter has two. Each second-order, state-variable section can implement bandpass or low-pass filter responses. The MAX274 programmable center frequency ranges from 100 Hz to 150 kHz; the MAX275's range is from 100 Hz to 300 kHz. Available in 24- and 20-pin packages, respectively, MAX274 and MAX275, from \$4.95 and \$3.75 (1000). **Maxim Integrated Products**, 120 San Gabriel Dr, Sunnyvale, CA 94086. Phone (408) 737-7600. **Circle No. 371**

## Breakthrough multichip modules



**Low drop-out regulators.** Designed for automotive applications, the MIC-2950/51/54 regulators combine low drop-out voltages with load-dump and reverse-battery protection. The 2950 provides a fixed 5V/150-mA output and has a 380-mV dropout. The 2951 has the same dropout voltage and current rating but provides an adjustable 1.24 to 29V output. The 2954 provides a fixed 5V/250-mA output and has a 500-mV dropout. Depending on type and package options, from \$1.07 to \$2.53 (100). **Micrel Semiconductor**, 560 Oakmead Pkwy, Sunnyvale, CA 94086. Phone (408) 245-2500. **Circle No. 372**

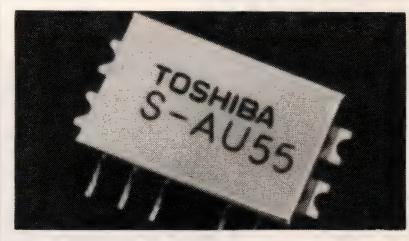
**10-bit A/D converter.** The AD773 10-bit ADC includes an onboard T/H amplifier, a high-impedance reference input, and CMOS/TTL-compatible outputs. Optimized for video application, the ADC features a full-power bandwidth of 100 MHz, a speed of 18 Msamples/sec, and differential gain and phase specifications of 0.4% and 0.2°, respectively. The ADC can acquire full-scale voltage swings in less than 55 nsec and offers common-mode noise rejection of

75 dB. In 28-pin ceramic DIP, from \$55 (100). **Analog Devices Inc**, Applications Engineering, 181 Ballardvale St, Wilmington, MA 01887. Phone (617) 937-1428. FAX (617) 821-4273.

**Circle No. 373**

**Dual comparator and pin receiver.** The 100-MHz EL2254 replaces the buffer, attenuator, and ECL comparators used in test equipment and data-communications line receivers. The IC provides a 4-nsec propagation delay with low dispersion of 100 psec (typ). The inhibit and latch-enable inputs are ECL-, TTL-, and CMOS-compatible differential inputs. In a 20-pin SO package, \$6.40 (100). **Elantec Inc**, 1996 Tarob Ct, Milpitas, CA 95035. Phone (408) 945-1323. **Circle No. 374**

**RF power amplifier.** Designed for handheld cellular-phone applications, the S-AU55 RF power amplifier operates over the frequency range of 824 to 849 MHz. Input power to the GaAs FET amplifier is 4 mW, and output power is 1.12W. The 17 × 12 × 4-mm



module operates from a 5.8V supply, has an efficiency of 55%, and a gain of 24.4 dB. \$36.50 (1 to 3000 qty). Delivery, 14 weeks ARO. **Toshiba America Electronic Components Inc**, 9775 Toledo Way, Irvine, CA 92718. Phone (714) 455-2000. **Circle No. 375**

**64-channel push-pull driver.** The HV3225X integrates low-voltage logic with 64 push-pull output drivers rated at 250V. The logic section, which operates at 5 or 12V, comprises a 64-bit shift register and 64 latches. The programmable output stages can source or sink currents from 25 to 250 μA. In die form waffle packs, \$13.24 (1000). **Supertex Inc**, 1350 Bordeaux Dr, Sunnyvale, CA 94089. Phone (408) 744-0100. **Circle No. 376**

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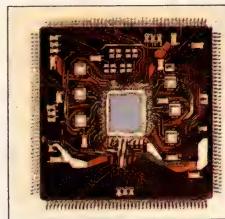
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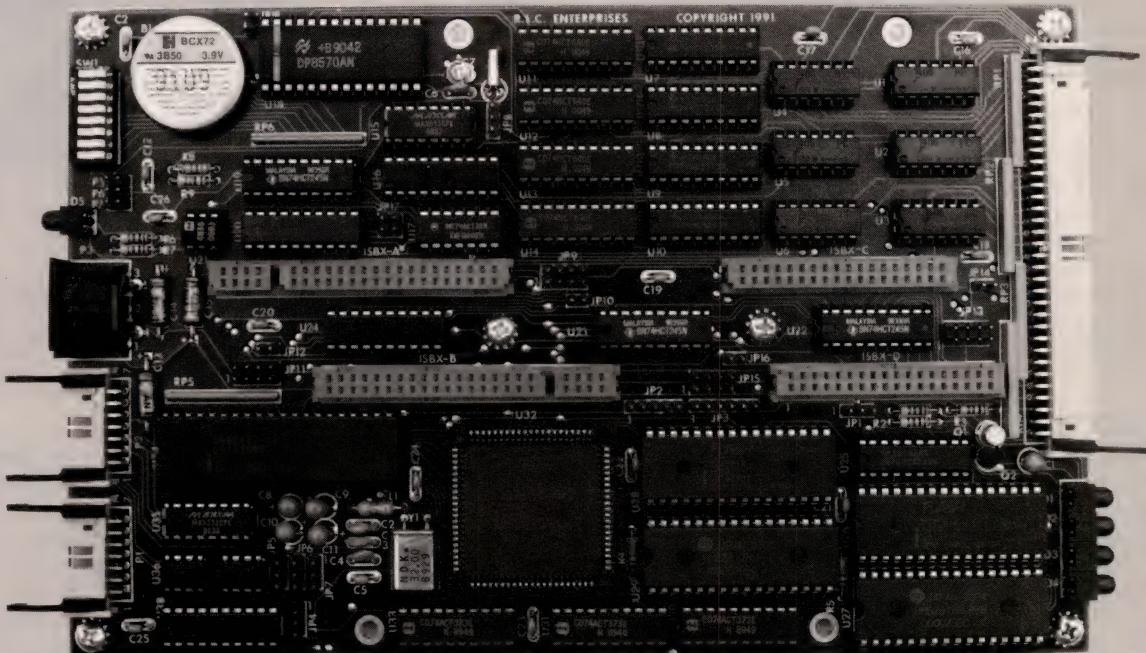


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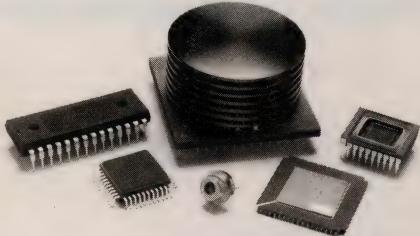
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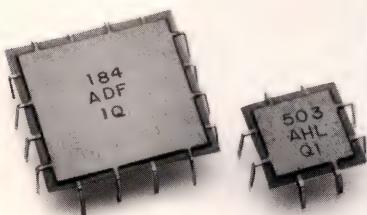
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CIRCLE NO. 89

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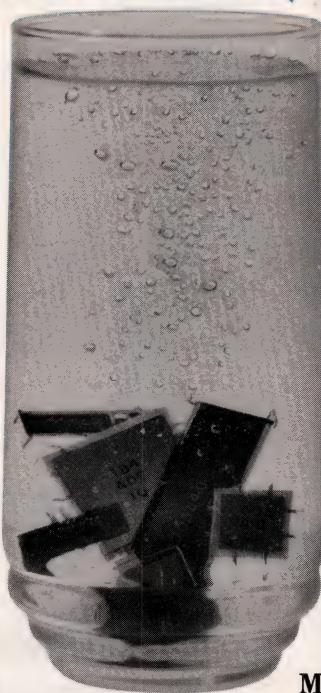
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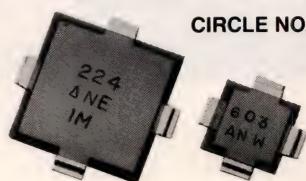
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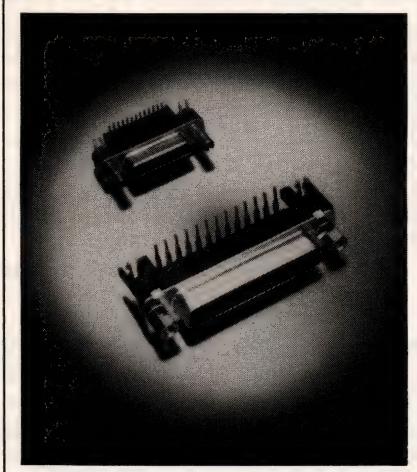
**Circular Connectors**

- Weigh 70% less than standard steel devices

**DGH123** Series circular connectors are manufactured with a metallized composite shell and panel nut. Compatible with MIL-C-29600 requirements, the units weigh 70% less than standard steel hermetic devices. Connector contacts accept wire sizes of #12 to #24 AWG. Immersible in fuels, coolants, solvents, and gases, the connectors have a leak rate of  $1.04 \times 10^{-6}$  cm<sup>3</sup>/sec at 14.7 psi differential. The connectors meet all requirements in MIL-STD-1344 for immersion, and the composite materials are unaffected by MIL-C-43616, TT-M-268, MIL-H-833-06, TT-S-735, or MIL-T-81533. Operating range spans -65 to +175°C. \$85 (100). Delivery, 8 to 12 weeks ARO.

**Deutsch Engineered Connecting Devices**, Municipal Airport, Banning, CA 92220. Phone (714) 849-7822.

**Circle No. 377**

**PC-Board Connectors**

- Feature a 0.05-in. pitch
- Comply with MIL-C-83513

Requiring only one-third the space of conventional D subminiature connectors, the MDSM family pc-board-to-cable connectors feature a

0.05-in. contact pitch. The units are fully compatible with MIL-C-83513 and feature a contact design that makes three points of contact. A shielding system integral to the backshell provides 70-dB attenuation. The line features right-angle and cable-type connectors in 9-, 15-, and 25-position versions, as well as double-stack 9- and 15-position versions. Crimp contacts for the cable versions are available for #26 and #28 AWG wire. \$7 per mated pair (1000).

**ITT Cannon**, 1851 E Deere Ave, Santa Ana, CA 92705. Phone (714) 261-5300.

**Circle No. 378**

**Rocker Switches**

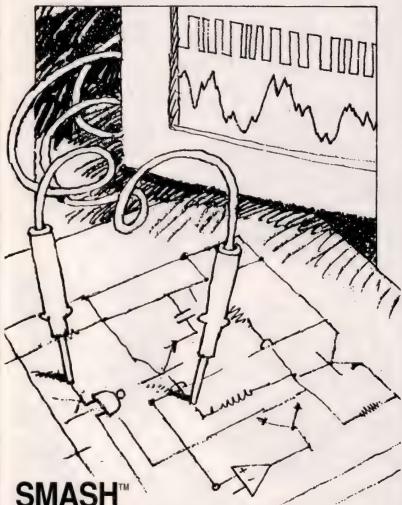
- Rated for 10A loads
  - Have a 10,000-cycle life
- D Series miniature power-rocker

switches feature a right-angle terminal style that snaps into a pc board to secure switches for soldering. The switches snap into a standard panel cutout and require no tools for mounting. The line features five spst switch functions. Contacts are rated for 10A at 125V ac and 5A at 250V ac. Electrical life is specified at 10,000 cycles at full load. Dielectric strength measures 1000V rms min at sea level. Actuators and housing are available in nine colors with custom actuator markings available. The 6/6 nylon material carries a UL 94V-2 rating. Most models are UL recognized and CSA certified. From \$1.11 (1000).

**C&K Components Inc**, 15 Riverdale Ave, Newton, MA 02158. Phone (617) 964-6400. FAX (617) 527-3062. TLX 922544.

**Circle No. 379**

# Simulator Multi-degree Analog-Structural Hierarchical on your personal workstation

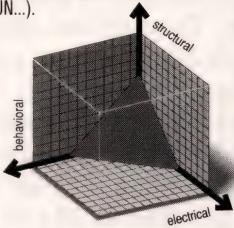


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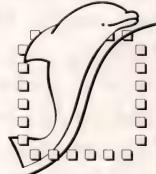
### Main features:

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- Libraries: compatibility with most common libraries of ASICs and PCBs; capability given to the user to write his own modules in a C-like language at behavioral degree, or available from Dolphin Integration upon request.
- Interactive set up and simulation display for all analyses: DC transfer function (including operating point and temperature analysis), AC transfer function, transient analysis.
- Delays at structural level.
- Processing capability in background mode.
- Device visibility through analog behavioral modeling.
- Modularly designed to enable separation of three modules initializer, engine and visualizer (ICD).
- Results: EXCEL files, ICD format files.
- Available on your personal computer (Mac, PC) and UNIX workstation (SUN...).

SMASH™ processes simultaneously 12000 gates, 250 transistors and 12000 steps or events.



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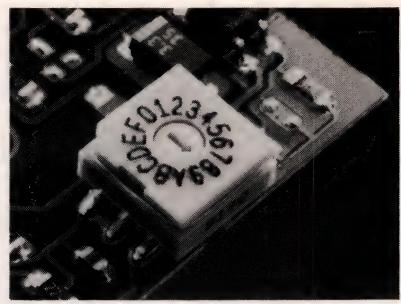
Dolphin - US  
P.O. BOX N - Santa Clara  
95 055 - 3740 - California - USA  
phone: (408) 727 - 4123  
fax: (408) 727 - 2541

CIRCLE NO. 126

164 • EDN March 30, 1992

**Fan trays.** Designed for VME systems, these fan trays feature a 5-fan design that offers direct cooling of slots 1 through 3—the most critical in a VME system. The trays are designed for use with 160-, 220-, 280-, or 400-mm-deep chassis. Each tray includes a filter, a power-on LED, and a quick-disconnect power connector. From \$300. ACT Inc., 1 Ivybrook Blvd, Suite 180, Ivyland, PA 18974. Phone (215) 957-9071.

Circle No. 380



**Circuit breaker.** The IML family of circuit breakers includes 1-, 2-, and 3-pole versions. The units are available with ratings of 0.5 to 70A at 80V dc and 0.5 to 50A at 240V ac. The breakers are UL recognized, CSA certified, and meet international spacing requirements of IEC-157-1 and VDE 0660. Models are available in screw panel-mount or snap-in styles. \$14 to \$16 (OEM qty). Airpax, Corporate Advertising, 7 McKee Pl, Cheshire, CT 06410. Phone (410) 228-4600. FAX (410) 228-8910.

Circle No. 381

BCD, hexadecimal—or their complements' coded-output choices. Octal unit, \$1.69 (1000). Grayhill Inc, Box 10373, La Grange, IL 60525. Phone (708) 354-1040. FAX (708) 354-2820. TLX 190254.

Circle No. 384

**Memory-card connector.** The FCN-560H series of DRAM-memory-card connectors consists of a right-angle board-mount plug and a surface-mountable card socket. The plug features 88 pins arranged in two rows with 0.05-in. contact spacing. Contact resistance equals 40 mΩ and operating range spans -55 to +105°C. \$5.42 and \$6.25 for plug and socket, respectively, (1000). Delivery, stock to six weeks ARO. Fujitsu Microelectronics Inc, 3545 N First St, San Jose, CA 95134. Phone (800) 642-7616; (408) 922-9000. FAX (408) 428-0640.

Circle No. 382

**DIN connectors.** These DIN 41612 connectors come with snap-in clips that secure the units during soldering. The connectors fit into boards that are 1.6 mm thick and are available in angled male and female versions. \$2.37 (1000). Harting Elektronik Inc, 2155 Stonington Ave, Suite 212, Hoffman Estates, IL 60195. Phone (708) 519-7700. FAX (708) 519-9771.

Circle No. 385

**Card cage.** The rack-mountable Power Cage III includes a 12-slot VME (6U × 160 mm) card cage, a high efficiency 400W power supply with integral cooling, and a rugged Eurocard subrack that features a 10-layer J1-J2 VME backplane. The unit features front-panel LED voltage indicators; the hinged rear panel provides access to the fans and power supply and the rear of the backplane. \$2495. Delivery, four to six weeks ARO. Electronic Solutions, 6790 Flanders Dr, San Diego, CA 92121. Phone (800) 854-7086; (619) 452-9333. TWX 910-335-1169.

Circle No. 386

**Crystal oscillator.** The HSM531/536 surface-mount oscillators are available with frequencies of 1.8432 to 70 MHz. The units are available with stabilities of ±50 or ±100 ppm over a temperature range of 0 to 70°C. The oscillators are housed in a ceramic package that has a grounded metal cover to suppress RFI. \$11.25. Connor-Winfield Corp, 1865 Selmarthen Rd, Aurora, IL 60505. Phone (708) 851-4722. FAX (708) 851-5040.

Circle No. 383

**Rotary switch.** Series 94 rotary switches are available in surface-mount and through-hole versions. The units operate logic level loads, are rated for 25,000 operations, and feature octal,

**Power supplies.** The SWA series of supplies includes 15, 20, and 30W wall plug-in units and 40 and 60W cord-to-cord units. The cord-to-cord models have an input range of 90 to 264V ac; plug-in versions accept 90 to 132V and 198 to 264V. The units output from 5 to 17.5V at currents ranging to 4A. All models feature overload protection and feature 65 to 70% efficiencies. Wall plug-ins, from \$39; cord-to-cord models, from \$78 (100). Tamura Corp of America, 1150 Dominguez St, Carson, CA 90746. Phone (213) 638-1790. FAX (213) 638-9956.

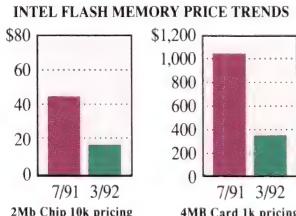
Circle No. 387

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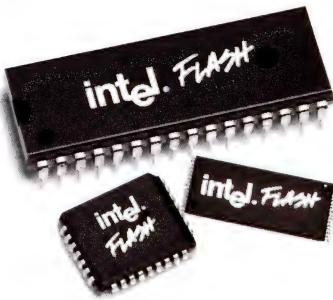
Our commitment to flash technology goes far beyond high performance,

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nent (2Mb). We played a leadership role in setting 68-pin PCMCIA/JEDEC standards. And we also brought you the first high-integration blocked flash architecture with on-chip automated program and erase.

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**Portable Computer**

- Has a 50-MHz 80486 μP and 4 Mbytes of RAM
- Optional TFT screen displays 24,389 colors

The P.A.C. 486-50E portable computer contains a 50-MHz μP. Standard features include 4 Mbytes of RAM expandable to 32 Mbytes; an 8- to 128-kbyte cache RAM; a 1.44-Mbyte floppy-disk drive; a 120- to 420-Mbyte hard-disk drive; a 64-kbyte disk buffer; and support for a WE4167 coprocessor. The unit has four internal EISA expansion slots and three external ISA expansion slots. A Gas-Plasma VGA display is standard, and you can opt for an active-matrix TFT screen that displays 24,389 colors. The unit has two serial ports, a parallel port, and a VGA port for simultaneous



display on an external monitor. The computer measures 16 × 9.5 × 7.8 in. and weighs 18 lbs. 120-Mbyte hard-disk-drive version, less than \$9000.

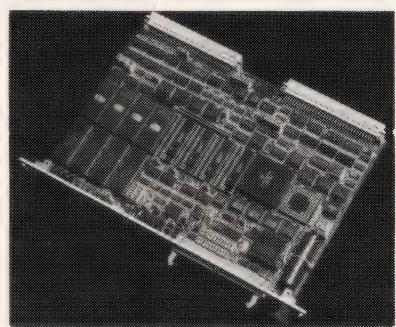
**Dolch Computer Systems**, 372 Turquoise St, Milpitas, CA 95035. Phone (408) 957-6575. FAX (408) 263-6305.

**Circle No. 388**

**VMEbus Single-Board Computer**

- Has a 25- or 40-MHz 68EC030 μP
- Three memory banks accept SRAM, EPROM, and dual-port RAM

The XVME-630 VMEbus single-board computer (SBC) contains a 25- or 40-MHz 68EC030 μP. The



6U board contains three memory banks having four 32-pin sockets each. Bank 1 accepts static RAMs (SRAMs); bank 2 accepts EPROM; and bank 3, which has dual-port access to the VMEbus, accommodates SRAM, EPROM, or flash memory. The board has a socket for a 68882 coprocessor; two serial ports; a single-level VMEbus arbiter; and ACfail and SYSfail monitoring func-

tions. It also has an interrupt handler and a programmable VME interrupter. The operating temperature ranges from 0 to 65°C, and board humidities are 0 to 95% non-condensing relative humidity. The board survives 30g and a vibration rate of 5 to 2000 Hz. From \$1950.

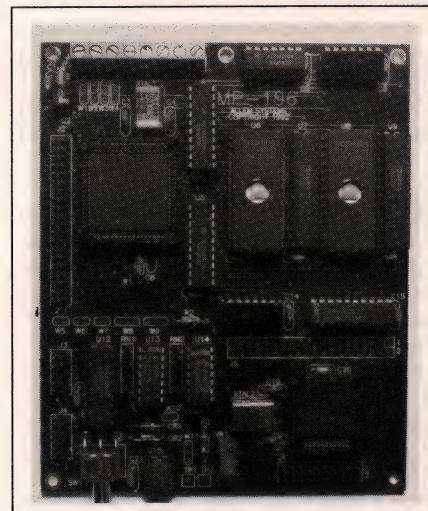
**Xycom Inc**, 750 N Maple Rd, Saline, MI 48176. Phone (800) 367-7300; (313) 429-4971. **Circle No. 389**

**Single-Board Computer**

- Has a 16-MHz 80C196KC μC
- Has 28 kbytes of static RAM

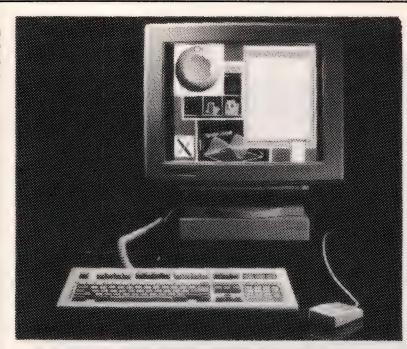
The MP-196 single-board computer has a 16-MHz 80C196KC microcontroller. It measures 4.5 × 5.5 in. and supports 32 kbytes of EPROM and 28 kbytes of static RAM (SRAM). An optional page-mode feature supports 64 kbytes of EPROM and 56 kbytes of SRAM. The board has as many as three 8-bit parallel ports, two buffered serial ports, and one unbuffered serial port. An optional analog daughter board provides a 4-channel ADC and a 2-channel DAC—both have 12-bit resolution. Two

27C128 EPROMs contain a system monitor and a Basic interpreter. The monitor can trace the execution of a user program and set as many as eight breakpoints. Using the board's serial link, you can save and load programs on a 5 1/4-in. disk. Board, with user's manual, \$125; assembled and



tested board having 32 kbytes of EPROM and 28 kbytes of RAM, \$500.

**Allen Systems**, 2346 Brandon Rd, Columbus, OH 43221. Phone (614) 488-7122. **Circle No. 390**



**Color display station.** The model TX600C features a 25-MHz 68030 µP for an X-Window CPU, a 40-MHz 34020 for a graphics CPU, and 6 Mbytes of RAM. Memory is upgradable to 37 Mbytes. A plug-and-play version comes with a 1280 × 1024-pixel, 19-in. monitor, keyboard, and mouse. A hot-key feature lets you switch between two screen presentations. Local client software connects to any host on the system. \$5865. **Visual Technology Inc.**, 120 Flanders Rd, Westboro, MA 01581. Phone (508) 836-4400. FAX (508) 366-4337. **Circle No. 391**

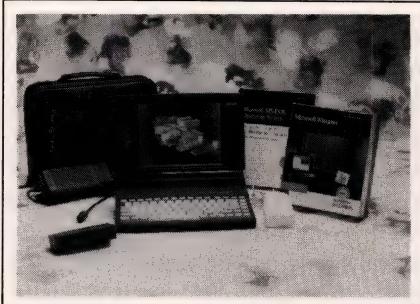
**GPIO adapter board.** The Model 600 GPIO adapter board for the ISA bus connects to HP's Model 98622 GPIO bus. It provides 16 TTL input-data lines, 16 open-collector output-data lines, six handshake and control lines, and four general-purpose lines. The board operates with High Tech Basic software that lets you transfer data between workstations running HP Basic and DOS software. \$375. **TransEra Corp.**, 3707 N Canyon Rd, Provo, UT 84604. Phone (801) 224-6550. FAX (801) 224-0355. TLX 296438. **Circle No. 392**

**SCSI converter.** The Parallel-SD10 converts single-ended SCSI-2 signals to differential SCSI-2 signals and vice versa. It handles 10-Mbyte/sec rates and is transparent to devices on the bus. The unit meets ANSI X3T9.2 standards for ports separated by as much as 102 ft. The stand-alone box has a wall-mount power supply. Model SD10, \$475; Model SD11, \$285. **Paralan Corp.**, 7171 Ronson Rd, San Diego, CA 92111. Phone (619) 560-7266. FAX (619) 560-8929. **Circle No. 393**

**Dual-channel SCSI-2 adapters.** The RF3590 and RF3870 are 9U and 6U, respectively, VMEbus SCSI-2 adapters. Two independent Fast SCSI-2

channels handle asynchronous and 10 Mbyte/sec synchronous data-transfer rates. The boards support both single-ended and differential SCSI connections. Both models handle 8-, 16-, and 32-bit data transfers on the VMEbus as fast as 30 Mbytes/sec. From \$3050 (OEM qty). **Ciprico Inc.**, 2955 Xenium Lane, Plymouth, MN 55441. Phone (612) 559-2034. **Circle No. 394**

**SPARCserver memory package.** The CPSM-09A/S16-80 is a 16-Mbyte memory package for Sun's SPARCserver 630MP, 670MP, and 690MP computers. The double-sided surface-mount package employs SOJ 16-bit dynamic RAMs. The package installs in Sun's 64 SIMM-slot (single-inline-memory-module) memory-expansion board to provide as much as 1024 Mbytes of system memory. \$6000. **Clearpoint Research Corp.**, 35 Parkwood Dr, Hopkinton, MA 01748. Phone (508) 435-2000. FAX (508) 435-7504. **Circle No. 395**



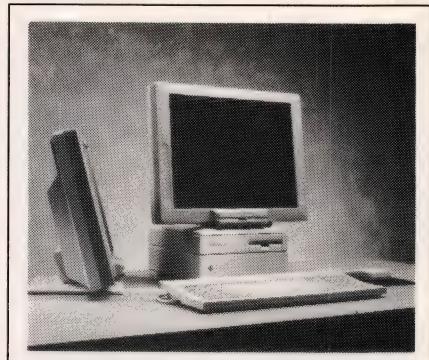
**80386SX notebook computer.** The NB913 Notebook PC contains a 20-MHz 80386SX µP, 2 Mbytes of RAM, and a 60-Mbyte hard-disk drive. The RAM is expandable to 4, 6, or 8 Mbytes. The computer runs on DOS 4.01 and Windows 3.0 operating systems. A 10-in. black-on-white LCD screen has 640 × 480 pixels and displays 64 levels of gray. Battery life is approximately 5 hours, and the unit weighs 7.7 lbs. \$1999. **Micro Express**, 1801 Carnegie Ave, Santa Ana, CA 92705. Phone (800) 989-9900; (714) 852-1400. FAX (714) 852-1225. **Circle No. 396**

**Laser printer.** The QMS-PS 1700 intelligent laser printer serves as many as 20 users. It connects directly to either Ethernet or Token-Ring networks and supports DECnet, TCP/IP, Netware, or EtherTalk protocols. The printer has either 600 × 600- or 300 × 300-dpi resolution and prints at 17 pages/minute. It comes with a 1000-

sheet input tray and has a duty cycle of 50,000 pages/month. \$7995. **QMS Inc.**, Box 81250, Mobile, AL 36689. Phone (205) 633-4300. FAX (205) 633-0013. **Circle No. 397**

**GPS receiver.** The GPStar device provides time and frequency with atomic accuracy by receiving the Universal Time Code (UTC) transmitted by Global Positioning System (GPS) satellites. It tracks as many as five satellites at a time and provides an accuracy of 100 nsec for UTC. The stand-alone unit accommodates long cable lengths by placing the down-converter near the antenna. It has an RS-232C port to download time data to a computer. \$3995. **Odetics**, 1515 S Manchester Ave, Anaheim, CA 92802. Phone (714) 774-5000. FAX (714) 774-9432. **Circle No. 398**

**Color Postscript printer.** The G5241-PS/4 prints Adobe Postscript images in Pantone licensed colors on A-size paper or overhead transparencies. The thermal-transfer printer has 300-dpi resolution and 4 Mbytes of RAM. Standard interfaces include Appletalk, Centronics parallel, and RS-232C ports. \$6990. **Océ Graphics Inc.**, Box 7169, Mountain View, CA 94039. Phone (415) 964-7900. FAX (415) 961-6152. **Circle No. 399**



**Plasma display.** The model FPF-20000S is a stand-alone ac-memory plasma flat-panel display. The screen has 100-dpi resolution on a 16-in. diagonal viewing area. The 1280 × 1024-pixel display interfaces to Sun's SPARC-stations. The monitor includes interface circuitry and an ac/dc converter in a chassis measuring 16.85 × 12.56 × 3.5 in. The unit weighs approximately 14 lbs and has an operational life of 50,000 hours. \$5000. **Fujitsu Microelectronics Inc.**, 3545 N First St, San Jose, CA 95134. Phone (800) 642-7616; (408) 992-9000. FAX (408) 428-0640. **Circle No. 400**

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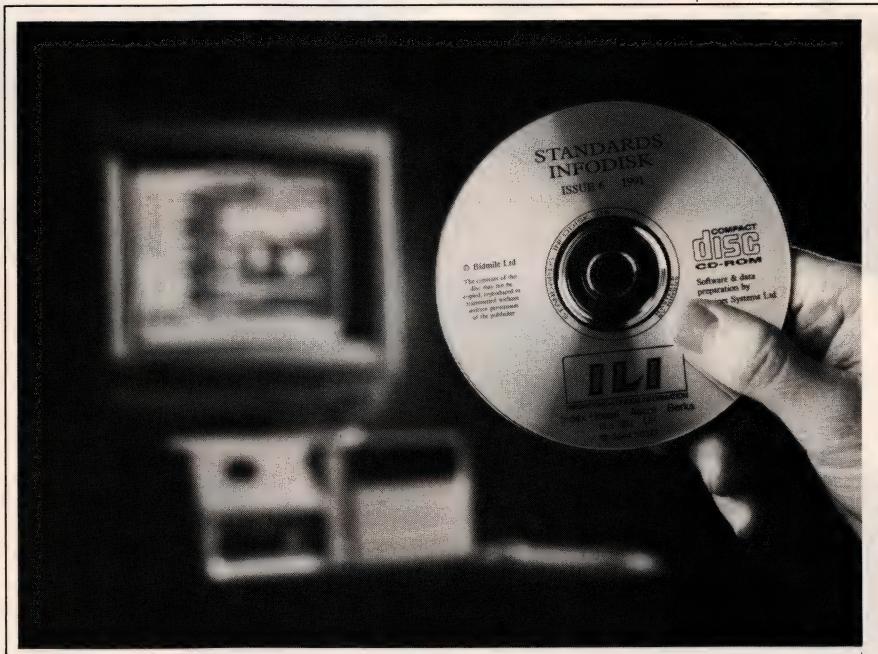
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date, country of origin, subject, or key word or phrase. To use the product, you need a PC XT, MS-DOS 3.0, and a CD-ROM drive. \$2195.

**Document Engineering Co Inc,** 15210 Stagg St, Van Nuys, CA 91405. Phone (800) 363-3647; (818) 782-1010. FAX (818) 782-2374.

**Circle No. 407**

**Interactive math for VAX.** Maple V for VAX/VMS is an interactive computer algebra system. A user interface for the X-Window system edits input expressions and maintains session logs. It also produces interactive 3-D color graphics. US \$1395. **Waterloo Maple Software**, 160 Columbia St W, Waterloo, ON, N2L 3L3, Canada. Phone (519) 747-2373. **Circle No. 408**

**Real-time operating system.** An optimized version of the OS-9 real-time operating system is now available for the Motorola MVME167 single-board computer. This latest version allows development of real-time software that uses all of the board's features, including onboard serial, SCSI, and Ethernet hardware. The software is available in two versions. The OS-9/167 Development Pak includes the OS-9/167 operating system and a full suite of development tools. A corresponding Run-Time Pak provides

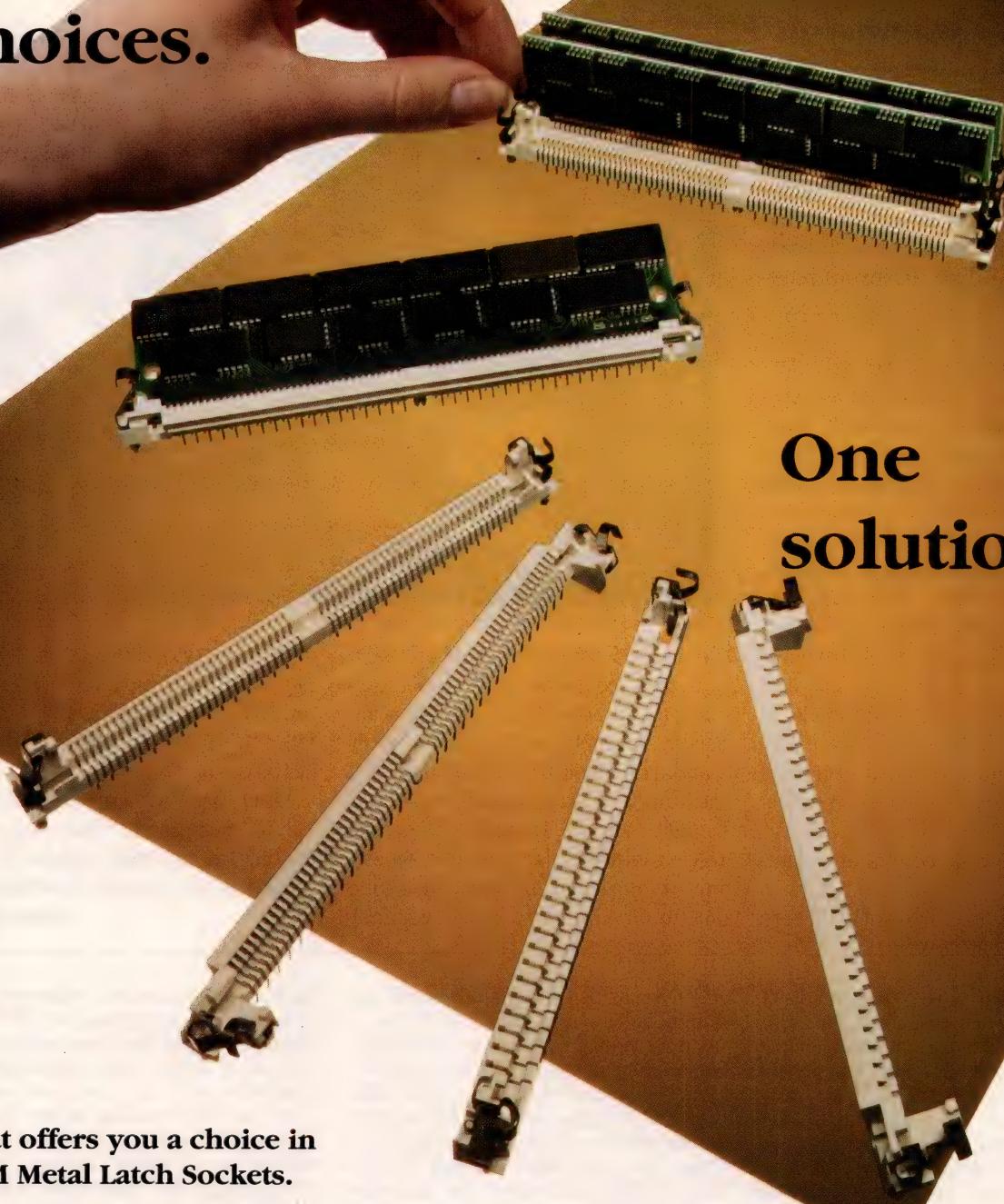
only OS modules. The development version includes a Kernighan & Ritchie C compiler, a macro assembler and linker, a user-state debugger, a screen editor, a shell-command interpreter, and utility programs. It also includes device drivers for next-generation I/O peripherals. These include SCSI drivers for the NCR 53C710 controller; the controller supports floppy and hard disks and tape units that use the Common Command Set. **Microware Systems Corp**, 1900 NW 114th St, Des Moines, IA 50322. Phone (515) 224-1929. **Circle No. 409**

**Fuzzy-logic design tool.** RT/Fuzzy aids the development and implementation of real-time software using rule-based logic. An extension of the supplier's family of tools for graphical modeling, system design, simulation, and code generation, it simulates and generates code for fuzzy-logic designs. Fuzzy

logic attempts to mimic imprecise human thinking by operating on IF-THEN statements that describe conditions and actions; it differs from conventional algorithms since all rules are based on qualitative information rather than a set of procedural equations. Software is available for Sun-4, SPARCstations, VAX, and HP workstations. From \$5000. **Integrated Systems Inc**, 3260 Jay St, Santa Clara, CA 95054. Phone (408) 980-1500. **Circle No. 410**

**VHDL tool set.** Silicon 1076 offers a complete concept-to-silicon VHSC hardware-description language, according to its developer. It lets you start at the architectural level, register-transfer level, or gate level and complete the design of an ASIC. It supports all of its developer's libraries. From \$55,000. **LSI Logic**, M/S D-102, 1551 McCarthy Blvd, Milpitas, CA 95035. Phone (408) 433-7161. **Circle No. 411**

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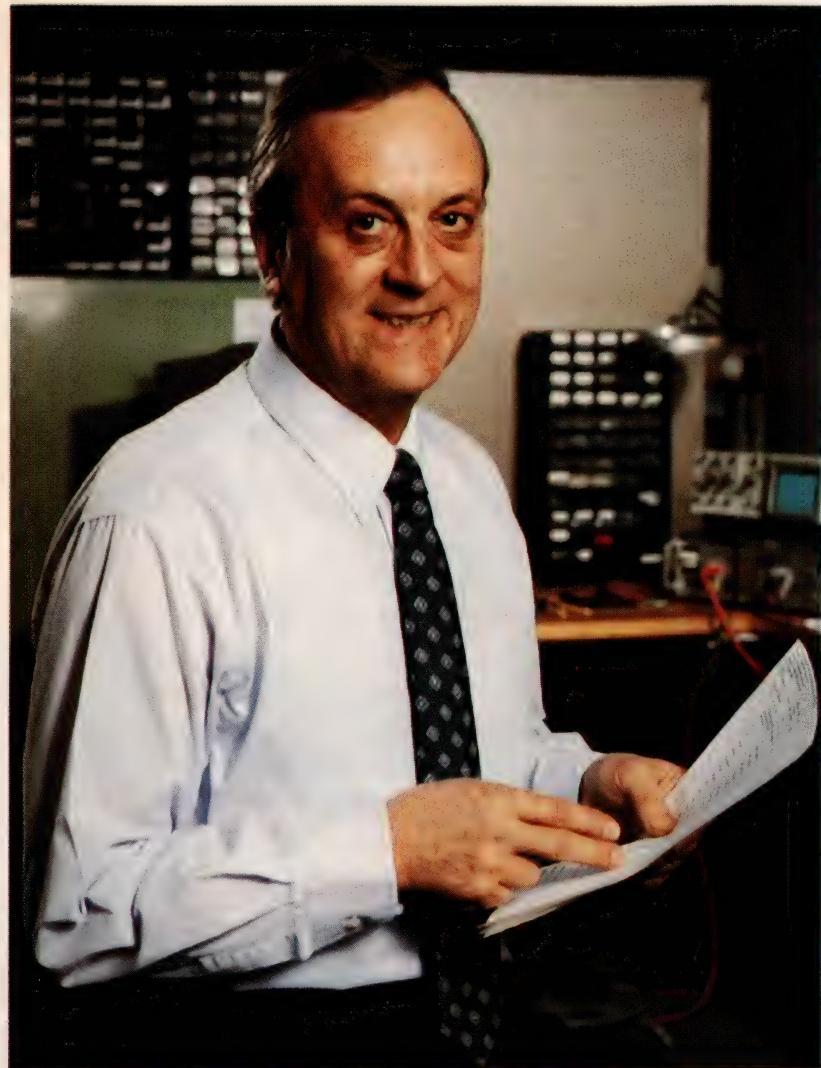
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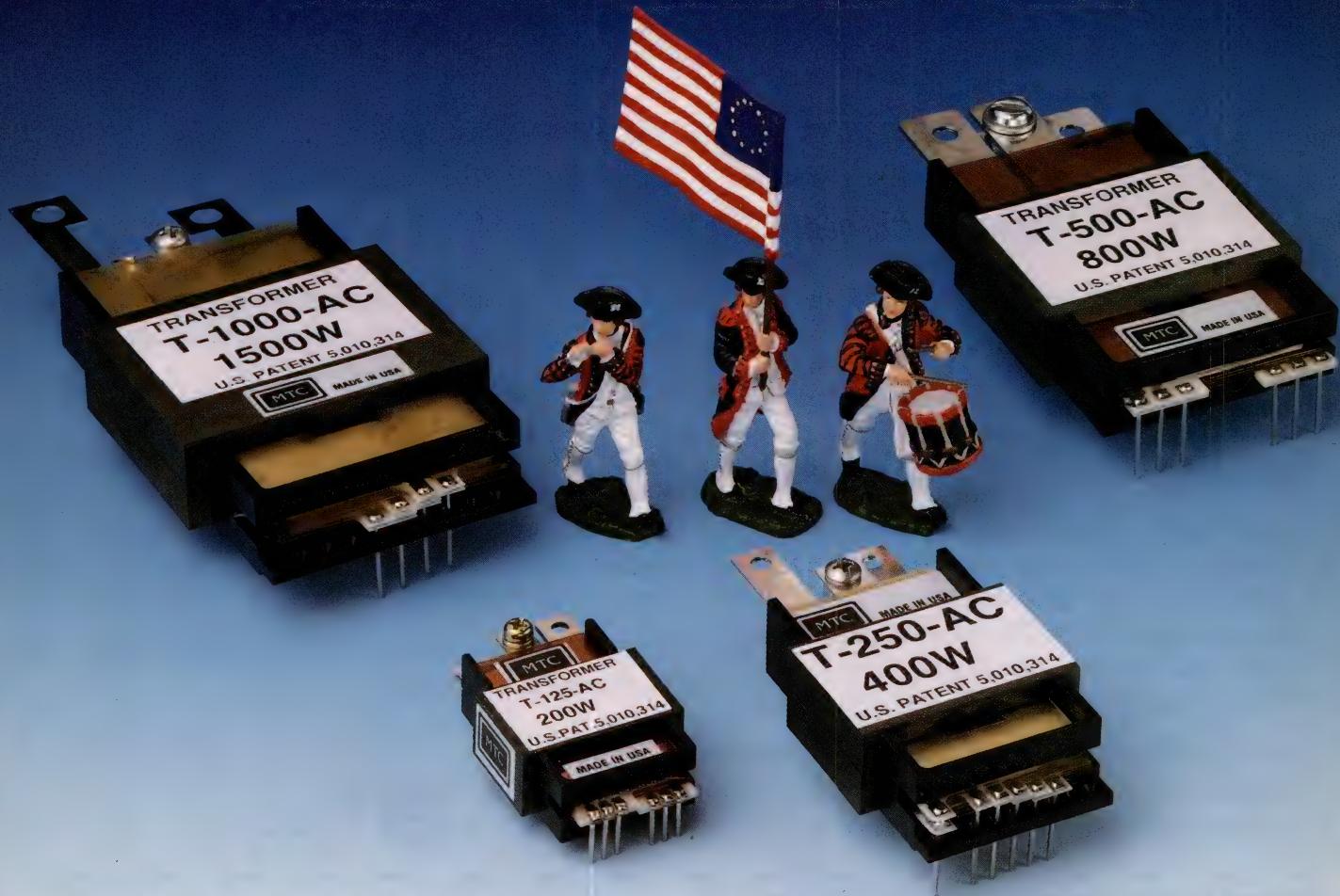
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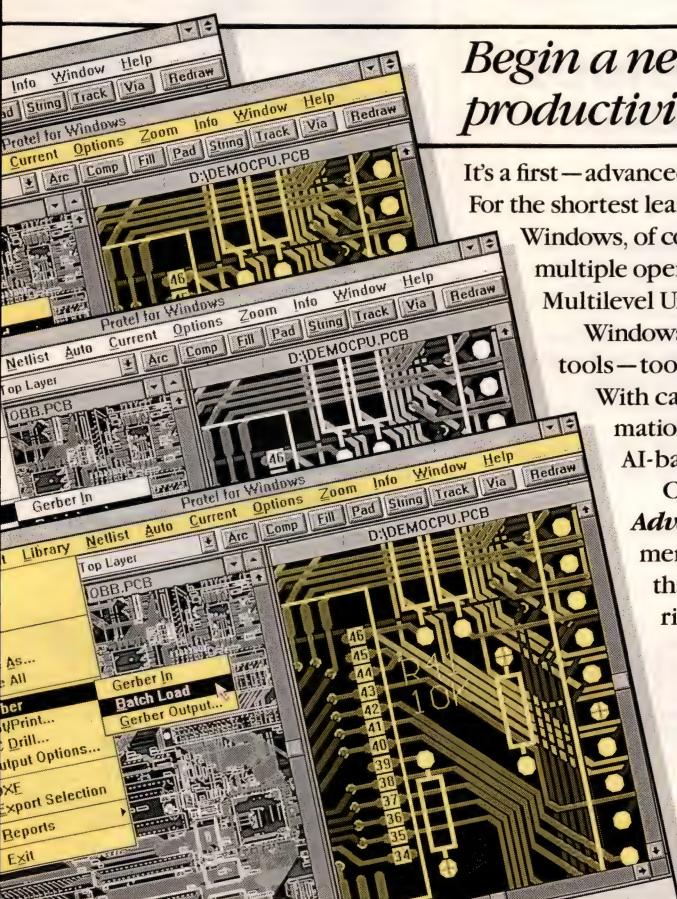
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**VXIbus product catalog.** This publication introduces more than 30 VXI modules, including analog and digital I/O, monitors and controllers, signal conditioners, and ARINC-429 and MIL-STD-1553 interfaces. It discusses VXIbus data-acquisition systems that you configure using the National Instruments' VXIpc-386 PC/AT and VXIpc-030 68030 embedded computers. **KineticSystems** 11 Maryknoll Dr, Lockport, IL 60441. Phone (815) 838-0005. **Circle No. 402**

**Test equipment catalogued.** The 40-pg catalog describes and illustrates recording systems, oscilloscopes, analog and digital snap-arounds, digital multimeters, data-logging digital multimeters, and many related devices. The alphanumeric table of contents lists products by model number. **AW Sperry Instruments Inc.**, Box 9300, Smithtown, NY 11787. Phone (516) 231-7050. **Circle No. 403**



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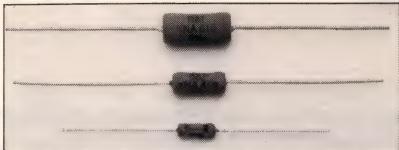


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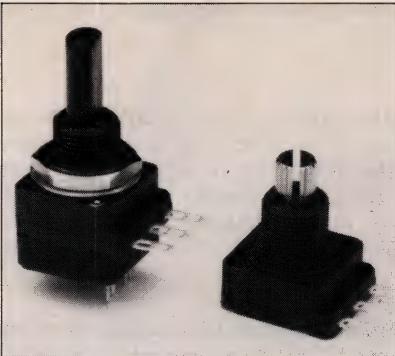
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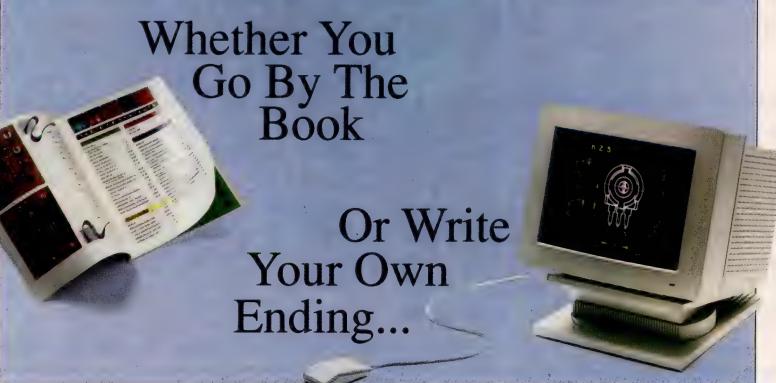
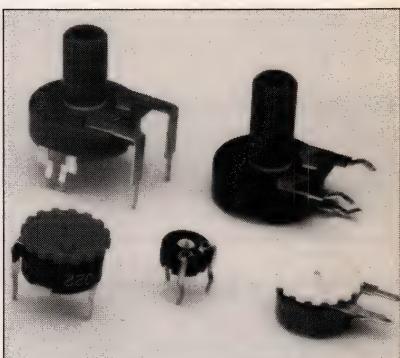
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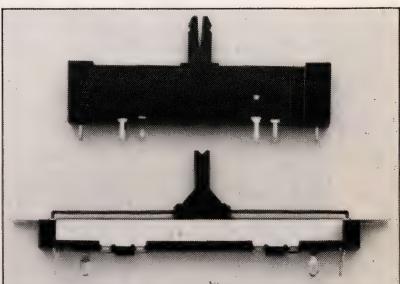
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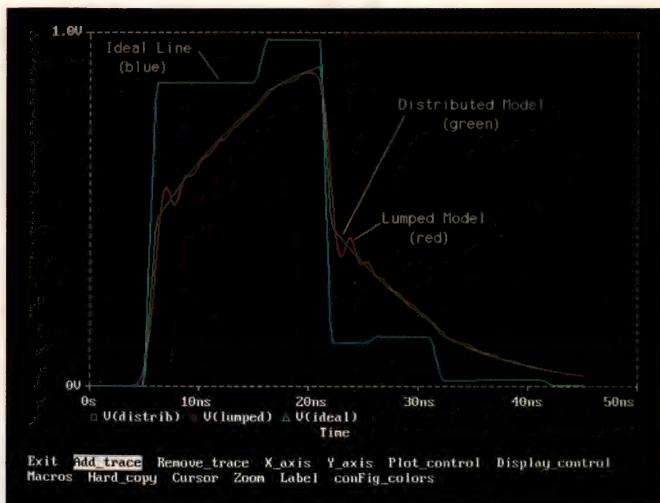


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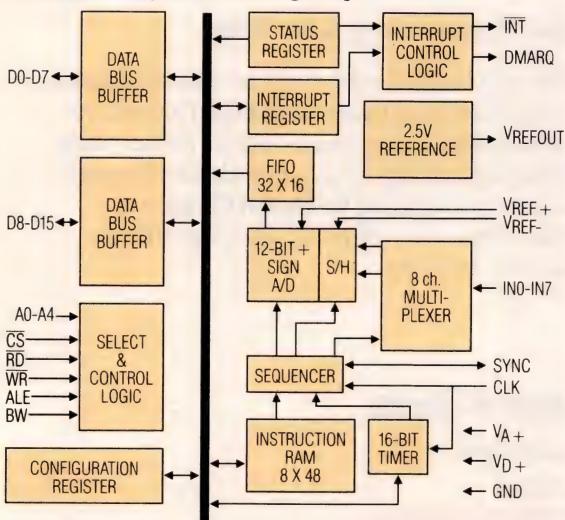
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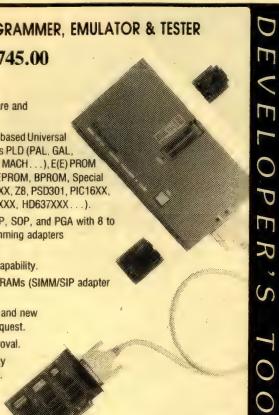
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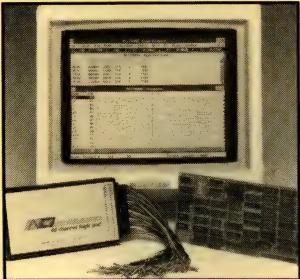
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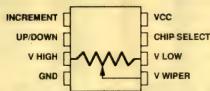
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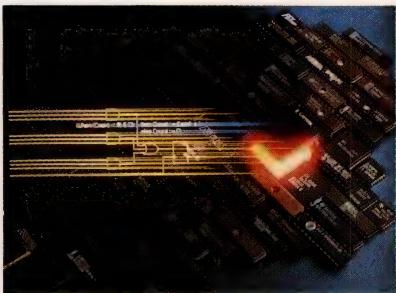
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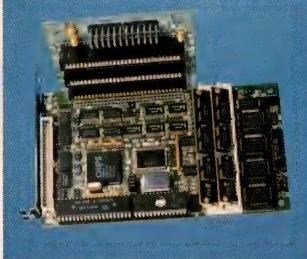
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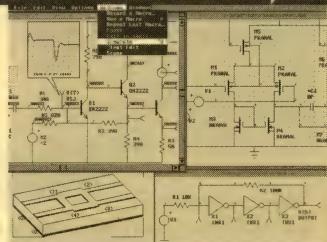
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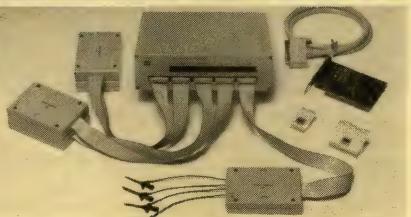


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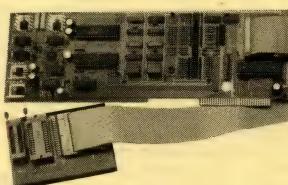
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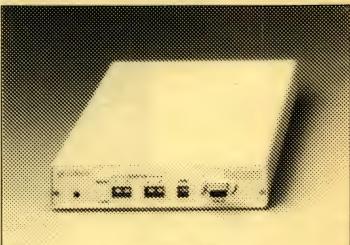
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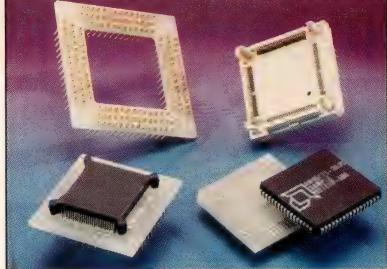
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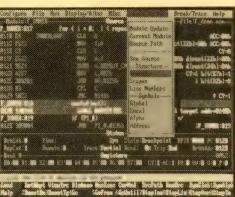
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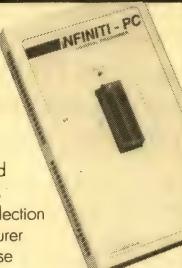
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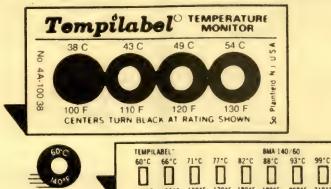
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News Edition	Apr. 30	Apr. 16	ASICs SPECIAL ISSUE • FPGAs and EPLDs • CICC Hot Products • ASICs • Regional Profile: Northern California
Magazine Edition	May 7	Apr. 16	Communications/Networks • Test & Measurement • Surface-Mount Components • Power Sources • Electro Show & Products Issue
ELECTRO SHOWGUIDE & PRODUCT SPOTLIGHT		Apr. 3	A free page available to all advertisers running a full page in 2 out of 3 Electro issues
News Edition	May 14	Apr. 30	Graphics Technology • Computers & Peripherals
Magazine Edition	May 21	Apr. 30	Analog ICs • Analog CAE • PC Board CAE Tools • Programmable-Logic Devices
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Magazine Edition	June 4	May 14	ASICs/PLDs • DSP Software • CAE/Software/Interoperability • Digital ICs & Semiconductors
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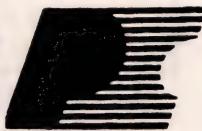
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**FIRMWARE ENGINEERS**—Positions require a BSEE or BSCS and a minimum of 3 years of recent experience developing firmware in 68000 assembly and "C" preferred. Positions involve firmware and embedded software development.

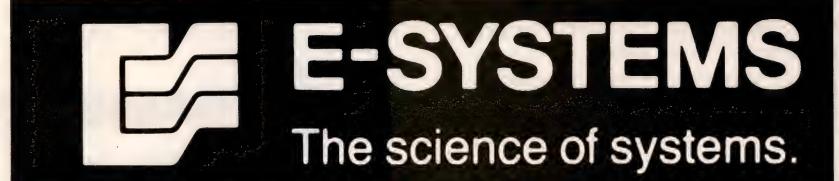
**RF HARDWARE ENGINEERS**—Positions require a BSEE and 3 years experience in the detailed design of complex RF circuitry including UHF through SHF synthesizers, receivers, and modems. Positions involve development of RF/IF modules for open architecture SHF and Interferometer Systems.

**COMMUNICATIONS SYSTEMS ENGINEERS**—Positions require a BSEE (MSEE preferred) and 6 years experience in the calculations and trade analysis of complex communications systems, including link budgets, DSP, data/network layer protocols and modem implementations.

**DIGITAL PROCESSOR ENGINEERS**—Positions require a BSEE and a minimum of 3 years of digital microprocessor implementation design experience using 680x0 embedded processors. In addition, digital signal processing experience with TMS 320 processors and digital de-modulator implementation experience is highly desirable.

**SYSTEMS ENGINEERS**—Positions require a BSEE or BSCS and a minimum of 3 years of experience in systems engineering including design, methodology and development processes on large hardware/software based signal processing systems. Experience with VAX/VMS, CADRE and Oracle desired. Positions involve requirements analysis and conceptual/functional design of large software subsystems.

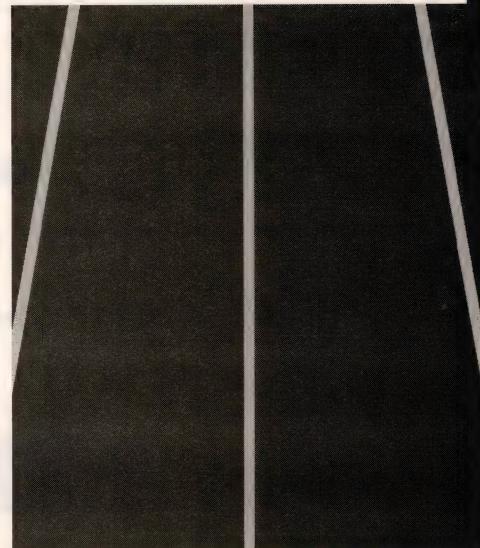
**REAL-TIME SOFTWARE ENGINEERS**—Positions require a BSEE or BSCS and experience with 680x0 embedded processors/or TMS 320 digital signal processors. Experience with 680x0 assembly, "C," ADA in a UNIX development environment is desirable. Experience with a disciplined software development methodology (2167-A, NSAM-81-3).



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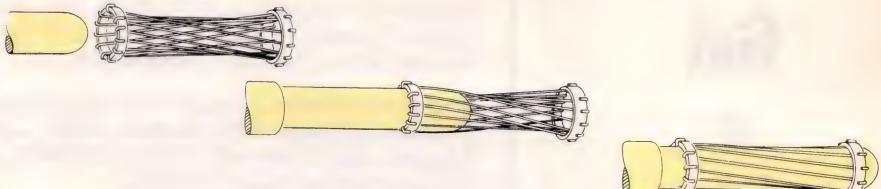
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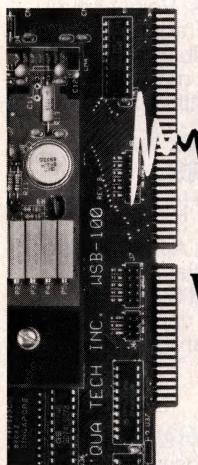
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# EDN-ACRONYMS & ABBREVIATIONS

AA—a size of nonrechargeable and rechargeable cell	MMU—memory-management unit
ACE—Advanced Computing Environment, an industry consortium	NiCd—nickel cadmium, a type of rechargeable cell and rechargeable battery
ADC—analog-to-digital converter	p-n junction—the region of transition between p-type and n-type material in a single semiconductor crystal
ALU—arithmetic and logic unit	p-p—peak-to-peak
C—a size of nonrechargeable and rechargeable cell	PAX—parallel architecture extension
CMOS—complementary metal-oxide semiconductor	PC—personal computer
CPI—cycles per instruction	pc board—printed-circuit board
CPU—central processing unit	PGA—pin-grid array
CRT—cathode-ray tube	ppm—part per million
CSA—Canadian Standards Association	RAM—random-access memory
DAC—digital-to-analog converter	RISC—reduced-instruction-set computer
DMA—direct memory access	rms—root-mean-square
DMM—digital multimeter	RS-232C—an Electronic Industry Association standard for serial data communication, popular in PCs
DSO—digital storage oscilloscope	S/H—sample and hold
DSP—digital signal processing	S/N ratio—signal-to-noise ratio
ENOB—effective number of bits	SFDR—spurious-free dynamic range
FFT—fast Fourier transform	SIMM—single in-line memory module
FPU—floating-point unit	SINAD—signal to noise and distortion
I/O—input-output	TC—temperature coefficient
IC—integrated circuit	T/H—track and hold
IEEE-488—The Institute of Electrical and Electronics Engineers' standard for communication with test instruments	THD—total harmonic distortion
ISA—the Industry Standard Architecture I/O bus of IBM PCs and compatible computers	3-D—three-dimensional
ISSCC—International Solid-State Circuits Conference	TLB—translation look-aside buffer
LCD—liquid-crystal display	UL—Underwriters' Laboratories Inc

This list includes acronyms and abbreviations found in EDN's Special Report, Technology Updates, and feature articles.



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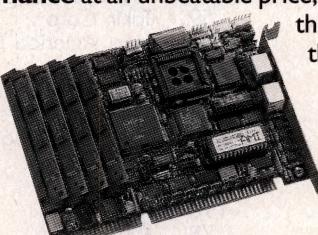
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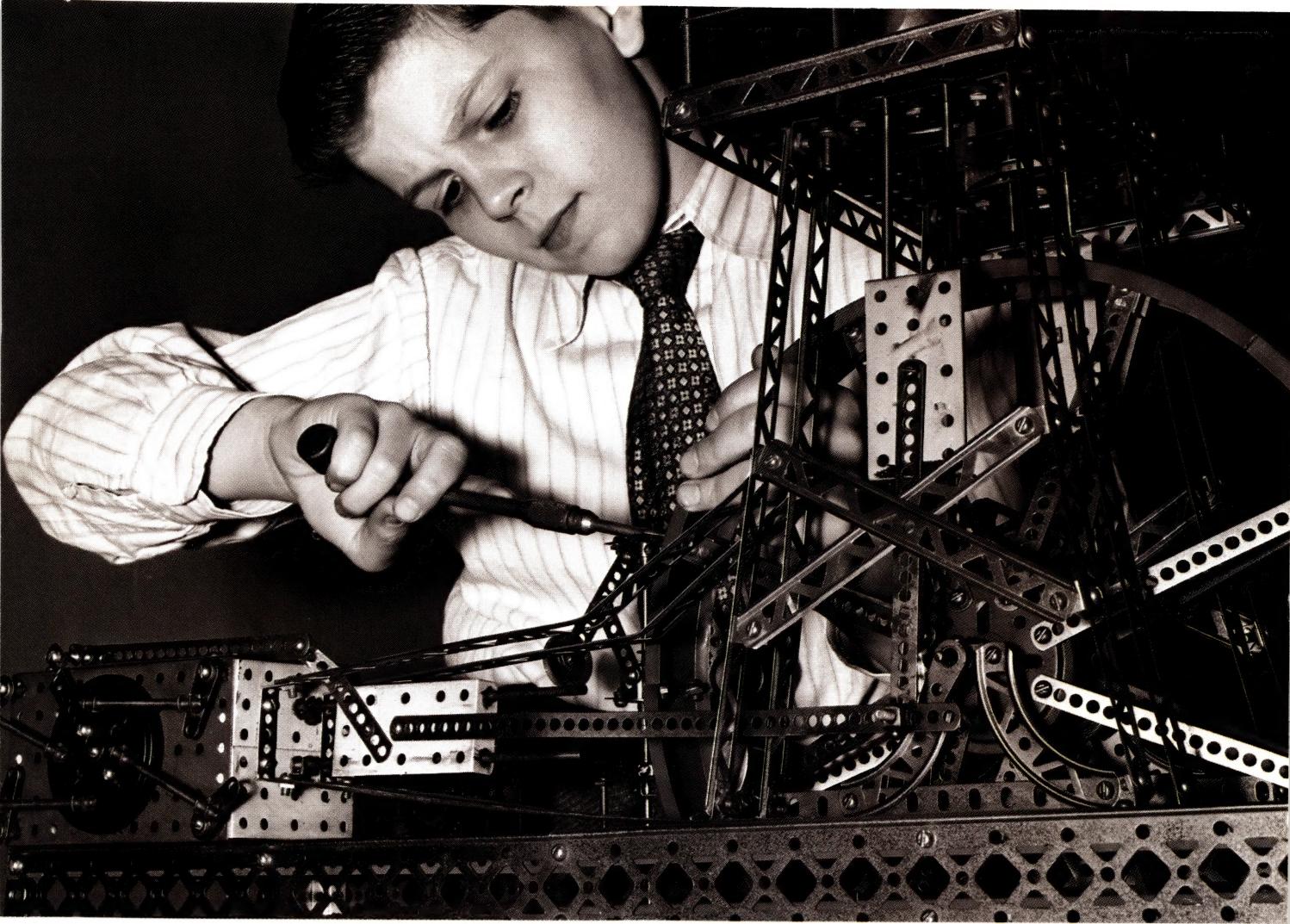
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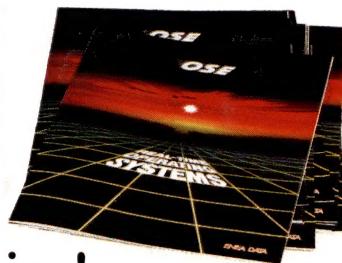
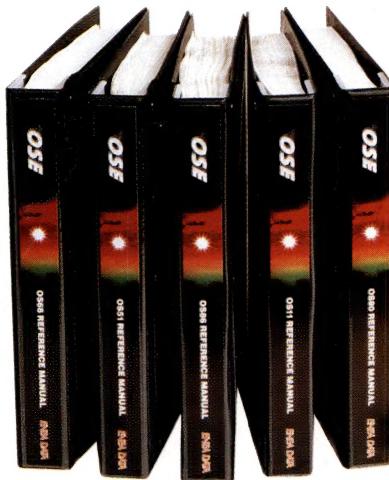


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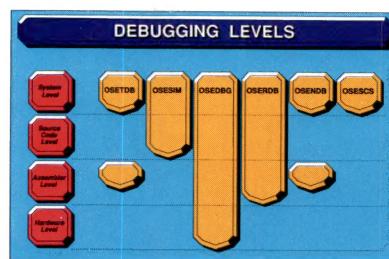
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